

HT 18 / G / 102 / 0621 / E

# **Wheel Motors**





## **CONTENTS**

GENERAL INFORMATION	4 - 21
WHEEL MOTORS WITHOUT GEARBOX	
P05R 20/A P05R F25	22 - 25
P1G 30/A P1G F30/D	
P2G 22/B P2G F32	
BD2 22/B BD2 F32	34 - 37
WHEEL MOTORS WITH GEARBOX	
REDUCTION GEAR UNITS WR SERIES	38
RADIAL LOAD GRAPHS	39
GM05+WR6B	40 - 41
GM1+WR6B	
BD1+WR6B BV1+WR6B	
GM05+WR10	
GM1+WR10	
BD1+WR10 BV1+WR10	50 - 51
GM2+WR10	
BD2+WR10 BV2+WR10	
GM1+WR20	62 - 63
BD1+WR20 BV1+WR20	64 - 67
GM2+WR20	
BD2+WR20 BV2+WR20	
WR SERIES ORDER CODE	73
REDUCTION GEAR UNITS K SERIES	71
RADIAL LOAD GRAPHS	
GK3 GFK3R	76 - 79
BDK3 BDFK3R BVK3 BVFK3R	
GK3A GFK3AR	84 - 87
BDK3A BDFK3AR BVK3A BVFK3AR	
GK4 GFK4	92 - 93
BDK4 BDFK4 BVK4 BVFK4	
K SERIES ORDER CODE	97
REDUCTION GEAR UNITS G3 - G3A SERIES	98
RADIAL LOAD GRAPHS	
GM05+G3 GM05+F10L+G3	
GM1+G3 GM1+F10L+G3	
BD1+G3 BD1+F10L+G3 BV1+G3 BV1+F10L+G3	
GM05+G3A GM05+F10L+G3A	
GM1+G3A GM1+F10L+G3A	
BD1+G3A BD1+F10L+G3A BV1+G3A BV1+F10L+G3A	
G3 - G3A SERIES ORDER CODE	124 - 12
REDUCTION GEAR UNITS TS8 SERIES	126
RADIAL LOAD GRAPHS	
TS8W TS8WF	120 - 13
TS8DW TS8DWF TS8VW TS8VWF	
TS8 SERIES ORDER CODE	136 - 13
DISTRIBUTORS	138 - 139
WHEEL APPLICATION DATA SHEET	140
APPLICATION DATA SHEET	141



### INTRODUCTION TO THE CATALOGUE AND SYMBOLS USED

This catalogue consists of:

- A topic index;
- An introduction page;
- Texts and warnings divided into chapters, paragraphs and subsections.

### SYMBOLS INDICATING DANGEROUS SITUATIONS OR VERY IMPORTANT INFORMATION.



### **WARNING!**

Indicates risky situations for people, refers to accident prevention and suggests behavioral procedures.



Indicates useful information for the consultation of the manual and the smooth operation of the machine

### GENERAL INFORMATION



### Introduction

Read and store this technical catalogue carefully.

The information in it contained will be needed to correctly select the product.

The manufacturer has designed the components in order to ensure safe usage conditions.



### Purpose of the catalogue

This catalogue is aimed to present the products in it contained to aid in the selection of the most suitable component for the required application.

The hydraulic motors will not be held liable for damages, accidents or drawbacks resulting to the failure to comply to the instructions given in this manual.

We will also not be held liable for the modification and/or installation of non-authorized accessories.



### Updating the catalogue

It is recommended to constantly keep this catalogue updated by adding amendments, updates or modifications made by the manufacturer.

New pages will be sent in the event of minor changes and it will be up to the user to integrate them within the catalogue, replacing the existing ones in the related chapters or paragraphs.

A revised copy of the catalogue will be sent to replace the existing version in the event of substantial changes to the components. At which point the old version of the catalogue must be destroyed.





### **COMMON DEFINITIONS**

In this catalogue and most of the documents the following specific terminology is used to describe specific key points of our products.

The peak values indicate the maximum working conditions that the product can withstand.

This means that the component can infact work at its peak working conditions for a period of time that does not exceed 1% per minute and not more than 10 times per hour.

The continuous working condition values are the ones that can be applied continuously without harming the product.

This means that it is the working conditions at which the component can run until the end of its calculated lifetime.



### **COMMON HYDRAULIC FORMULA**

Torque	$Torque[Nm] = \frac{displace}{m}$	$ement[cc/rev] \times pressure[bar]$
rorque	1 or que [wm] =	62.83

 $Torque[Nm] = specific torque[Nm/bar] \times pressure[bar]$ 

**Power** 
$$[kW] = \frac{torque [Nm] \times speed [rpm]}{9549,3}$$

**Shaft speed** 
$$Speed [rpm] = \frac{flow \ rate \ [l/min] \times 1.000}{displacement \ [cc/rev]}$$

**Motor displacement** 
$$Displacement [cc/rev] = \frac{maximum \ required \ torque \ [Nm] \times 62,83}{maximum \ pressure \ [bar]}$$

If gearbox is used:

$$Displacement \ [cc/rev] = \frac{maximum \ required \ torque \ [Nm] \times 62{,}83}{maximum \ pressure \ [bar] \times gearbox \ ratio}$$

Required pump flow rate 
$$Flow \ [l/min] = \frac{displacement \ [cc/rev] \times maximum \ motor \ speed \ [rpm]}{1.000}$$
 
$$Speed \ [rpm] = \frac{vehicle \ speed \ [km/h] \times 5,305}{external \ wheel \ \emptyset \ [m]}$$





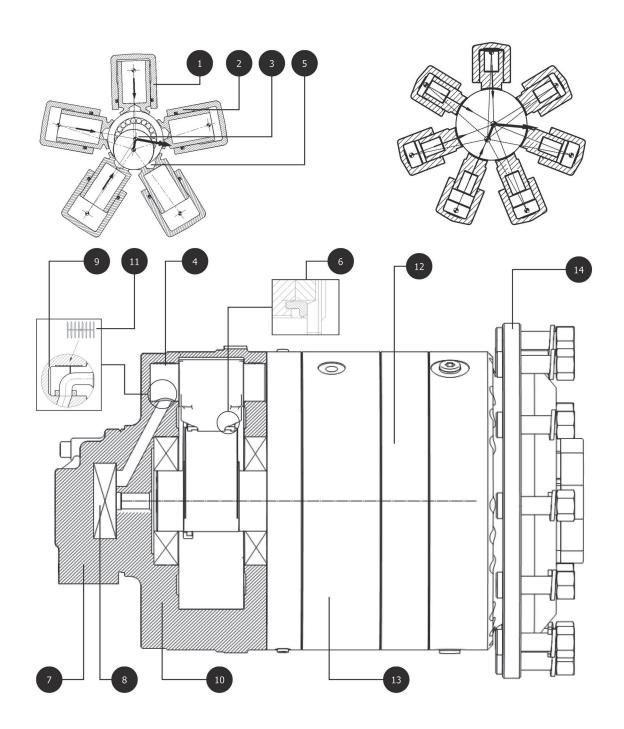
### **CRANKSHAFT DESIGN RADIAL PISTON MOTORS**

The main characteristics of this type of design are the high mechanical efficiency, especially at start up, and high volumetric efficiency.

A number of features distinguish our motors from the other radial piston designs:

Fixed displacement, 5 piston motor.

Fixed displacement, 7 piston motor.





### Swivelling cylinder:

The cylinder (1) always remains aligned with the eccentric (3) of the crank,

thus eliminating the stress between the walls of the piston (2) and the cylinder.

The articulation of the cylinder is done by the trunnions (4) that ensure low specific loads.

#### Piston:

The pistons transfer the load to the shaft through an hydrostatic bearing (5).

This bearing reduces the contact between metals and ensures an optimal lubrication and lowers the friction.

### Piston retaining rings (6):

Ensure the contact between the foot of the piston and the shaft in all working conditions, even in the event of cavitation.

### Axial distribution rotary (8):

Ensures an optimal distribution of the oil with short ducts with a wide diameter in order to reduce the power loss when high flow is present.

The high volumetric efficiency and the recovery of the tolerances by the seals ensure an optimal functionality throughout the entire life of the product and in conditions of thermal shock.

### Interchangeable distributor (7):

A wide range of distributors is available for different motors with various pressure and flow control valves.

### Radial injection cylinder feed (9):

Eliminates direct hydraulic axial load on the motor body.

These are also larger compared to previous products to reduce power loss with high flow rates.

### Stronger casting (10):

To allow higher internal and external load capacity and bear higher stress levels compared to previous products.

### Larger cylinder trunnions (4):

For increased resistance and reduced specific loads compared to previous products.

### Spigots with hydraulic balancer (11):

To reduce friction and wear.

This also allows for a lower heat generation, allowing the product to work with higher powers and higher performances, thus improving efficiency.

### Planetary wheel gearbox (12):

The torque and speed of the motor are transformed by a single stage planetary gearbox.

This allows the unit to reach higher admissible radial loads and transmissible torques compared to the normal direct motors.

### **Brake (13):**

The gearbox can be supplied with a hydraulic negative disc brake integrated in its design.

### Hub (14):

The wheel hub can have different dimensions and shapes allow the unit to be coupled with the various types of wheel in commerce.



### **MAXIMUM MOTOR TORQUE**

F - traction force (N)

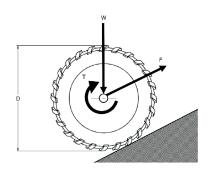
W - vehicle weight (kg)

T - motor torque (Nm)

D - external wheel diameter (m)

n - number of hydraulic motors

R - sin (slope angle°) or traction resistance (%)



$$F[N] = \frac{W \times R \times 9,81}{n}$$

$$T[Nm] = \frac{F \times D}{2}$$

### **DISPLACEMENT VARIATION**

Over the years we has developed a wide range of dual and variable displacement motors whilst keeping the outside dimensions the same within the size of the fixed displacement motor series originally made.

The dual and variable displacement motor technology satisfies awide operational range request.

The same power can be utilized from high torque-low speed to high speed-low torque working conditions.

With the technological advances the user can optimize the operating range of the application by adjusting the starting torque and the speed to meet the requirements of the application.

The displacement variation can occur whilst the vehicle is in motion and loaded, thus eliminating the need to stop the rotation of the motor to change the displacement of the motor.

Thanks to the design of the motors, we can, where possible, provide the motors with a minimum displacement equal to 0 cc/rev.

### **WORKING KNOWLEDGE**

The displacement change is done by varying the stroke (2 x e) of the pistons, whilst keeping the bore and the number of "active" pistons unchanged.

This makes it possible to change displacement in motion.

The "reaction time", or the time needed to change displacement, is specific for each application. We can supply motors with various reaction times.

Real displacement = 
$$\frac{d^2}{2} \times \pi \times nc \times e$$
 Nominal displacement =  $\left(\frac{d^2}{2} \times \pi \times nc \times e\right) \times i$ 

where:

d = cylinders bore
nc = n° of cylinders
e = eccentricity (= ½ stroke)
i = reduction ratio of the gearbox



### **DUAL DISPLACEMENT MOTOR**

This type of control switches between two displacement positions: minimum and maximum.

The change of position of the directional valve occurs via a pilot signal PIL(c).

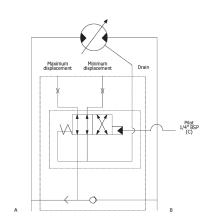
When there is no pressure in the pilot line, the valve maintains (or changes it into) maximum displacement. When the pressure in the pilot line is between 20 and 30 bar, the valve shifts the spool, changing the displacement to minimum.

Pilot pressure is affected by the case pressure and the motor speed.

The crankshaft eccentricity moves from maximum to minimum (and back), enabling the motor to switch displacement whilst running with no shock to the system.

The valves in the scheme are integrated in the motor.

Ratio between max. and min. displacement is available on all models as follows: 1:2 - 1:3 - 1:4.





### VARIABLE DISPLACEMENT MOTOR

The variable displacement motor package includes:

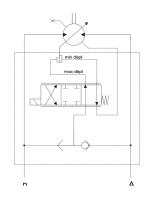
- 1. Electroproportional valve driven by the controller;
- 2. Angular sensor, used to measure the oscillation angle of the cylinders;
- 3. Electronic controller, used for elaborating signals and control the electroproportional valve;
- 4. Potentiometer.

This allows the user to set the required displacement.

The control logic used by the CPU is of proportional-integral-derivative type (PID).

The user requires a displacement through the potentiometer.

The controller (CPU) compares the displacement request with the motor measured displacement and adjusts it varying the motor eccentricity through the electroproportional valve.







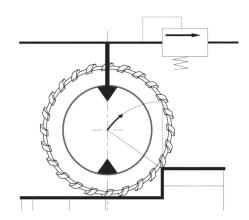
# CHARACTERISTICS AND INDICATIONS HIGH STARTING TORQUE

The design of the radial piston motor with crankshaft and oscillating cylinders ensures very high starting torque efficiencies, especially at high pressures which are required in most mobile applications.

The mechanical efficiency of the motor is typically higher than 90% at 400 bar.

The high starting torque is usually required when the vehicle is at standstill or during low speed operations.

For example when the mobile application accelerates from standstill or when it has to overcome an obstacle or a slope. The motors with a high starting torque, therefore, improve vehicle performances and reduce energy consumption, especially with frequent start-stop working cycles.



### HIGH VOLUMETRIC EFFICIENCY

The motors have very high volumetric efficiency levels in all working conditions.

The seal system used ensures the maintenance of the volumetric efficiency even when the surfaces present signs of being worn over time.

The combination of high volumetric and mechanical efficiencies ensure a lower heat generation from the motors, which enables a reduction or, in some cases, removal of the heat exchanger.

### **NOISE LEVELS**

Our motors are extremely silent. The noise level can be reduced further with back pressure of 5-10 bar. Please note that the structure and connections can be very efficient sound propagators and amplifiers. The motors are available, on request, with a special distributor which ensures silent working conditions within wide operational ranges. Please contact our Technical Department for further information.

### ALLOWABLE BACK PRESSURE

The motors are capable of operating with high back pressures with high efficiency, e.g. for series circuit applications.

The allowable pressures vary in function of the piston diameter and other factors.

If the motors are required for an application with back pressure contact our Technical Department for further details. Typical allowable back pressure values are:

	Port A	Port B	Port A+B
Continuous	210 bar	140 bar	350 bar
Peak	350 bar	350 bar	700 bar

Pressure values have to be within the ones on the technical data sheet.



### **CAVITATION RESISTANCE**

The piston retaining rings ensure that the pistons remain in full contact with the eccentric, no matter what the pressure conditions inside the cylinders or the motor casing are.

The retaining force counteracts continuously the separating force, thus preventing lifting, tilting or hammering of the piston during cavitation.

### MOTOR CASE PRESSURE

### Standard shaft seal

Continuous pressure 1 bar Peak pressure 5 bar

### **High pressure shaft seals (option A)**

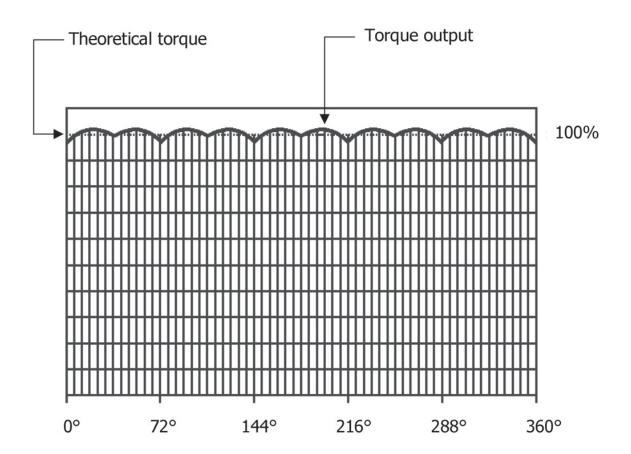
Continuous pressure 5 bar Peak pressure 15 bar

### **TORQUE**

The theoretical torque of the motor may be obtained by multiplying the specific torque given in the tables by the  $\Delta p$  value required.

The graph below shows the variation in output torque due to the pistons as the shaft rotates through a full 360° revolution.

The graph refer to five piston motor.



# HANSA-TMP

# **Wheel Motors**

### **HYDRAULIC FLUIDS**

### MINERAL OILS

For the combined lubrication wheel motors it is possible to use the same oil stated in the motor catalogues: ISO VG 46. For the separated oil applications the lubricant suggested is: ISO VG 220 SAE 90 EP.

We suggests to use good quality hydraulic mineral oil, preferably with additives for high pressure, anti-corrosive, anti-wear and anti-foaming. The hydraulic fluid used has to be chosen in order for the viscosity is within the indicated range to the normal working temperature conditions.

Admissible temperature range:

Ideal: +30°C to +50°C

Allowable: -20°C to +80°C

On request our motors can be manufactured to operate at lower

(down to -40°C) or higher (up to +120°C) temperatures.

Operating viscosity range:

Ideal: 40 cSt to 60 cSt

Allowable: 25 cSt to 150 cSt

After the initial start up please verify the level of the lubricant periodically and top up whenever necessary. The first oil change has to be made after 15-20 hours of operation.

The following changes must be performed after 800-1000 hours, or one year of operation, whichever comes first.



### FIRE RESISTANT FLUIDS

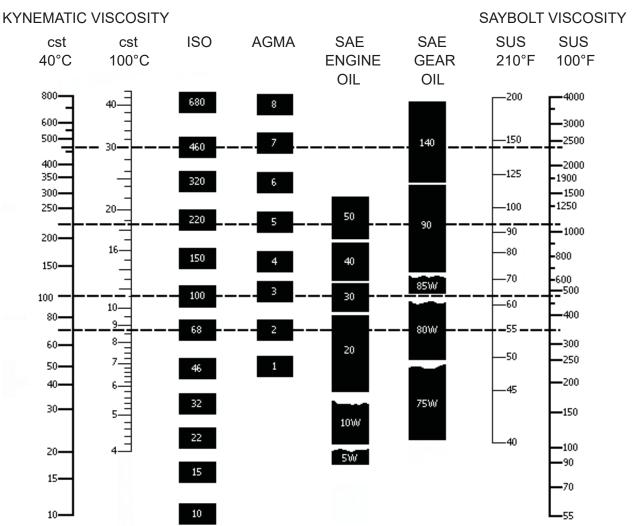
(i) **Synthetic fluids:** (phosphate esters, polyesters, ...). These fluids have similar characteristics to mineral oils and the same temperature and viscosity ranges are applicable.

These kinds of fluids may, however, require seals of suitable material (such as FKM seals) which are available on request.

(ii) Water based fluids: (water-oil emulsions, water-glycol solutions, ...) due to the low viscosity of these fluids the lifetime of the components is reduced.

### **VISCOSITY REFERENCE TABLE**

### **GRADE SYSTEM**



Viscosities can be COMPARED horizontally only.

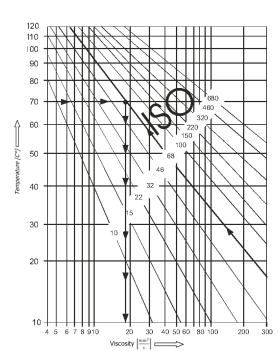
For example, the following oils have similar viscosities:

ISO 460, AGMA 7 AND SAE GEAR OIL 140. The relationships between temperature and viscosity are based on 95 VI oils and are usable only for mono-grade engine oils, gear oils and other 95 VI oils.

Crankcase oils and gear oils are based on 100°C viscosity.

The "W" grades are classified on low temperature properties.

ISO and AGMA grade oils are based on 40°C viscosity.



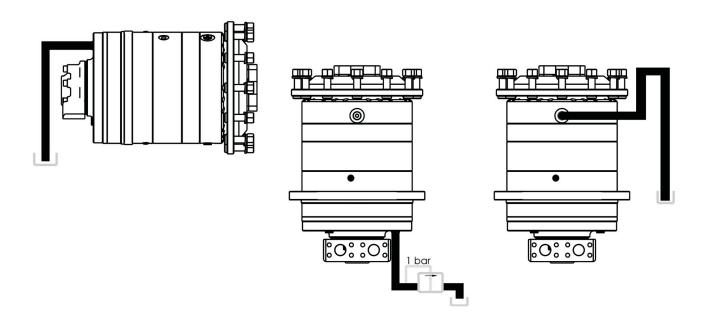




### DRAIN LINE POSITION

The position of the drain line must be placed in such a way that there is always sufficient oil in the casing for the lubrication of the shaft bearing. If the motor has to be installed with the shaft in horizontal position, the drain line should be connected to the uppermost drain line hole.

If the motor is installed with the shaft pointing upwards, the motor casing has to be entirely filled with oil and the drain line has to be connected in such a way that no air can enter the motor to avoid the bearing on the motor body to work without lubrication.



# HANSA-TMP

## **Wheel Motors**



Before connecting the pipes, make sure that they are clean and that there is no rust.

Before the initial start up, fill the motor and the gearbox with oil.

In the shared oil versions the motor has no shaft seal between motor and gearbox, therefore the unit can be filled either from the drain line in the motor cover or the one on the gearbox body.

In the separated oil versions the motor has to be filled with hydraulic oil from one of the drain lines on the motor cover and the gearbox has to be filled with gearbox oil from one of the drain lines on the gearbox body.

On the first start up remove all air from the hydraulic circuit. Make sure that there are no oil leaks from the joints and from the body. The products are tested at the factory and do not need a testing period.

### **FILTRATION**

We recommends using filters with gradation up to 25 µm, preferably 10 µm.

Our products have a good resistance to contaminated oil; however filter efficiency and therefore clean oil, are important for the correct functioning and reliability of all the components in the hydraulic system.

The efficiency of the filtering agents is greatly reduced with a progressive accumulation of filtered particles, therefore the filters have to be regularly checked. It is recommended to pay close attention at the first start up of the hydraulic system or in the event of a replacement of any component for damage or excessive usage. It is advisable to follow the filter manufacturer's recommendations for its life span and cleaning or substitution cycles.

### PIPES AND CONNECTIONS

We recommend the use of high quality piping and connections for high pressure hydraulic applications. Follow manufacturer's recommendations for pipe sizes, in any case do not use pipes which are smaller than the port connections; to reduce the effects of oil compressibility, use pipes with minimum possible width and diameter and maximum rigidity; to reduce the effects of a load loss avoid sharp corners, restrictions and high flow speed.

The nominal diameter ND of a pipe depends on the flow (I/min) and average speed (m/s). The formula to calculate the minimum recommended diameter, considering a maximum speed of 6 m/s, is:

$$ND [mm] = 4,607 \times \sqrt{\frac{Q [l/min]}{v [m/s]}}$$

Where:

Q = flow 6 [m/s] = v (average speed recommended)

### OIL CHANGE

The first oil change has to be done after the first 20 hours of work, subsequently the oil changes will have to be carried out every 1000 hours of work. We suggests to perform an oil change once a year if the unit is used in machines that work on a seasonal basis.

# HT HANSA-TMP

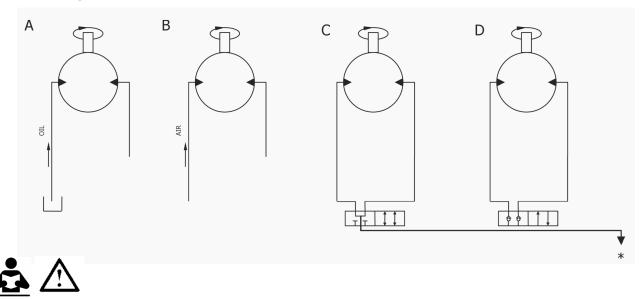
# **Wheel Motors**



### SPECIAL CONDITION FOR USE: FREE WHEELING

All our motors can be disconnected from the hydraulic circuit and driven externally for applications where freewheeling, free fall or breakdowns may be present.

The diagrams below show some possible circuit configurations for motor disconnection and/or operation in freewheeling:



- **A Freewheeling with oil in the circuit**. This condition is suitable only for low speeds. With the speed increase it will be necessary to pressurize the inlet to prevent noise due to cavitation.
- **B Freewheeling with air in the circuit.** This condition is ideal for high speed freewheeling applications. The transition from or to normal operation must be done at low speed and low pressure while the pistons are emptying or filling with oil.
- C "Short circuit" freewheeling. The motor runs with the inlet and outlet ports connected.

This condition is suitable to applications that require speed control with a throttle.

### **WARNING!**

Danger of overheating in unfavourable conditions, especially with throttle.

**D - "Vacuum" freewheeling.** This is the favourable freewheeling condition for fixed displacement motors, especially for very high speeds. The check valves allow the oil to be expelled from the pistons which subsequently operate under vacuum conditions.

The motors can operate in these conditions for several hours without being damaged or overheating. Torque absorption is constant with speed and equivalent to 2 - 3 bar of pressure.

The transition from or to normal operation must be done at low speed and low pressure while the pistons are emptying or filling with oil.

For further information on the T and B series motors, please contact our Technical Department.

### \* BOOST PRESSURE SHOULD BE PROVIDED TO AVOID CAVITATION







### BEARING LIFE TIME (ISO 281 - 1980)

The bearing lifetimes given in this catalogue and in most official documentations are L10 lifetimes.

The L10 lifetime is the period of work after which 10% of the bearings can be expected to show signs of wear.

The average lifetime of the bearing, L50 lifetime (where 50% show signs o wear), is approximately 5 times the L10 value.

To determine the lifetime of the bearings in an application, the values of constant or average pressures and speeds should be used, not peak or maximum values.

The continuous operating pressures of any motor should be chosen in function of the desired motor lifetime which can be calculated from the bearing lifetime graphs supplied in the technical documentation.



In any motor series the larger displacement models generally have shorter bearing lifetimes.

This is due to the larger diameter pistons which creates higher bearing loads.

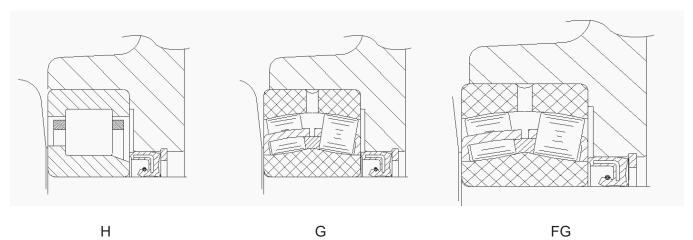
The smaller displacement motors of any series are suitable for heavy duty applications, whereas the larger displacement motors are more suitable for high torque applications but with reduced continuous or average power.

### **WORKING CYCLE FACTOR**

Non-stop operation sometimes causes shorter than calculated lifetimes.

This is due to increases in oil temperature and/or contamination combined with a decrease in viscosity when operating continuously for long periods. If, however, the hydraulic system is continuously monitored, then the working cycle factor may be disregarded.

### **MOTOR BEARING TYPE**



Cylindrical roller bearings

Spherical roller bearings

Reinforced spherical roller bearings



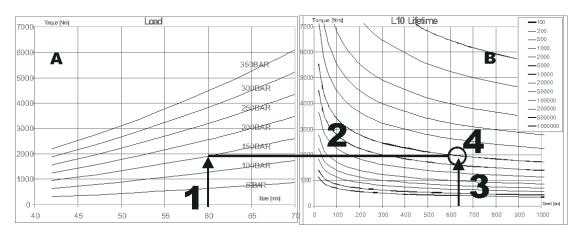


### **BEARING LIFE TIME GRAPHS**

These graphs are found in every leaflet and in the catalogues and are used to determine the lifetime of a given motor for a given pressure input and speed output.

The graphs work as follows:

- 1. Choose the piston diameter on graph A;
- 2. Define the intersection with the pressure curve;
- 3. Define the speed on graph B;
- 4. Determine the lifetime using the curve on graph B found on the intersection between 2 and 3, indicated with O.



### Bearings lifetime calculation of the gearbox:

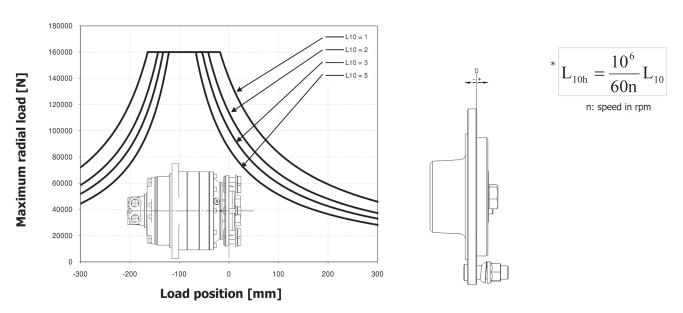
Permissible loads are calculated for different steps of lifetime L10 according to ISO 281:1990.

L10: lifetime of the bearing system in millions of revolutions.

L10 value can be converted in hours L10h using the formula\*.

Permissible radial load in dynamic conditions at the maximum torque allowed by the gearbox.

### N.B. Diagrams are influenced by the shaft permissible radial loads.







### **DISTRIBUTOR COVER ORIENTATION**

The motors can be provided with the distributor cover orientated in any of the following directions.

These are selectable among the following positions:

DM1 for position 1, DM2 for position 2, etc.

This position has to be stated at the end of the full description of the motor.

If no specification is made the standard position is DM1.

### Five piston motor



Position 1 DM 1



Position 2 DM 2



Position 3 DM 3



Position 4 DM 4



Position 5 DM 5

Seven piston motor



Position 1 DM 1



Position 2 DM 3



Position 3 DM 6



### **DIRECTION OF SHAFT ROTATION**

All motors are bidirectional.

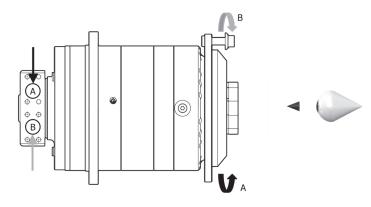
The direction of the rotation of the shaft is determined by the direction of the oil flow.

The standard motor configuration is set to have the input flow through port A which causes the shaft to move clockwise, taking the shaft as the focal point.

Should the oil flow be supplied through port B, the shaft will turn anti-clockwise.

All motors can be supplied with the shaft rotating anticlockwise.

Should this option be needed it has to be pointed out in the order as instructed in the order codes tables.





### **BOLT TORQUE SETTINGS**

NO.	DM						CLA	SS OF RES	ISTANCE					
NO	RM	PITCH			5.8 6.8 8.8 10.9								2.9	
DIN	267			5S							OK		12K	
	207			PIT	СН	PI	ГСН	PIT	СН	PIT	ГСН	PITCH		
bolt Ø	hexagon	coarse	fine	coarse	fine	coarse	fine	coarse	fine	coarse	fine	coarse	fine	
₩	mm	mm	mm	Nm										
М2	4	0,4	-	0,2 0,2	-	0,2 0,3	-	0,3 0,4	-	0,4 0,5	-	0,5 0,6	-	
M2,5	5	0,45	-	0,4	-	0,5	-	0,6	-	0,9	-	1,1	-	
		·		0,5	-	0,6	-	0,8	-	1,1	-	1,3	-	
М3	5,5	0,5	-	0,7 0,8	-	0,8 1,0	-	1,1 1,3	-	1,5 1,9	-	1,8 2,3	-	
M3,5	6	0,6	-	1,1 1,3	-	1,3 1,5	-	1,7 2,1	-	2,4 2,9	-	2,8 3,5	-	
				1,6	_	1,9	-	2,5	-	3,5	_	4,2	-	
M4	7	0,7	-	1,9	-	2,3	-	3,1	-	4,3	-	5,2	-	
M5	8	0,8	-	3,1	-	3,7	-	4,9	-	6,9	-	8,3	-	
				3,8	-	4,5	-	6,0 8,5	-	8,5 12,0	-	10,0	-	
М6	10	1,0	-	5,3 6,5	-	6,4 7,8	-	10,0	-	15,0	-	14,0 18,0	-	
M7	11	1,0	-	8,7 11,0	-	10,0 13,0	-	14,0 17,0	-	20,0 24,0	-	24,0 29,0	-	
				13,0	14,0	15,0	16,0	20,0	22,0	29,0	31,0	34,0	37,0	
M8	13	1,25	1,0	16,0	17,0	19,0	20,0	25,0	27,0	35,0	38,0	42,0	46,0	
M10	17	1,5	1,25	25,0	26,0	30,0	32,0	40,0	42,0	57,0	59,0	68,0	71,0	
MIO	17	1,3	1,23	31,0	33,0	37,0	39,0	50,0	53,0	70,0	74,0	84,0	89,0	
M12	19	1,75	1,5	43,0	45,0	52,0	54,0	69,0	72,0	97,0	101,0	116,0	121,0	
		·		53,0	56,0	64,0	67,0	85,0	89,0	119,0	125,0	143,0	150,0	
M14	22	2,0	1,5	68,0 84,0	74,0 92,0	82,0 101,0	89,0 111,0	110,0 135,0	118,0 148,0	154,0 190,0	166,0 208,0	185,0 228,0	199,0 250,0	
				106,0	112,0	128,0	135,0	128,0	180,0	240,0	253,0	287,0	303,0	
M16	24	2,0	1,5	132,0	141,0	159,0	170,0	212,0	226,0	298,0	318,0	357,0	382,0	
M18	27	2,5	2,0	147,0	155,0	176,0	186,0	235,0	248,0	330,0	349,0	397,0	419,0	
MIO	27	2,3	2,0	182,0	194,0	218,0	233,0	290,0	310,0	402,0	436,0	490,0	523,0	
M20	30	2,5	2,0	208,0	217,0	249,0	261,0	332,0	347,0	467,0	489,0	561,0	586,0	
				258,0 284,0	273,0 296,0	310,0 341,0	327,0 355,0	413,0 454,0	436,0 474,0	580,0 639,0	614,0 666,0	697,0 767,0	736,0 799,0	
M22	34	2,5	2,0	355,0	373,0	426,0	448,0	568,0	597,0	798,0	840,0	958,0	1.008,0	
M24	36	3,0	2,0	359,0	386,0	431,0	463,0	574,0	617,0	808,0	868,0	969,0	1.041,0	
		3,0	2,0	446,0	488,0	535,0	586,0	714,0	781,0	1.004,0	1.098,0	1.204,0	1.317,0	
M27	41	3,0	2,0	525,0 656,0	561,0 712,0	630,0 788,0	673,0 855,0	840,0 1.050,0	897,0 1.139,0	1.181,0 1.477,0	1.261,0 1.602,0	1.418,0 1.772,0	1.513,0 1.923,0	
1420	16	2.5	2.0	716,0	780,0	859,0	936,0	1.146,0	1.248,0	1.611,0	1.754,0	1.933,0	2.105,0	
M30	46	3,5	2,0	893,0	994,0	1.072,0	1.193,0	1.429,0	1.590,0	2.009,0	2.236,0	2.411,0	2.648,0	
М33	50	3,5	2,0	968,0	1.045,0	1.162,0	1.254,0	1.549,0	1.673,0	2.179,0	2.351,0	2.614,0	2.821,0	
		•	*	1.213,0	1.335,0	1.456,0	1.602,0	1.941,0	2.136,0	2.792,0	3.004,0	3.275,0	3.605,0	
М36	55	4,0	3,0	1.248,0 1.561,0	1.310,0 1.658,0	1.498,0 1.873,0	1.572,0 1.989,0	1.997,0 2.497,0	2.096,0 2.652,0	2.809,0 3.511,0	2.948,0 3.730,0	3.370,0 4.213,0	3.537,0 4.476,0	
Mag	60	4.0	2.0	1.615,0	1.690,0	1.938,0	2.028,0	2.584,0	2.703,0	3.633,0	3.802,0	4.360,0	4.562,0	
M39	00	4,0	3,0	2.026,0	2.144,0	2.431,0	2.573,0	3.242,0	3.430,0	4.559,0	4.824,0	5.471,0	5.789,0	

The torque values are to be considered as reference only as they can vary depending on the kind of coupling (rigid, semi-rigid, elastic, etc.), on the material on wich the bolts have to be fixed on, on the lenght of the bolt, on the kind of the wrench used (impact wrench, friction wrwnch, continuous torque wrench, etc.), on the finishing condition of the thread etc. Therefore it is advised to test the coupling to identify the most correct way to tighten them. In the event that the coupling is done with locknuts or self-locking nuts, the value of the torque has to be increased by approximately 15%.



# WHEEL MOTORS





## WHEEL MOTORS WITHOUT GEARBOX

P05R 20/A

P05R F 25





### **TECHNICAL SPECIFICATION**

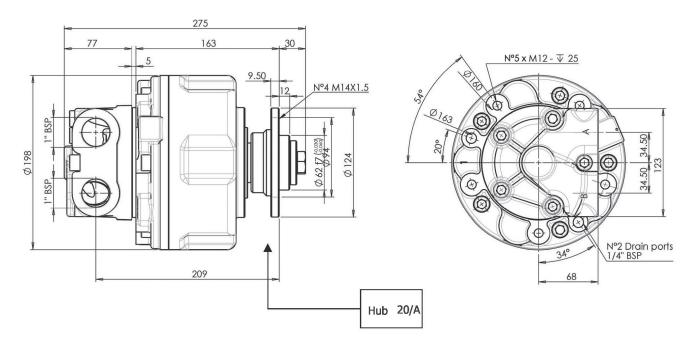
		60	75	110	130	150		170	200
Displacement	[cc/rev]	59	74	115	129	151		166	191
Bore	[mm]	25	28	35	37	40		42	45
Stroke	[mm]				24				
Specific torque	[Nm/bar]	0,94	1,18	1,84	2,05	2,40		2,65	3,04
Continuous pressure	[bar]				250				
Peak pressure (1)	[bar]	450	425	400	375	325		325	280
Peak power (2)	[kW]	20	33	33	33	33		33	33
Continuous speed (3)	[rpm]	700	700	650	650	650		600	600
Maximum speed (3)	[rpm]	1000	1000	900	900	900		800	800
Approximative weight with hub	[kg]	15	unit	Approxim	native weight with	n brake	[kg]	16	unit
Maximum casing pressure	[bar]	1 5	continuous peak	Admissib	le temperatures		[°C]	-20 +80	minimum maximum
Type of brake		Positive	e drum brake	Static bra	aking torque		[Nm]	500	
Unit oil capacity	[1]	0,8		Maximum	n cable force		[N]	1250	
Bolt torque setting	[Nm]	69,0 85,0	coarse 72,0 fine	e Suggeste	d bolt type		M12	8,8	
			NOTES						
(1) For higher peak pressure please	contact our T	ech. D	ept.						
(2) For higher peak power please co	ntact our Tec	h. Dep	t.						

<sup>(3)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

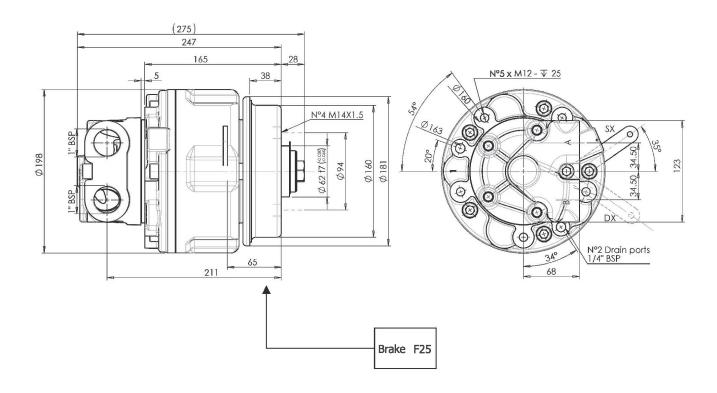


## P05R 20/A - P05R F 25 DIMENSIONAL DRAWINGS

### P05R 20/A

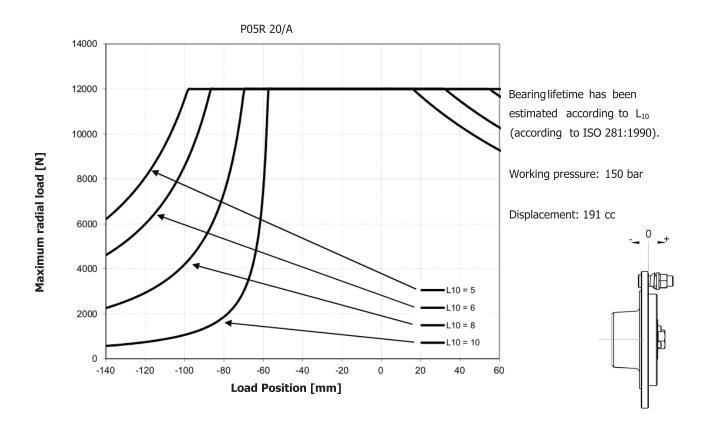


### P05R F 25





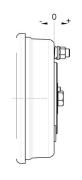
## P05R 20/A - P05R F 25 GRAPHS

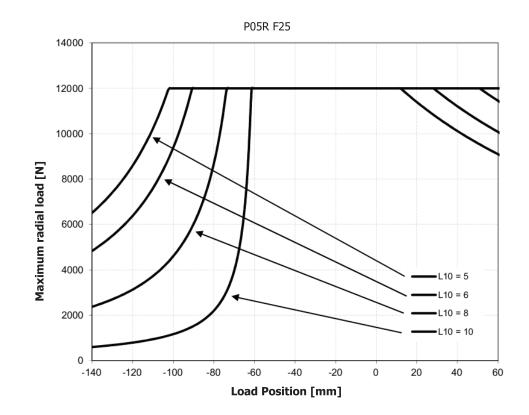


Bearing lifetime has been estimated according to  $L_{10}$  (according to ISO 281:1990).

Working pressure: 150 bar

Displacement: 191 cc







## P05R 20/A - P05R F 25 ORDER CODE

1		2	3	4	5	6
P05R +	+ 2HGPD +	+	D40 +		+ +	+

1	Displacement	see table							
2	Ontions	V	=	FKM seals					
2	Options	I	=	breath valve					
3	Distributor	see distributors section							
	DISCRIBUTOR	D40 standard							
4	<b>Direction of rotation</b> (viewed from the output side)	No code	=	clockwise rotation					
	with flow in port A, out in port B	L	=	anti-clockwise rotation					
		No code	=	position 1					
	Distributor cover	DM2	=	position 2					
5	orientation	DM3	=	position 3					
		DM4	=	position 4					
		DM5	=	position 5					
		20/A	=	hub 20/A					
6	Brake or hub option	F25SX	=	F25 brake left					
		F25DX	=	F25 brake right					

Example

P05 200 2HGPD D40 (standard)

P05R 220 2HGPDV D40L F25DX

(options: FKM seals and anti-clockwise sense of rotation)



## WHEEL MOTORS WITHOUT GEARBOX

P1G 30/A P1G F 30/D





### **TECHNICAL SPECIFICATION**

		100	11	0	130	150	175	200	220	2	50	300
Displacement	[cc/rev]	99	115	5	129	154	172	201	222	2	43	290
Bore	[mm]	28	35		32	35	37	40	42	2	14	48
Stroke	[mm]	32	24	-	32	32	32	32	32	3	32	32
Specific torque	[Nm/bar]	1,58	1,8	3	2,05	2,45	2,74	3,20	3,50	3,	.87	4,62
Continuous pressure	[bar]						250					
Peak pressure (1)	[bar]	425	400	)	400	400	375	350	350	3	50	300
Peak power (2)	[kW]						48					
Continuous speed (3)	[rpm]	550	550	)	550	550	550	550	550	4	50	350
Maximum speed (3)	[rpm]	1000	100	0	1000	1000	900	800	700	7	00	650
Approximative weight with hub	[kg]	36	unit			Approximat	ive weight	with brake	[kg]	44	unit	
Maximum casing pressure	[bar]	1 5	continue peak	ous	_	Admissible	temperatur	es	[°C]	-20 +80	minim maxin	
Type of brake		Positive	e drum bra	ake		Static braki	ng torque		[Nm]	2000		
Unit oil capacity	[1]	0,8				Maximum c	able force		[N]	1800		
Brake pilot volume	[cm³]	6,5				Maximum b	rake pilot <sub>l</sub>	oressure	[bar]	100		
Bolt torque setting	[Nm]	110,0 135,0	COarco	118,0 148,0	fine	Suggested	bolt type		M14	8,8		
				NOT	ES							

<sup>(1)</sup> For higher peak pressure please contact our Tech. Dept.

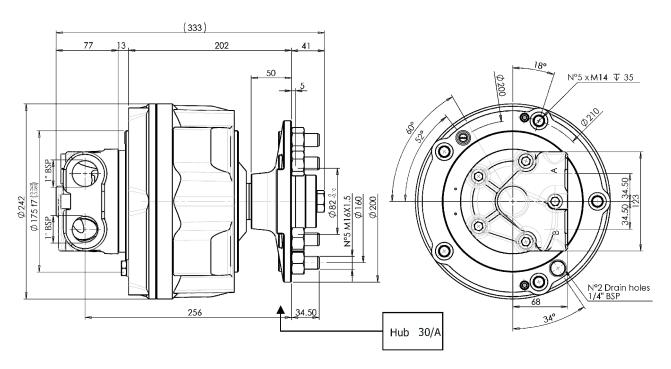
<sup>(2)</sup> For higher peak power please contact our Tech. Dept.

<sup>(3)</sup> For higher continuous and maximum speeds please contact our Tech. Dept.

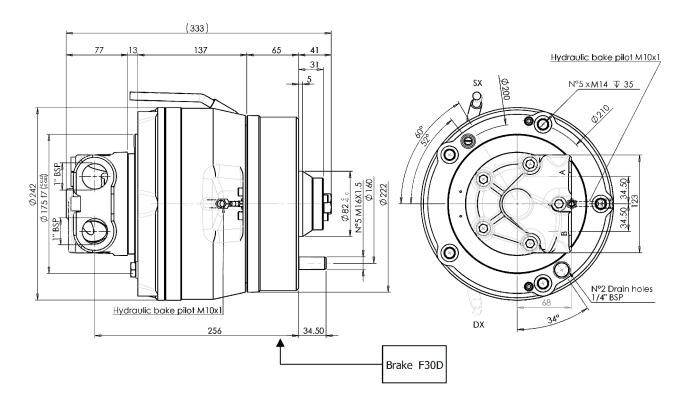


## P1G 30/A - P1G F 30/D DIMENSIONAL DRAWINGS

## P1G 30/A



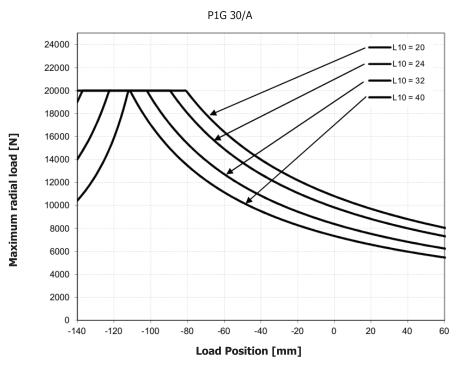
## P1G F 30/D







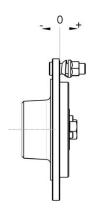
# P1G 30/A - P1G F 30/D GRAPHS



Bearing lifetime has been estimated according to  $L_{10}$  (according to ISO 281:1990).

Working pressure: 200 bar

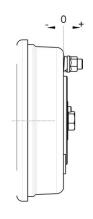
Displacement: 201 cc

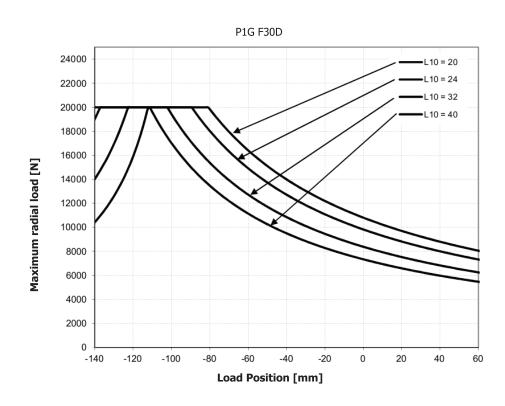


Bearing lifetime has been estimated according to  $L_{10}$  (according to ISO 281:1990).

Working pressure: 200 bar

Displacement: 201 cc





## P1G 30/A - P1G F 30/D ORDER CODE

1	2	3	4	5	6	7
P1G + + 2HGP	+	+ D40 +	+	1	+	+

1 Displacement	see table						
	V = FKM seals						
Additional	I = breath valve						
options	A = high pressure shaft seal						
	RS = integrated speed sensor						
Direction of rotation (viewed from the output side) with flow in port A, out in port B.	see distributors section						
	D40 standard						
(viewed from the output side)	No code = clockwise rotation						
	L = anti-clockwise rotation						
Direction of rotation (viewed from the output side) with flow in port A, out in port B.  Distributor cover orientation  Brake or hub option	No code = position 1						
	DM2 = position 2						
	DM3 = position 3						
	DM4 = position 4						
	DM5 = position 5						
	30/A = hub 30/A						
6 Brake or hub option	F30DSX = F30D brake left						
333	F30DDX = F30D brake right						
	1600 mm						
7 Brake cable lenght	2195 mm						
	6000 mm						

Example

P1G 200 2HGP D40

(standard)

P1G 200 2HGPV D40L F30DSX

(options: FKM seals and anti-clockwise sense of rotation)



## WHEEL MOTORS WITHOUT GEARBOX

**P2G 22/B** 

**P2G F 32** 



### **TECHNICAL SPECIFICATION**

		20	0 2	:50	300	350	420	50	00	600
Displacement	[cc/rev]	192	2 2	251	304	347	425	49	93	565
Bore	[mm]	35		40	44	47	52	5	6	60
Stroke	[mm]					40				
Specific torque	[Nm/bar]	3,0	0 3	,92	4,84	5,52	6,77	7,	85	9,50
Continuous pressure	[bar]					250				
Peak pressure (1)	[bar]	425	5 4	125	400	375	350	3!	50	300
Peak power (2)	[kW]					59				
Continuous speed (3)	[rpm]	550	) 5	550	500	500	450	4:	50	450
Maximum speed (3)	[rpm]	800	3 (	300	750	750	750	70	00	700
Approximative weight with hub	[kg]	58 unit		Approxim	ative weig	ht with brake	[kg]	61	unit	
Maximum casing pressure	[bar]	1 continuo 5 peak	ous	Admissib	e tempera	tures	[°C]	-20 +80	minim maxin	
Type of brake		Positive drum bra	ake	Static bra	king torqu	е	[Nm]	2000		
Unit oil capacity	[1]	0,8		Maximum	cable for	ce	[N]	800		
Brake pilot volume	[cm³]	6,5		Maximum	ı brake pilo	ot pressure	[bar]	100		
Bolt torque setting	[Nm]	<sup>69,0</sup> coarse 85,0	72,0 89,0 fine	Suggeste	d bolt type	!	M12	8,8		
			NOTES							

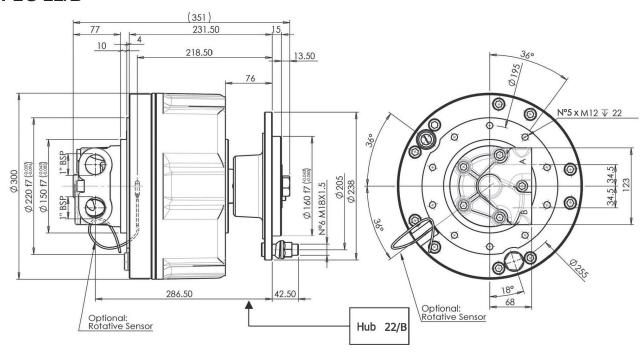
<sup>(2)</sup> For higher peak power please contact our Tech. Dept.

<sup>(3)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

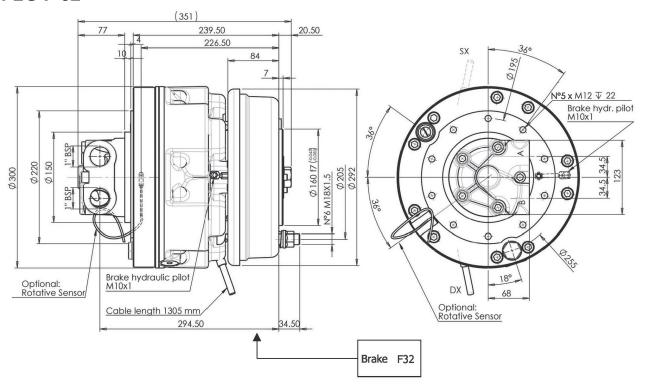


## P2G 22/B - P2G F 32 DIMENSIONAL DRAWINGS

## P2G 22/B

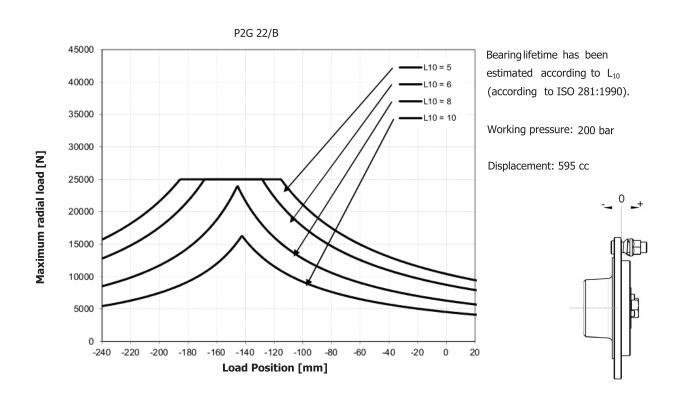


### **P2G F 32**





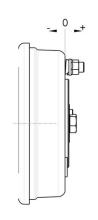
## P2G 22/B - P2G F 32 GRAPHS

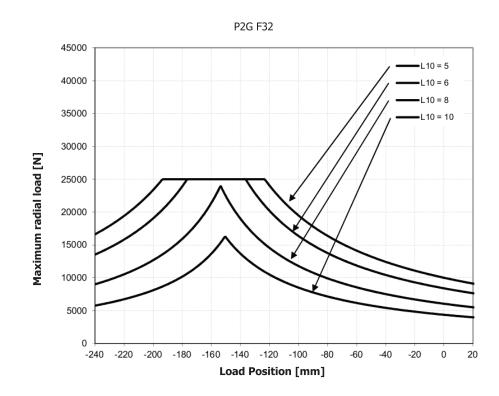


Bearing lifetime has been estimated according to  $L_{10}$  (according to ISO 281:1990).

Working pressure: 200 bar

Displacement: 595 cc





## P2G 22/B - P2G F 32 ORDER CODE

1	2	3	4	5	6	7
P2G + + 2HGPD +	+	D40 +	+	+	+	

1 Displacement	see table						
2 Additional options	V = FKM seals						
	I = breath valve						
	A = high pressure shaft seal						
	RS = integrated speed sensor						
3 <b>Distributor</b>	see distributors section						
	D40 standard						
<b>Direction of rotation</b> 4 (viewed from the output side) with flow in port A, out in port B.	No code = clockwise rotation						
	L = anti-clockwise rotation						
5 <b>Distributor cover orientation</b>	No code = position 1						
	DM2 = position 2						
	DM3 = position 3						
	DM4 = position 4						
	DM5 = position 5						
6 Brake or hub option	22/B = hub 22/B						
	F32SX = F32 brake left						
	F32DX = F32 brake right						
Brake cable lenght	1305 mm						
	1500 mm						

Example

P2G 200 2HGPD D40 (standard)

P2G 200 2HGPD D40 F30DSX

(options: FKM seals and anti-clockwise sense of rotation)



## WHEEL MOTORS WITHOUT GEARBOX

BD2 22/B (dual displacement)

BD2 F 32 (dual displacement)





### **TECHNICAL SPECIFICATION**

			500	250	500	125	350	175	350	90	250	125	250	65
Displacement	[cc/rev]		493	246	493	123	347	173	347	87	251	126	251	63
Bore	[mm] 56		6	56		47		47		40		40		
Stroke	[mm]		40	20	40	10	40	20	40	10	40	20	40	10
Specific torque	[Nm/bar]		7,85	3,91	7,80	2,00	5,50	2,80	5,50	1,40	4,00	2,00	4,00	1,00
Continuous pressure	[bar]		250		250		250		250		250		250	
Peak pressure (1)	[bar]		35	50	3	50	37	75	3	75	42	:5	42	25
Peak power (2)	[kW]		75	65	75	62	75	65	75	65	75	65	70	60
Continuous speed (3)	[rpm]		400	800	400	1500	700	1500	700	1500	700	1500	700	1500
Maximum speed (3)	[rpm]		800	1600	800	2200	1000	1800	1000	2200	1000	1800	1000	2400
Approximative weight with hub	[kg]	58	unit			Appr	oximati	ve wei	ght wit	h brake	[kg]	61	unit	
Maximum casing pressure	[bar]	1 5	continu peak	ious	Admissible temperatures				[°C]	-20 +80	minimum maximum			
Type of brake		Positive	e drum bi	rake		Stati	c brakiı	ng torq	ue		[Nm]	2000		
Motor oil capacity	[1]	3				Maxii	mum ca	able fo	ce		[N]	800		
Volume pilot change displaceme	ent [cm³]	5,568			Pilot pressure change displace ment				[bar]	25 35	minimum maximum			
Brake pilot volume	[cm³]	6,5			Maximum cylinder pressure				[bar]	100				
Suggested bolt type	M18	8,8				Maxi	mum b	rake pi	lot pre	ssure	[bar]	100		
Bolt torque setting	[Nm]	235,0 290,0	coarse	248,0 310,0	tina									
				NOTI	ES									

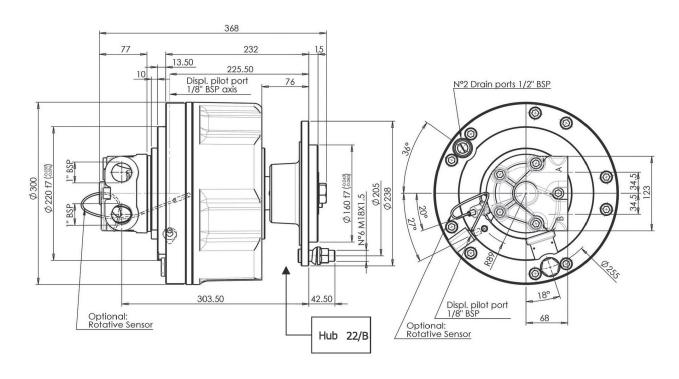
 $<sup>(1) \ \</sup> For higher peak pressure please contact our Tech. \ Dept.$ (2) For higher peak power please contact our Tech. Dept.

<sup>(3)</sup> For higher continuous and maximum speeds please contact our Tech. Dept.



## BD2 22/B - BD2 F 32 DIMENSIONAL DRAWINGS

### **BD2 22/B**

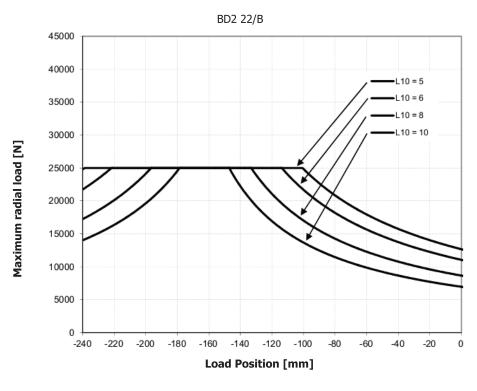


### **BD2 F 32** (368)240 20.50 233.50 N°2 Drain ports 1/2" BSP 84 Displ. pilot port 1/8" BSP axis 7 Brake hydraulic pilot M10x1 0 Ø 160 f7 (50063) 0 Ø 220 f7 (50%) 34.5 34.5 N°6 M18X1.5 Ø 205 Ø 292 123 0 Brake hydraulic pilot M10x1 18° Displ. pilot port 68 Optional: Rotative Sensor Cable length 1305 mm Brake F32





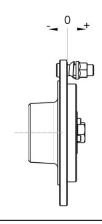
## BD2 22/B - BD2 F 32 GRAPHS



Bearing lifetime has been estimated according to  $L_{10}$  (according to ISO 281:1990).

Working pressure: 200 bar

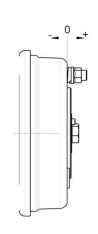
Displacement: 493 cc

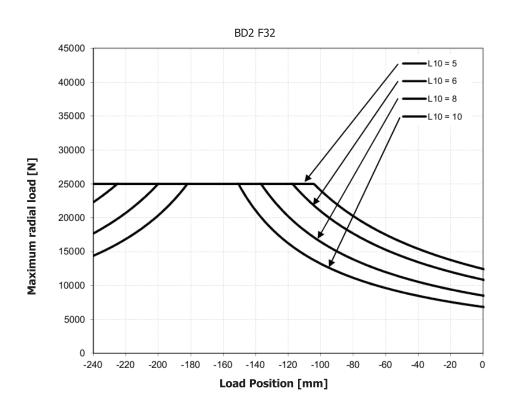


Bearing lifetime has been estimated according to  $L_{10}$  (according to ISO 281:1990).

Working pressure: 200 bar

Displacement: 493 cc







#### BD2 22/B - BD2 F 32 ORDER CODE

1	2	!	3	4	5	6	7
BD2 +	+	+ 2HGPMD +	+	D40 +	-	F	+

1 Maximum displacement	see table
Minimum displacement	see table
	V = FKM seals
3 Additional options	I = breath valve
	RS = rotative sensor
	see distributors section
4 Distributor	D40 standard
Direction of rotation	No code = clockwise rotation
5 (viewed from the output side) with flow in port A, out in port B.	L = anti-clockwise rotation
	No code = position 1
	DM2 = position 2
6 Distributor cover orientation	DM3 = position 3
	DM4 = position 4
	DM5 = position 5
	22/B = hub 22/B
7 Brake or hub option	F32SX = F32 brake left
	F32DX = F32 brake right

Example Esempio

BD2 500 125 2HGPMD D40 (standard)

BD2 500 125 2HGPMD D40L F30DSX

(options: FKM seals and anti-clockwise sense of rotation)



# WHEEL MOTORS WITH GEARBOX WR Series PRODUCT OVERVIEW



		WR6B	WR10	WR20
[Nm]		3000	6500	9650
[Nm]		4200	10000	14300
		5:1	4,80:1	6,60:1
[Nm]		3000	7000	10000
[hav]	minimum	18	15	15
[bar]	maximum	60	60	60
[kg]		47	75	90
		Negative disk brake	Negative disk brake	Negative disk brake
		GM05 GS05* GM1 GS1* BD1 BV1	GM05 GS05* GM1 GS1* BD1 BV1 GM2 GS2* BD2	GM05 GS05* GM1 GS1* BD1 BV1 GM2 GS2* BD2 BV2
	[Nm]	[Nm]  [Nm]  minimum  [bar]  maximum	[Nm] 3000  [Nm] 4200  5:1  [Nm] 3000  minimum 18  [bar] maximum 60  [kg] 47  Negative disk brake  GM05 GS05* GM1 GS1* BD1	[Nm] 3000 6500  [Nm] 4200 10000  5:1 4,80:1  [Nm] 3000 7000  [Nm] 18 15  [bar] maximum 60 60  [kg] 47 75  Negative disk brake Negative disk brake  GM05 GS05* GS05* GM1 GS1* BD1 BD1 BV1 GM2 GS2*

 $<sup>\</sup>hbox{$^*$ For further information on the use of the high speed GS Series Motors on these gearboxes please contact our Tech. Dept.}\\$ 



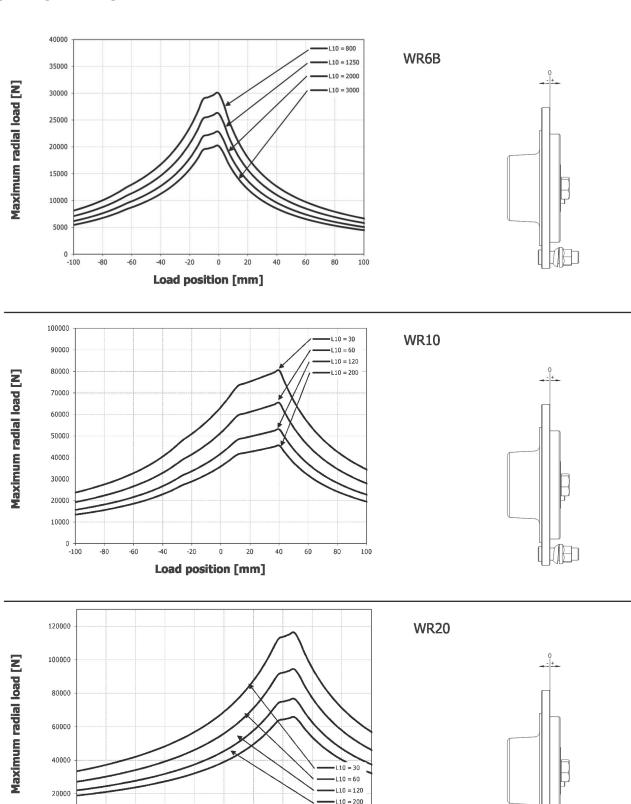
#### WHEEL MOTORS WITH GEARBOX WR Series

#### **LOAD GRAPHS**

0 <del>├</del> -100

-60

Load position [mm]



80

100



#### WHEEL MOTORS WITH GEARBOX WR Series

GM05 + WR6B (fixed displacement)

#### **TECHNICAL SPECIFICATION**



		200	300	400	450	600	650	750	850	950
Equivalent displacement (1)	[cc/rev]	196	295	369	430	577	645	754	831	954
Reduction ratio						5:1				
Bore	[mm]	25	25	28	37	35	37	40	42	45
Stroke	[mm]	16	24	24	16	24	24	24	24	24
Specific torque	[Nm/bar]	3,10	4,70	5,90	6,85	9,15	10,25	12,00	13,20	15,20
Continuous pressure	[bar]	250	250	250	250	250	250	250	250	250
Peak pressure (2)	[bar]	450	450	425	375	400	375	325	315	275
Peak power (3)	[kW]	20	20	33	33	33	33	33	33	33
Continuous speed (4)	[rpm]	140	140	140	140	130	130	130	120	120
Maximum speed (4)	[rpm]	200	200	200	200	180	180	180	160	160
Approximative weight	[kg]	72	unit		Type of bra	ke		Negative o	lisc brake	
Maximum casing pressure	[bar]	1 5	continuous peak		Admissible	temperatu	res	[°C]		imum kimum
Motor oil capacity	[1]	0,8			Static brakii	ng torque	(5)	[Nm]	3000	
Gearbox oil capacity	[1]	0,5			Minimum bi	ake pilot p	oressure	[bar]	18	
Brake pilot volume	[cm³]	14			Maximum b	rake pilot	pressure	[bar]	60	
Bolt torque setting	[Nm]	287, 357,	0 coarse 303,0 382,0	11111	Suggested I	oolt type		M16	12.9	
			NO	TES						

NOTES

 $<sup>(1) \</sup> Equivalent \ displacement = motor \ displacement \ x \ reduction \ ratio \ of \ gearbox \ (5:1)$ 

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

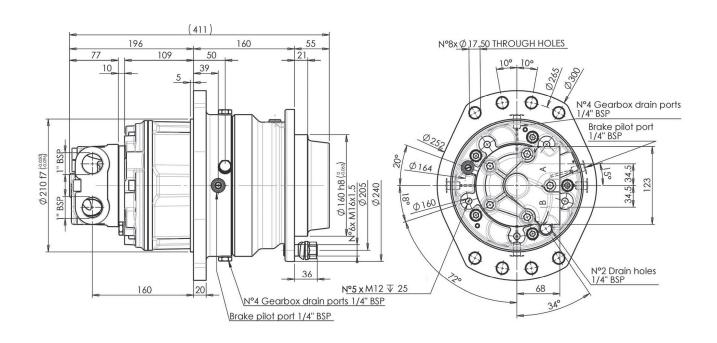
<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

The brake requires to be periodically engaged and disengaged to mantain the desired performance.



#### **GM05 + WR6B - INSTALLATION DRAWINGS**

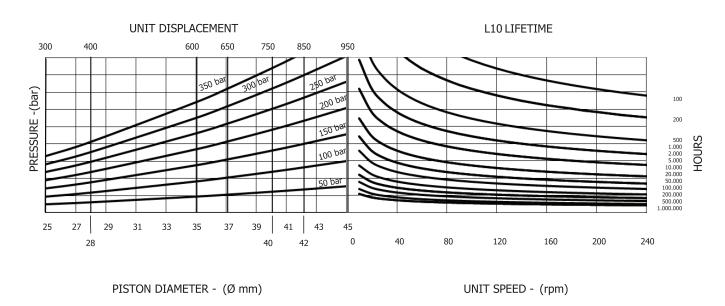


#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 24 mm.

Please contact our Technical Department for other graphs relating to this product.





#### WHEEL MOTORS WITH GEARBOX WR Series

GM1 + WR6B (fixed displacement)



		50	00	650	775		860	1000
Equivalent displacement (1)	[cc/rev]	4	95	645	770		860	1005
Reduction ratio					5:1			
Bore	[mm]	2	28	32	35		37	40
Stroke	[mm]				32			
Specific torque	[Nm/bar]	7,	84	10,27	12,26		13,69	16,00
Continuous pressure	[bar]	2	50	250	250		250	250
Peak pressure (2)	[bar]	4.	25	400	400		375	250
Peak power (3)	[kW]				48			
Continuous speed (4)	[rpm]	1	10	110	110		110	110
Maximum speed (4)	[rpm]	2	00	200	200		180	160
Approximative weight	[kg]	<sub>79</sub> un	it	Type of bra	ke	Negative	e disc b	rake
Maximum casing pressure	[bar] -	1 co	ntinuous ak	Admissible	temperatures	[°C]	-20 +80	minimum maximum
Motor oil capacity	[1]	1		Static braki	ng torque (5)	[Nm]	3000	
Gearbox oil capacity	[1]	0,5		Minimum bi	rake pilot pressure	[bar]	18	
Brake pilot volume	[cm³]	14		Maximum b	rake pilot pressure	[bar]	60	
Bolt torque setting	[Nm]	287,0 co	arse 303,0 fine	Suggested I	bolt type	M16	12.9	
			NOTES					

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (5:1)

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

 $<sup>\</sup>hbox{(3) For higher peak power please contact our Tech. Dept.}\\$ 

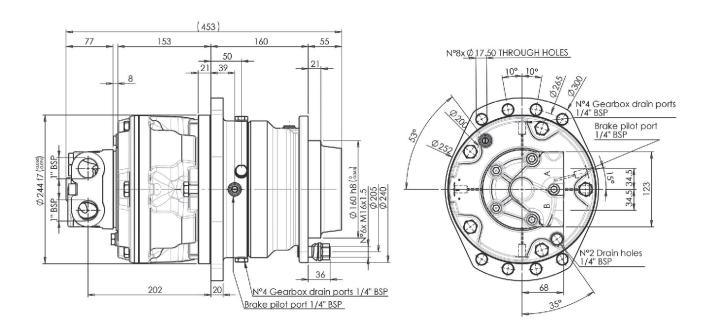
 $<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. \ Dept. \\$ 

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

The brake requires to be periodically engaged and disengaged to mantain the desired performance.

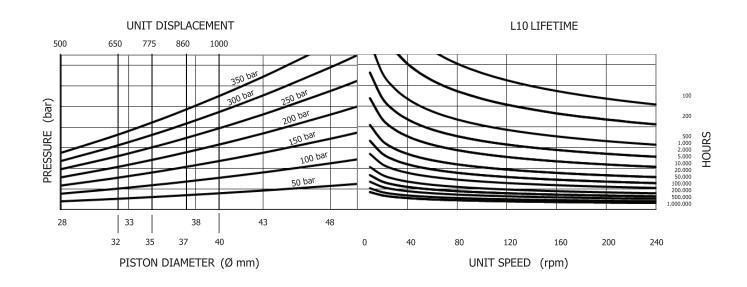


#### **GM1 + WR6B - INSTALLATION DRAWINGS**



#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





#### WHEEL MOTORS WITH GEARBOX WR Series

BD1 + WR6B (dual displacement)
BV1 + WR6B (variable displacement)



				500	270	875	225	875	400	1250	300	1250	600
Equivalent displacement (1)	[cc/rev]			510	270	860	215	880	380	1215	305	1215	608
Reduction ratio								5:1					
Bore	[mm]			37	37	37	37	44	44	44	44	44	44
Stroke	[mm]			19	10	32	8	23	10	32	8	32	16
Specific torque	[Nm/bar]			8,10	4,50	13,68	3,50	14,00	6,04	19,40	4,85	19,50	9,67
Continuous pressure	[bar]			250	250	220	250	210	250	150	250	150	250
Peak pressure (2)	[bar]			425	425	310	400	300	400	215	375	215	375
Peak power <sup>(3)</sup>	[kW]			55	42	55	42	55	42	55	42	55	42
Continuous speed (4)	[rpm]			100	250	100	250	100	250	100	250	100	250
Maximum speed (4)	[rpm]			250	250	200	250	200	250	170	250	170	250
Approximative weight	[kg]	85	unit			Туре	of brak	ке			Negative o	lisc brak	е
Maximum casing pressure	[bar]	1 5	continu peak	ious		Admis	ssible t	empera	ntures		[°C]		minimum maximum
Motor oil capacity	[1]	1,5				Static	brakin	ıg torqı	ıe (5)		[Nm]	3000	
Gearbox oil capacity	[1]	0,5				Minim	ium br	ake pilo	ot press	sure	[bar]	18	
Brake pilot volume	[cm³]	14				Maxin	num br	ake pil	ot pres	sure	[bar]	60	
Volume pilot change displacement	[cm³]	2,12					oressur cemen	e chan	ge		[bar]		minimum maximum
Suggested bolt type	M16	12.9				•							
Bolt torque setting	[Nm]	287, 357,	coarse	303,0 382,0	fine								
				NO	TES								

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

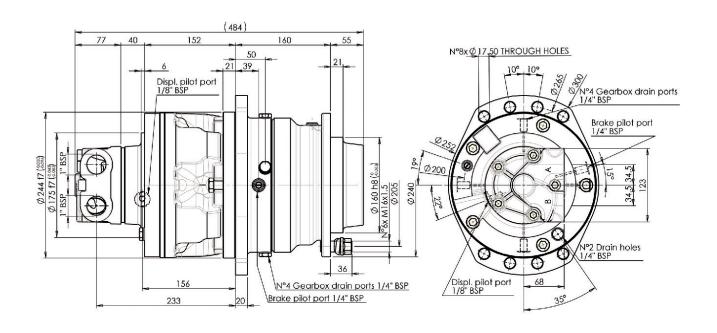
<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

 <sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

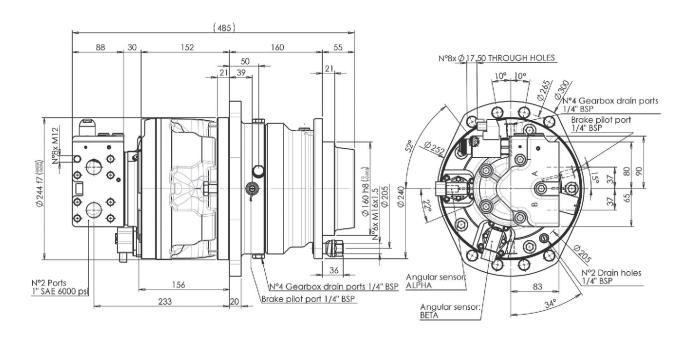
<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably. The brake requires to be periodically engaged and disengaged to mantain the desired performance.



#### **BD1 + WR6B - INSTALLATION DRAWINGS**



#### **BV1 + WR6B - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX WR Series

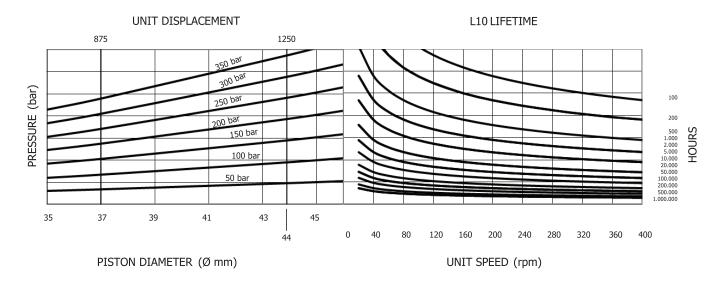
BD1 + WR6B BV1 + WR6B

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 32 mm.

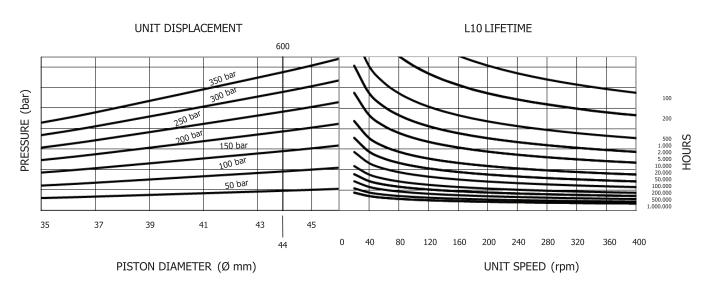
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 16 mm.

Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank



#### WHEEL MOTORS WITH GEARBOX WR Series

#### GM05 + WR10 (fixed displacement)



		200	300	350	400	550	620	725	77!	5 900
Equivalent displacement (1)	[cc/rev]	187	283	355	412	552	619	724	772	916
Reduction ratio						4,8:1				
Bore	[mm]	25	25	28	37	35	37	40	42	45
Stroke	[mm]	16	24	24	16	24	24	24	24	24
Specific torque	[Nm/bar]	2,98	4,51	5,66	6,56	8,78	9,84	11,52	12,2	9 14,59
Continuous pressure	[bar]					250				
Peak pressure (2)	[bar]	450	450	425	375	400	375	325	315	5 280
Peak power (3)	[kW]	20	20	33	33	33	33	33	33	33
Continuous speed (4)	[rpm]	145	145	145	145	135	135	135	125	5 125
Maximum speed (4)	[rpm]	200	200	200	200	185	185	185	165	5 165
Approximative weight	[kg]	97	unit		Type of bra	ke		Negative	disc brake	
Maximum casing pressure	[bar]	1 5	continuous peak	_	Admissible	temperatu	res	[°C]		minimum maximum
Motor oil capacity	[1]	0,8			Static braki	ng torque	(5)	[Nm]	7000	
Gearbox oil capacity	[1]	0,75			Minimum bi	rake pilot p	oressure	[bar]	15	
Brake pilot volume	[cm³]	37,5			Maximum b	rake pilot	pressure	[bar]	60	
Bolt torque setting	[Nm]	767,0 958,0		11116	Suggested I	bolt type		M22	12.9	
			NO	TES						

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (4,8:1)

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

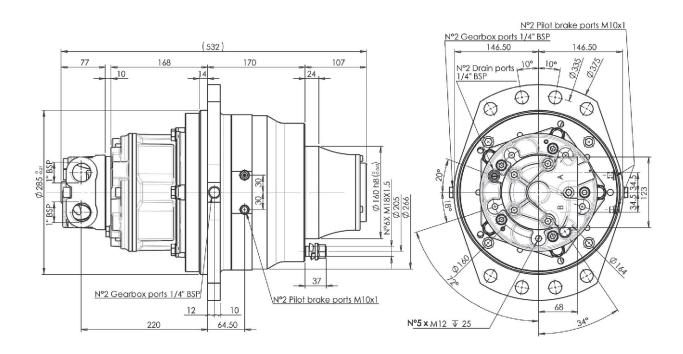
<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

The brake requires to be periodically engaged and disengaged to mantain the desired performance.



#### **GM05 + WR10 - INSTALLATION DRAWINGS**

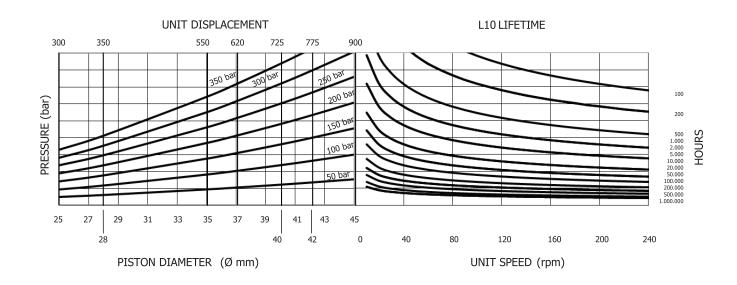


#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 24 mm.

Please contact our Technical Department for other graphs relating to this product.





#### WHEEL MOTORS WITH GEARBOX WR Series

GM1 + WR10 (fixed displacement)



		500	620	750	800	950	1050	1150	140	00	1500
Equivalent displacement (1)	[cc/rev]	475	619	739	825	964	1060	1166	139	92	1507
Reduction ratio						4,8:1					
Bore	[mm]	28	32	35	37	40	42	44	48	3	50
Stroke	[mm]					32					
Specific torque	[Nm/bar]	7,53	9,83	11,76	13,14	15,36	16,93	18,59	22,	12	24,00
Continuous pressure	[bar]					250					
Peak pressure (2)	[bar]	425	400	400	375	350	350	350	30	0	280
Peak power (3)	[kW]					48					
Continuous speed (4)	[rpm]	115	115	115	115	115	115	90	70	)	70
Maximum speed (4)	[rpm]	200	200	200	185	165	145	145	13	5	125
Approximative weight	[kg]	102	unit		Type of bra	ke		Negative	disc brake	9	
Maximum casing pressure	[bar]	1 5	continuous peak		Admissible	temperatu	res	[°C]		minimı maxim	
Motor oil capacity	[1]	1			Static braki	ng torque	(5)	[Nm]	7000		
Gearbox oil capacity	[1]	0,75			Minimum bi	rake pilot p	oressure	[bar]	15		
Brake pilot volume	[cm³]	37,5			Maximum b	rake pilot	pressure	[bar]	60		
Bolt torque setting	[Nm]	767,0 958,0	0 coarse 799,0 1008,0	HHE	Suggested I	bolt type		M22	12.9		
			NO	TES							

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (4,8:1)

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

 $<sup>\</sup>hbox{(3) For higher peak power please contact our Tech. Dept.}\\$ 

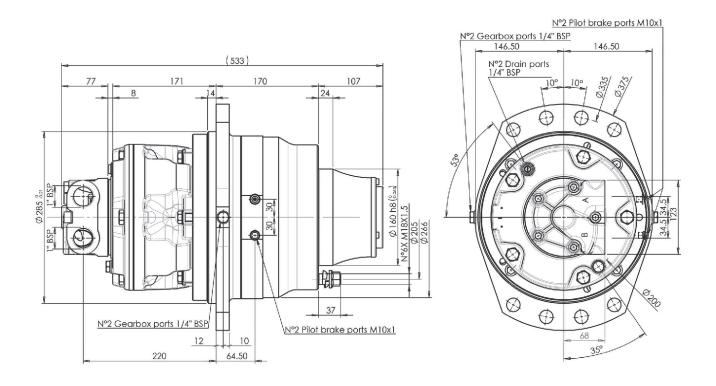
<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

The brake requires to be periodically engaged and disengaged to mantain the desired performance.

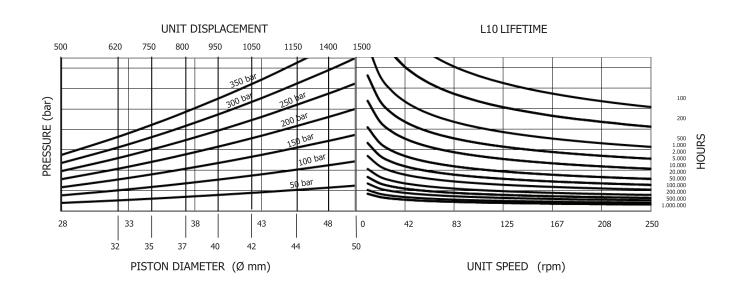


#### **GM1 + WR10 - INSTALLATION DRAWINGS**



#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.



# HANSA-TMP

### **Wheel Motors**

#### WHEEL MOTORS WITH GEARBOX WR Series

BD1 + WR10 (dual displacement)
BV1 + WR10 (variable displacement)



				500	250	800	200	850	375	1200	300	1200	600
Equivalent displacement (1)	[cc/rev]			489	259	825	206	845	365	1166	292	1166	584
Reduction ratio								4,8:1				•	
Bore	[mm]			37	37	37	37	44	44	44	44	44	44
Stroke	[mm]			19	10	32	8	23	10	32	8	32	16
Specific torque	[Nm/bar]			7,80	4,11	13,14	3,29	13,36	5,81	18,59	4,65	18,59	9,29
Continuous pressure	[bar]			250	250	250	250	250	250	250	250	250	250
Peak pressure (2)	[bar]			425	425	400	400	400	400	375	375	375	375
Peak power (3)	[kW]			55	42	55	42	55	42	55	42	55	42
Continuous speed (4)	[rpm]			100	200	100	200	100	200	100	200	100	200
Maximum speed (4)	[rpm]			200	200	200	200	200	200	175	200	175	200
Approximative weight	[kg]	110	unit			Туре	of bra	ike			Negative (	disc brak	e
Maximum casing pressure	[bar]		continu peak	ous	-	Adm	issible	temper	atures		[°C]	-20 +80	minimum maximum
Motor oil capacity	[1]	1,5				Stati	c braki	ng torq	ue (5)		[Nm]	7000	
Gearbox oil capacity	[1]	0,75				Minir	num b	rake pil	ot pres	sure	[bar]	15	
Brake pilot volume	[cm³]	37,5				Maxi	mum b	orake pi	lot pre	ssure	[bar]	60	
Volume pilot change	[cm³]	2,12						ıre chai	nge		[bar]	25	minimum
displacement Suggested bolt type	Maa	12.0				aispi	aceme	nt				35	maximum
Bolt torque setting	M22 [Nm]	767,0 958,0	coarse	799,0 1008,0	rine								
				NOTE	S								
(1) Equivalent displacement = moto	r displacement	x reduction	n ratio of	gearbox	(4,8:1)								
(2) For higher peak pressure please of	ontact our Tech	ı. Dept.											
(3) For higher peak power please co	ntact our Tech. I	Dept.											
/A) = 1 · 1 · · · · · · · · · · · · · · · ·	1.1		<b>.</b>	<b>D</b> (									

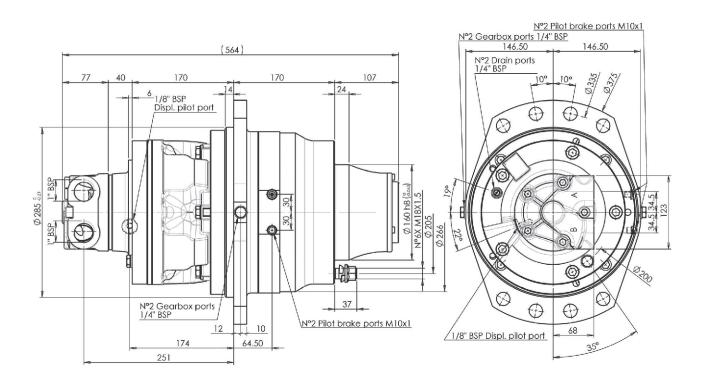
<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

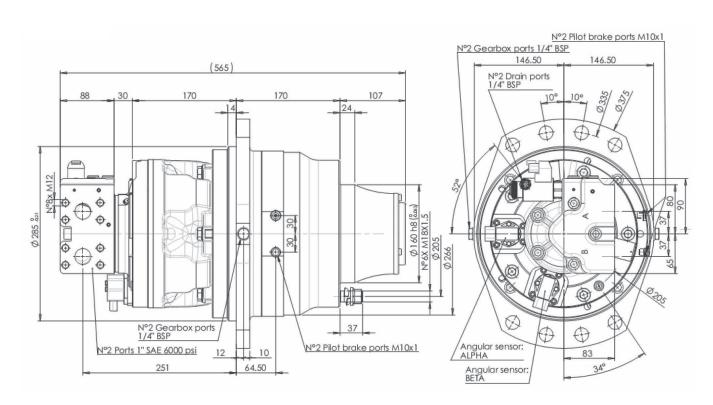
The brake requires to be periodically engaged and disengaged to mantain the desired performance.



#### **BD1 + WR10 - INSTALLATION DRAWINGS**



#### **BV1 + WR10 - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX WR Series

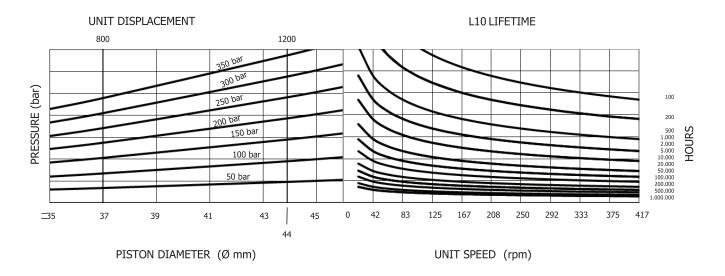
BD1 + WR10 BV1 + WR10

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 32 mm.

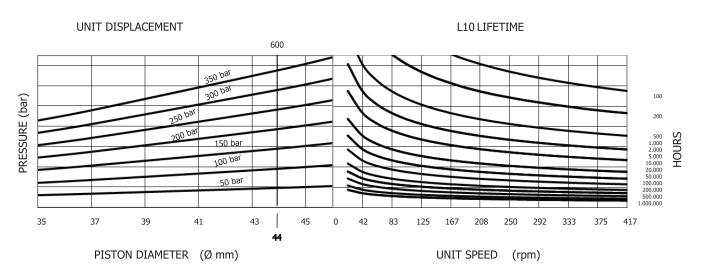
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 16 mm.

Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank



#### WHEEL MOTORS WITH GEARBOX WR Series

GM2 + WR10 (fixed displacement)



			900	1200	1450	1650	2000	2350	27	00	3000
Equivalent displacement (1)	[cc/rev]		921	1204	1459	1665	2040	2366	27	'12	2990
Reduction ratio						4,8:1					
Bore	[mm]		35	40	44	47	52	56	6	50	63
Stroke	[mm]					4	10				
Specific torque	[Nm/ bar]		14,70	19,20	23,23	26,51	32,45	37,63	43	,20	47,63
Continuous pressure	[bar]		250	250	250	250	200	175	1	50	135
Peak pressure (2)	[bar]		425	400	400	375	310	270	2	35	210
Peak power (3)	[kW]					į	59				
Continuous speed (4)	[rpm]		110	110	100	100	90	90	g	90	80
Maximum speed (4)	[rpm]		165	155	155	155	155	145	1	45	135
Approximative weight	[kg]	126	unit		Type of br	ake		Negative	disc brak	æ	
Maximum casing pressure	[bar]	<u>1</u> 5	continuous peak		Admissible	temperatu	res	[°C]	-20 +80	minii maxi	mum imum
Motor oil capacity	[1]	2			Static brea	king torque	(5)	[Nm]	7000		
Gearbox oil capacity	[1]	0,75			Minimum b	orake pilot p	oressure	[bar]	15		
Brake pilot volume	[cm³]	37,5			Maximum	brake pilot	pressure	[bar]	60		
Bolt torque setting	[Nm]	767, 958,	0 coarse 799,0 1008,0	HILLE	Suggested	bolt type		M22	12.9		
			NO	TES							

 $<sup>(1) \</sup> Equivalent \ displacement = motor \ displacement \ x \ reduction \ ratio \ of \ gearbox \ (4,8:1)$ 

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

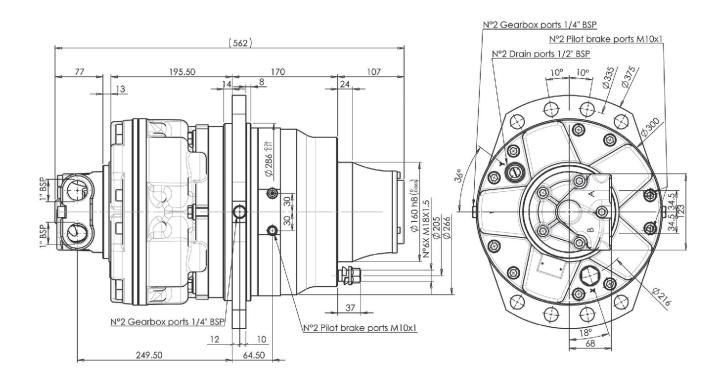
 $<sup>\</sup>hbox{(3) For higher peak power please contact our Tech. Dept.}\\$ 

 <sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.  $The \ brake\ requires\ to\ be\ periodically\ engaged\ and\ disengaged\ to\ mantain\ the\ desired\ performance.$ 

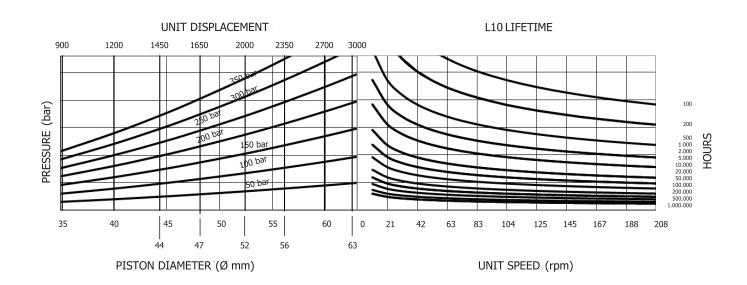


#### **GM2 + WR10 - INSTALLATION DRAWINGS**



#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





#### WHEEL MOTORS WITH GEARBOX WR Series

BD2 + WR10 (dual displacement)
BV2 + WR10 (variable displacement)



			1200	300	1200	600	1650	420	1650	850	2350	600	2350	1200
Equivalent displacement (1)	[cc/rev]		1204	302	1204	604	1665	417	1665	830	2366	590	2366	1180
Reduction ratio								4,8:1						
Bore	[mm]		40	0	4	Ю	4	7	4	7	56	5	5	56
Stroke	[mm]		40	10	40	20	40	10	40	20	40	10	40	20
Specific torque	[Nm/bar]		19,20	4,80	19,20	9,60	26,51	6,63	26,51	13,25	37,63	9,41	37,63	18,82
Continuous pressure	[bar]		250	250	250	250	250	250	250	250	170	250	170	250
Peak pressure (2)	[bar]		425	425	425	425	375	375	375	375	265	350	265	350
Peak power (3)	[kW]		75	65	75	65	75	65	75	65	75	65	75	65
Continuous speed (4)	[rpm]		145	200	145	200	140	200	140	200	140	200	140	200
Maximum speed (4)	[rpm]		200	200	200	200	200	200	200	200	165	200	165	200
Approximative weight	[kg]	125	unit	'		Туре	of brake		ı		Negative	disc br	ake	
Maximum casing pressure	[bar]	1 5	continu peak	ous		Admis	sible ter	nperat	ures		[°C]		minimu maxim	
Motor oil capacity	[1]	3				Static	braking	torque	e <sup>(5)</sup>		[Nm]	7000		
Gearbox oil capacity	[1]	0,75				Minim	um brak	e pilot	pressu	re	[bar]	15		
Brake pilot volume	[cm³]	37,5				Maxim	um bra	ke pilo	t pressu	ire	[bar]	60		
Bolt torque setting	[Nm]	767,0 958,0	coarse	799,0 1008,0	mie i	Sugge	sted bo	lt type			M22	12.9		
				NOTE	S									

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

 $<sup>\</sup>hbox{(3) For higher peak power please contact our Tech. Dept.}\\$ 

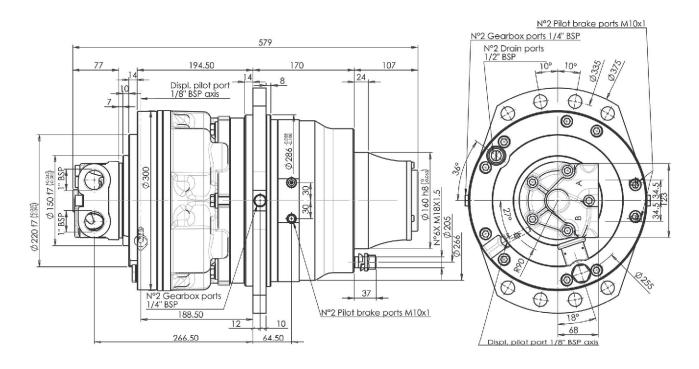
 $<sup>(4)</sup> For higher continuous and maximum speed please contact our {\it Tech}. Dept. \\$ 

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

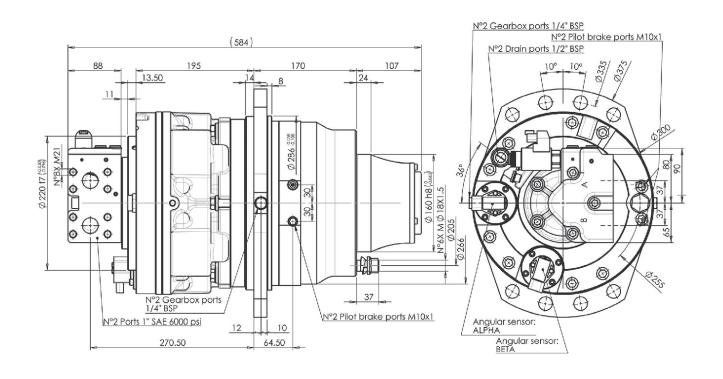
The brake requires to be periodically engaged and disengaged to mantain the desired performance.



#### **BD2 + WR10 - INSTALLATION DRAWINGS**



#### **BV2 + WR10 - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX WR Series

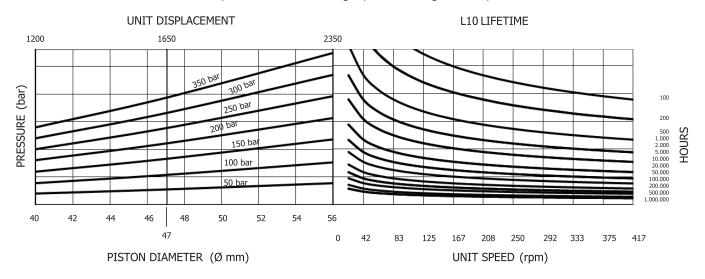
**BD2 + WR10 BV2 + WR10** 

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 40 mm.

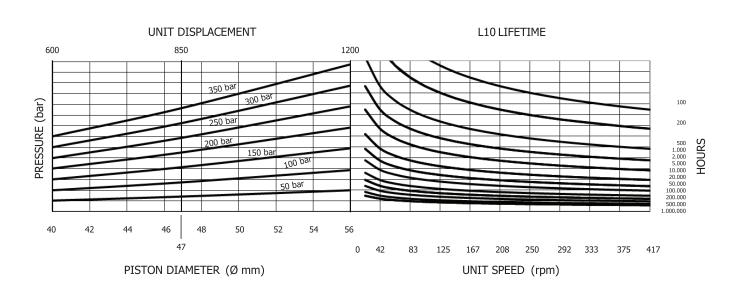
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 20 mm.

Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank



#### WHEEL MOTORS WITH GEARBOX WR Series

GM1 + WR20 (fixed displacement)

#### **TECHNICAL SPECIFICATION**



		650	85	0	1000	1100	1300	1450	1600	1900	2050
Equivalent displacement (1)	[cc/rev]	653	85	1	1016	1135	1326	1458	1603	1914	2072
Reduction ratio							6,6:1				
Bore	[mm]	28	32	2	35	37	40	42	44	48	50
Stroke	[mm]						32				
Specific torque	[Nm/bar]	10,35	13,	52	16,17	18,07	21,12	23,28	25,56	30,41	33,00
Continuous pressure	[bar]						250				
Peak pressure (2)	[bar]	425	40	0	400	375	350	350	350	300	280
Peak power (3)	[kW]						48				
Continuous speed (4)	[rpm]	80	80	)	80	80	80	80	65	50	50
Maximum speed (4)	[rpm]	150	15	0	150	135	120	105	105	95	90
Approximative weight	[kg]	117	unit			Type of b	ake		Negative	e disc brake	
Maximum casing pressure	[bar]	1 5	continu peak	ous		Admissible	e temperati	ıres	[°C]		nimum ximum
Motor oil capacity	[1]	1				Static bral	king torque	(5)	[Nm]	10000	
Gearbox oil capacity	[1]	1				Minimum	brake pilot	pressure	[bar]	15	
Brake pilot volume	[cm³]	37,5				Maximum	brake pilot	pressure	[bar]	60	
Bolt torque setting	[Nm]	767,0 958,0	) coarse	799,0 1008,0	fine	Suggested	l bolt type		M22	12.9	
				NOTE	S						
(1) Equivalent displacement = motor	displacement x i	eductio	n ratio of	gearbox	(6,6 :1)						
(2) For higher peak pressure please c	ontact our Tech. I	Dept.									
(3) For higher peak power please cor	ntact our Tech. De	pt.									

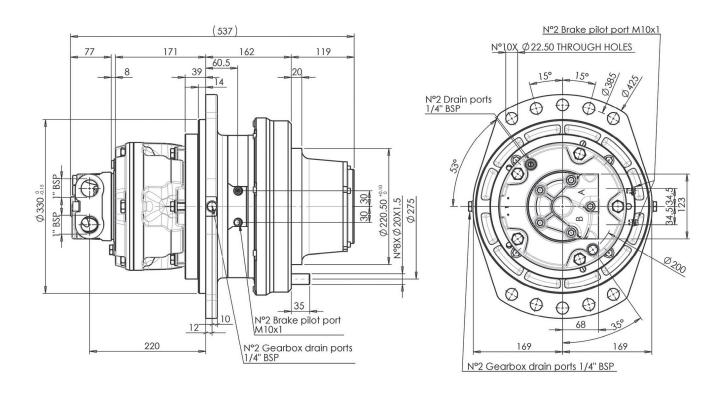
<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

The brake requires to be periodically engaged and disengaged to mantain the desired performance.

(4) For higher continuous and maximum speed please contact our Tech. Dept.

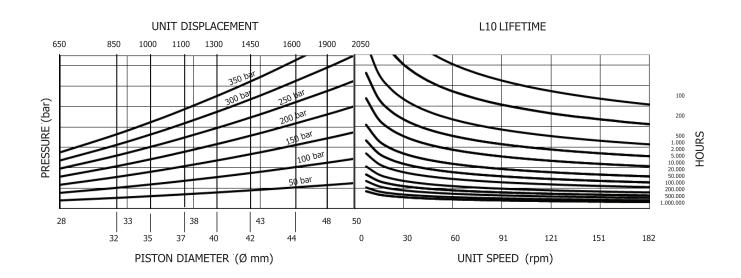


#### **GM1 + WR20 - INSTALLATION DRAWINGS**



#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





#### WHEEL MOTORS WITH GEARBOX WR Series

BD1 + WR20 (dual displacement)
BV1 + WR20 (variable displacement)



				685	350	1100	300	1150	500	1600	400	1600	800
Equivalent displacement (1)	[cc/rev]			673	356	1135	283	1154	502	1603	402	1603	802
Reduction ratio								6,6:1					
Bore	[mm]			37	37	37	37	44	44	44	44	44	44
Stroke	[mm]			19	10	32	8	23	10	32	8	32	16
Specific torque	[Nm/bar]			10,73	5,65	18,07	4,52	18,37	7,99	25,56	6,39	25,56	12,73
Continuous pressure	[bar]			250	250	250	250	250	250	250	250	250	250
Peak pressure (2)	[bar]			425	425	400	400	400	400	375	375	375	375
Peak power (3)	[kW]			55	42	55	42	55	42	55	42	55	42
Continuous speed (4)	[rpm]			75	150	75	150	75	150	75	150	75	150
Maximum speed (4)	[rpm]			150	150	150	150	150	150	125	150	125	150
Approximative weight	[kg]	125 ι	unit			Туре	e of bra	ake			Negative	disc br	ake
Maximum casing pressure	[bar]		continu beak	lous		Adm	issible	temper	atures		[°C]		minimum maximum
Motor oil capacity	[1]	1,5				Stati	c brak	ing torc	ue (5)		[Nm]	10000	
Gearbox oil capacity	[1]	1				Minii	mum b	rake pi	ot pre	ssure	[bar]	15	
Brake pilot volume	[cm³]	37,5				Maxi	mum l	orake pi	lot pre	ssure	[bar]	60	
Volume pilot change displacement	[cm³]	2,12					pressi aceme	ire char ent	nge		[bar]	25 35	minimum maximum
Bolt torque setting	[Nm]	767,0 958,0	coarse	799,0 1008,0	fine	Sugg	gested	bolt typ	е		M22	12.9	)
				NOTE	S	•							

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (6,6:1)

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

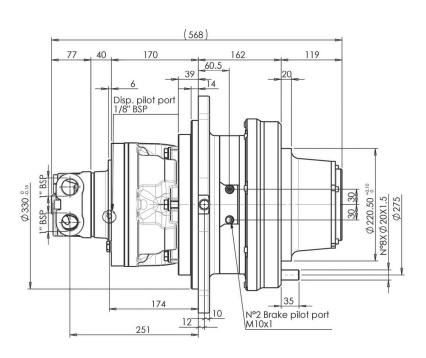
<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

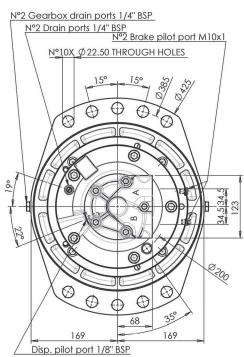
<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably. The brake requires to be periodically engaged and disengaged to mantain the desired performance.

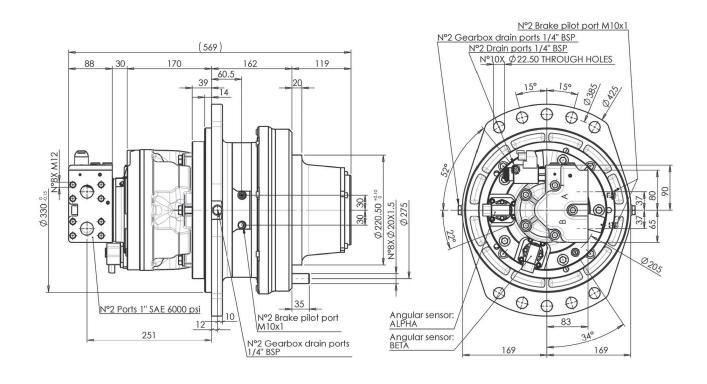


#### **BD1 + WR20 - INSTALLATION DRAWINGS**





#### **BV1 + WR20 - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX WR Series

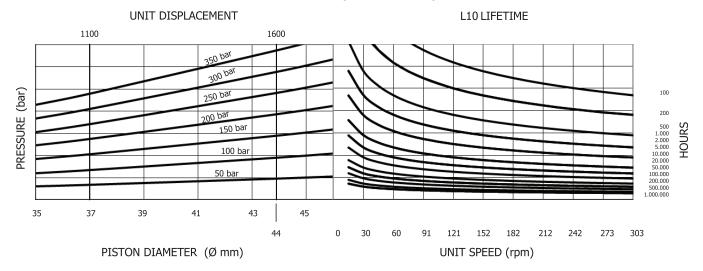
BD1 + WR20 BV1 + WR20

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 32 mm.

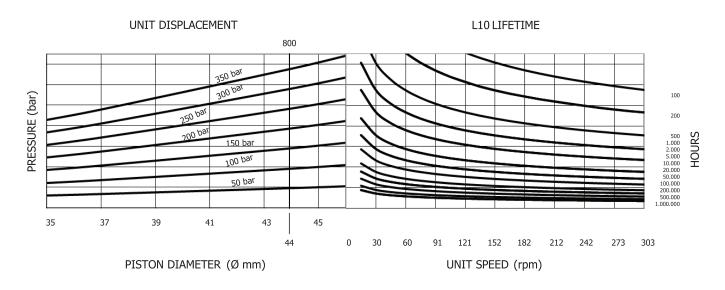
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 16 mm.

Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank



#### WHEEL MOTORS WITH GEARBOX WR Series

GM2 + WR20 (fixed displacement)



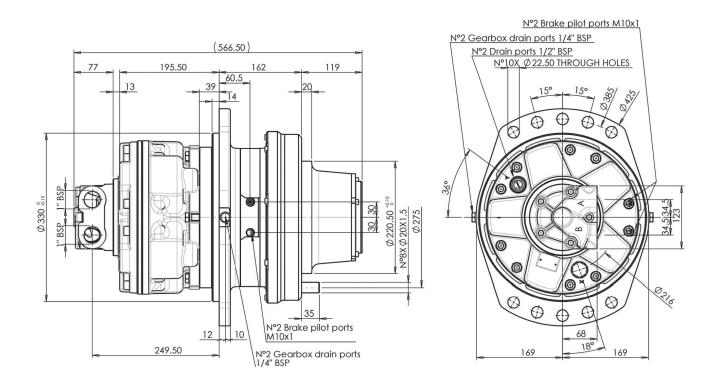
			1250	1650	2000	2300	2800	3250	37!	50	4100
Equivalent displacement (1)	[cc/rev]		1267	1656	2006	2290	2805	3253	372	29	4111
Reduction ratio						6,6:1					
Bore	[mm]		35	40	44	47	52	56	60	)	63
Stroke	[mm]					40					
Specific torque	[Nm/bar]		20,21	26,40	31,94	36,45	44,65	51,74	53,	40	65,49
Continuous pressure	[bar]		250	250	250	250	250 220		165		150
Peak pressure (2)	[bar]		425	425	400	375	325	280	245		220
Peak power (3)	[kW]					59					
Continuous speed (4)	[rpm]		80	80	80	80	70	70	65		60
Maximum speed (4)	[rpm]		150	150	150	150 135		105	10	5	95
Approximative weight	[kg]	117	unit Type of brake						Negative disc brak		
Maximum casing pressure	[bar]	1 5	continuous Admissible temperatures							minir maxi	mum mum
Motor oil capacity	[1]	1	Static braking torque (5)						10000		
Gearbox oil capacity	[1]	1			Minimum b	rake pilot p	[bar]	15			
Brake pilot volume	[cm³]	37,5			Maximum brake pilot pressure			[bar]	60		
Bolt torque setting	[Nm]	767, 958,	0 coarse 799,	M22	12.9						
		, 	NO <sup>-</sup>								
(1) Equivalent displacement = motor	r displacement x	educti	on ratio of gearb	ox (6,6 :1)							
(2) For higher peak pressure please of	ontact our Tech. I	Dept.									
(3) For higher peak power please cou	ntact our Tech. De	pt.									
(4) For higher continuous and maxim	num speed please	conta	ct our Tech. Dept	t.							

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

The brake requires to be periodically engaged and disengaged to mantain the desired performance.

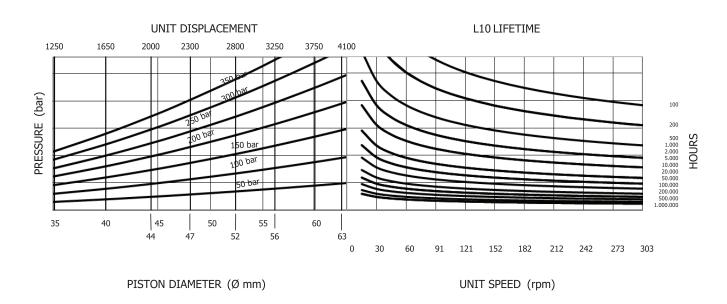


#### **GM2 + WR20 - INSTALLATION DRAWINGS**



#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





#### WHEEL MOTORS WITH GEARBOX WR Series

BD2 + WR20 (dual displacement)
BV2 + WR20 (variable displacement)

#### **TECHNICAL SPECIFICATION**



		1700	450	1700	800	2300	600	2300	1150	3300	800	3300	1600	
Equivalent displacement (1)	[cc/rev]	1656	415	1656	831	2290	574	2290	1141	3253	811	3253	1623	
Reduction ratio							6,6:1							
Bore	[mm]	40	)	4	40		47		47		56		56	
Stroke	[mm]	40	10	40	20	40	10	40	20	40	10	40	20	
Specific torque	[Nm/bar]	26,40	6,60	26,40	13,20	36,30	9,24	36,30	18,48	51,48	13,2 0	51,48	25,74	
Continuous pressure	[bar]	250	250	250	250	250	250	250	250	250	185	180	250	
Peak pressure (2)	[bar]	425	425	425	425	375	375	375	375	280	350	280	375	
Peak power (3)	[kW]	75	65	75	65	75	65	75	65	75	65	75	65	
Continuous speed (4)	[rpm]	100	150	100	150	100	150	100	150	60	150	60	150	
Maximum speed (4)	[rpm]	150	150	150	150	150	150	150	150	120	150	120	150	
Approximative weight	[kg] 140 unit					Type of brake Negative disc brake								
Maximum casing pressure	[bar] 1 continuous 5 peak					Admissible temperatures [°0						minim maxim		
Motor oil capacity	[l] 3				Static braking torque (5)					[Nm]	lm] 10000			
Gearbox oil capacity	[ ] 1				Minin	num bra	ake pil	ot press	sure	[bar]	15			
Brake pilot volume	[cm³] 37,5				Maxir	mum br	ake pi	lot pres	sure	[bar]	60			
Volume pilot change displacement	[cm³] 5,568					pressur acemen		nge		[bar]	23	minim maxim		
Bolt torque setting	[Nm] 767, 958,	Coarse	799,0 1008,0	rine	Sugg	ested b	oolt typ	е			N	<b>1</b> 22	12.9	
			NOTES	S										

(1) Equivalent displacement = motor displacement x reduction ratio of gearbox (6,6:1)

(2) For higher peak pressure please contact our Tech. Dept.

(3) For higher peak power please contact our Tech. Dept.

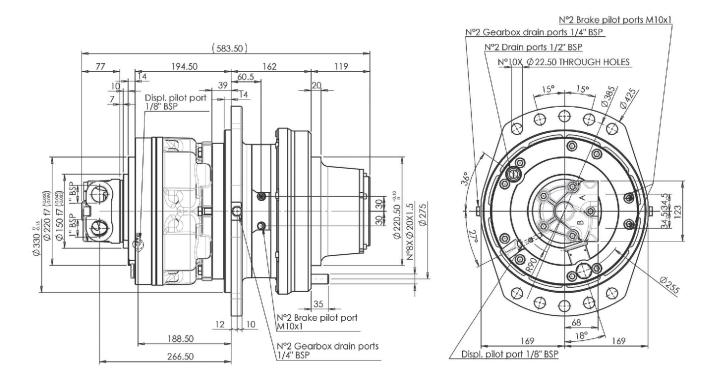
(4) For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

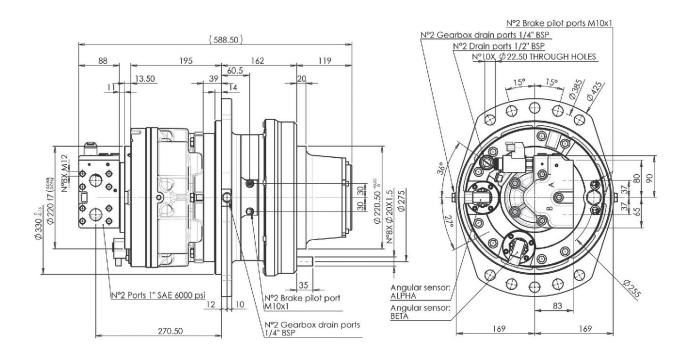
The brake requires to be periodically engaged and disengaged to mantain the desired performance.



#### **BD2 + WR20 - INSTALLATION DRAWINGS**



#### **BV2 + WR20 - INSTALLATION DRAWINGS**





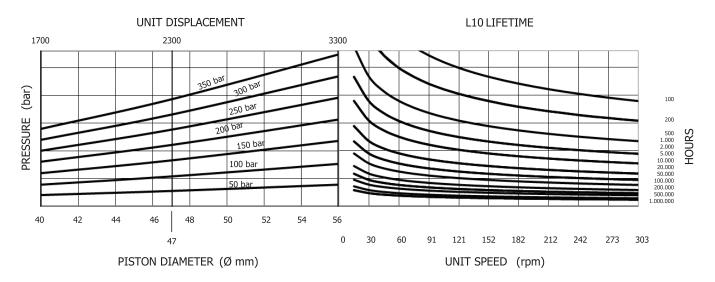
**BD2 + WR20 BV2 + WR20** 

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 40 mm.

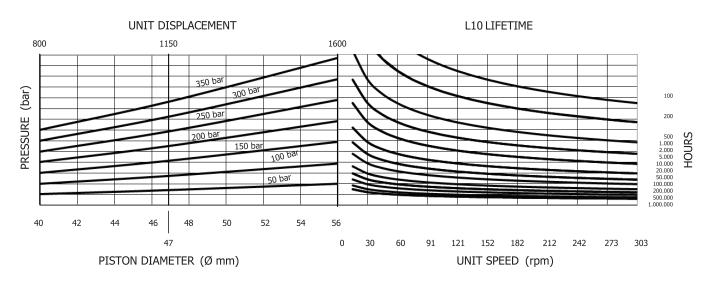
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

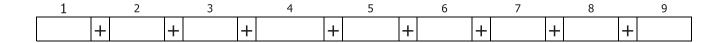
The following graph has been plotted using the stroke of 20 mm.

Please contact our Technical Department for other graphs relating to this product.





# WHEEL MOTORS WITH GEARBOX WR Series ORDER CODE



1 Motor type	
2 Displacement	see table
2 Additional and a	U = shared oil
3 Additional options	O = separated oil
4 Distributes	see distributors section
4 Distributor	D40 standard
<b>Direction of rotation</b> <sub>5</sub> (viewed from the output side)	No code = clockwise rotation
with flow in port A, out in port B.	L = anti-clockwise rotation
	No code = position 1
	DM2 = position 2
6 Distributor cover orientation	DM3 = position 3
	DM4 = position 4
	DM5 = position 5
	WR6B
7 WR series	WR10
	WR20

Example

GM05 600 U D40 WR6B (standard)

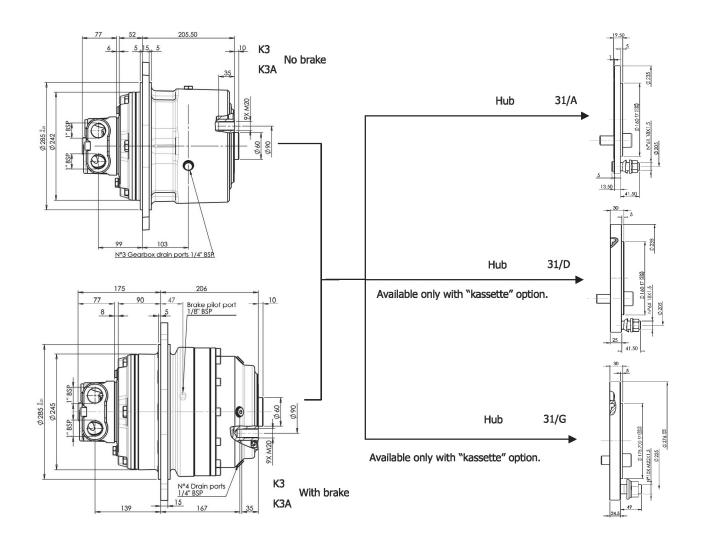
GM05 600 U D40LDM2 WR6B

(options: anti-clockwise sense of rotation)

### WHEEL MOTORS WITH GEARBOX K Series

### **PRODUCT OVERVIEW**

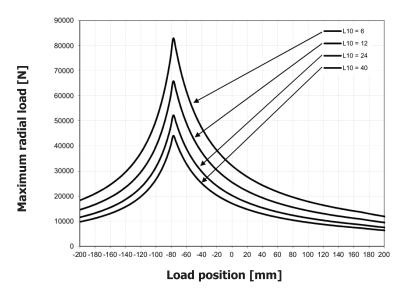
			КЗ	КЗА	К4
Maximum continuous torque	[Nm]		3500	5000	14000
Peak torque	[Nm]		7000	10000	19000
Reduction ratio			7:1	5:1	5,6:1
Maximum braking torque	[Nm]		6500	8000	18000
P. I. III.		nimum	20	20	20
Brake pilot pressure	[bar] <del></del> ma	aximum	50	50	50
Type of brake			Negative	Negative	Negative
			GK3	GK3A	GK4
			GFK3R	GFK3AR	GFK4
Available combinations			BDK3	BDK3A	BDK4
Available combinations			BDFK3R	BDFK3AR	BDFK4
			BVK3	BVK3A	BVK4
			BVFK3R	BVFK3AR	BVFK4

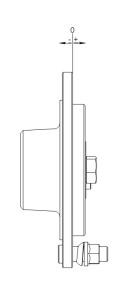




### WHEEL MOTORS WITH GEARBOX K Series

### **LOAD POSITION GRAPH**

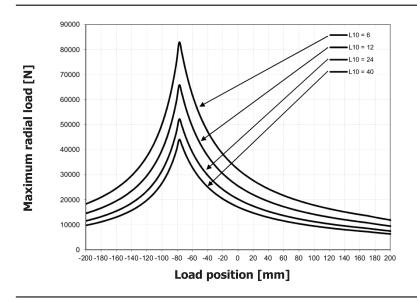


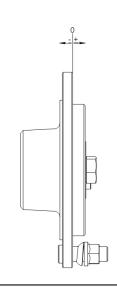


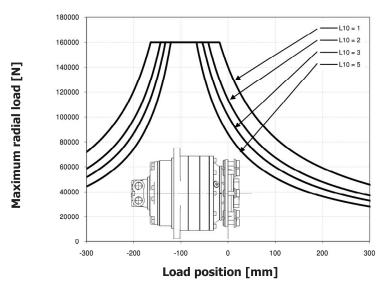
К3

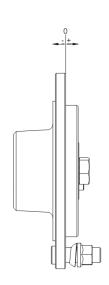
КЗА

K4











### WHEEL MOTORS WITH GEARBOX K Series

**GK3** (fixed displacement without brake)

**GFK3R** (fixed displacement with brake)



		700	900	1000	1200	1400	1600	1700	2000	2200
Equivalent displacement (1)	[cc/rev]	690	901	1078	1204	1407	1552	1703	2027	2199
Reduction ratio						7:1				
Bore	[mm]	28	32	35	37	40	42	44	48	50
Stroke	[mm]					32				
Specific torque	[Nm/bar]	10,98	14,34	17,15	19,17	22,40	24,70	27,10	32,26	35,00
Continuous pressure	[bar]	250	245	200	180	155	140	130	105	100
Peak pressure (2)	[bar]	425	400	400	365	310	280	255	215	200
Peak power (3)	[kW]					48				
Continuous speed (4)	[rpm]	78	78	78	78	78	78	64	50	50
Maximum speed (4)	[rpm]	150	150	150	130	103	100	100	100	90
Approximative weight	[kg]	75	unit		Type of bra	ke		Negative	disc brake	
Maximum casing pressure	[bar]	1 5	continuous peak		Admissible	temperatui	res	[°C]	-20 minir +80 maxi	
Motor oil capacity	[1]	1,5			Static braki	ng torque (	5)	[Nm]	6500	
Gearbox oil capacity	[1]	1,7			Minimum bi	rake pilot p	ressure	[bar]	20	
Brake pilot volume	[cm³]	3,9			Maximum b	rake pilot	pressure	[bar]	60	
Bolt torque setting	[Nm]	767,0 958,0	coarse 799,0 1008,0	fine	Suggested I	bolt type		M22	12.9	
			NOTE	S						

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (7:1)

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

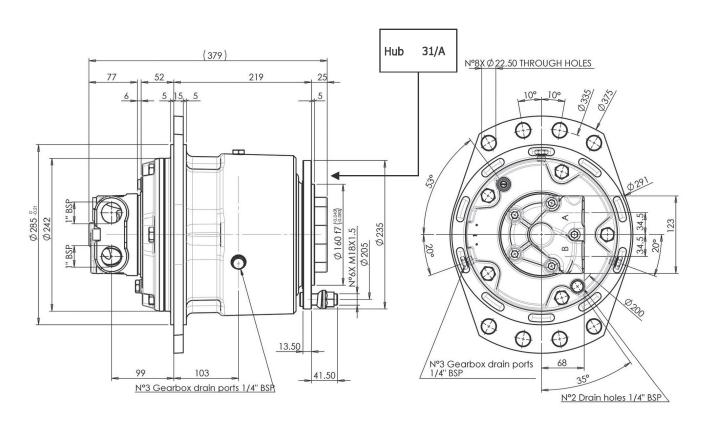
<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

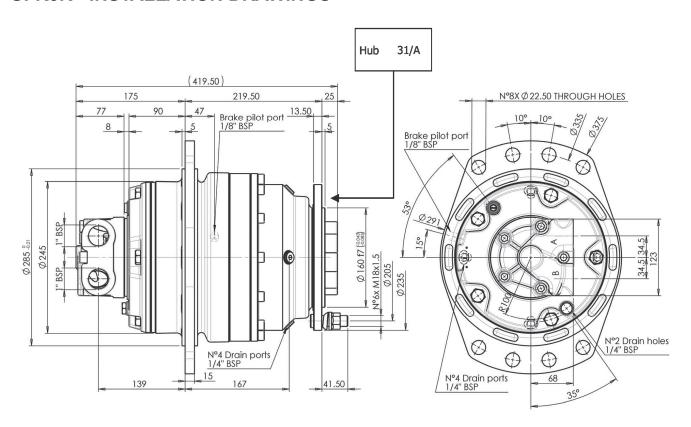
The brake requires to be periodically engaged and disengaged to mantain the desired performance.



### **GK3 - INSTALLATION DRAWINGS**



#### **GFK3R - INSTALLATION DRAWINGS**



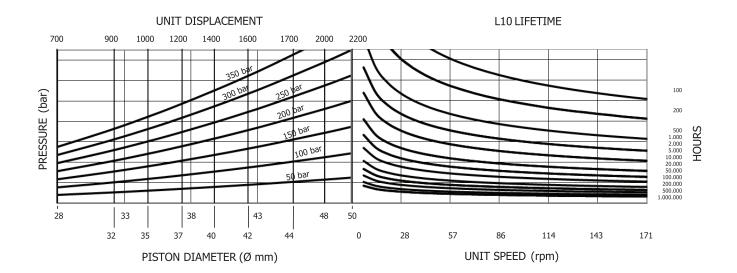


### WHEEL MOTORS WITH GEARBOX K Series

### GK3 GFK3R

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank



#### WHEEL MOTORS WITH GEARBOX K Series

BDK3 (dual displacement without brake) BDFK3R (dual displacement with brake)

BVK3 (variable displacement without brake) BVFK3R (variable displacement with brake)



				700	375	1200	300	1200	550	1700	425	1700	850
Equivalent displacement (1)	[cc/rev]			714	378	1204	301	1232	532	1701	427	1701	851
Reduction ratio								7:1					
Bore	[mm]			37	37	37	37	44	44	44	44	44	44
Stroke	[mm]			19	10	32	8	23	10	32	8	32	16
Specific torque	[Nm/bar]			11,38	5,99	19,17	4,79	19,48	8,47	27,10	6,78	27,10	13,55
Continuous pressure	[bar]			250	250	185	250	180	250	130	250	130	250
Peak pressure (2)	[bar]			425	425	370	400	355	400	250	375	250	375
Peak power (3)	[kW]			55	42	55	42	55	42	55	42	55	42
Continuous speed (4)	[rpm]			70	200	70	200	70	200	70	200	70	200
Maximum speed (4)	[rpm]			200	500	140	500	140	400	120	400	120	350
Approximative weight	[kg]	75	unit			Туре	of bral	ке			Negative o	disc brak	e
Maximum casing pressure	[bar]	1 5	continu peak	ous		Admis	ssible t	empera	tures		[°C]	-20 +80	minimum maximum
Motor oil capacity	[1]	1,5				Static	brakir	ıg torqu	ie (5)		[Nm]	6500	
Gearbox oil capacity	[1]	1,7				Minim	ium br	ake pilo	t pres	sure	[bar]	20	
Brake pilot volume	[cm³]	3,9				Maxin	num bi	ake pil	ot pres	sure	[bar]	60	
Volume pilot change displace ment	[cm³]	2,12					oressur icemer	e chan	ge		[bar]	25 35	minimum maximum
Bolt torque setting	[Nm]	454,0 568,0	coarse	474,0 597,0	fine	Sugge	ested b	olt type	e		M22	8,8	
				NOTE	S								

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (7 :1)

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

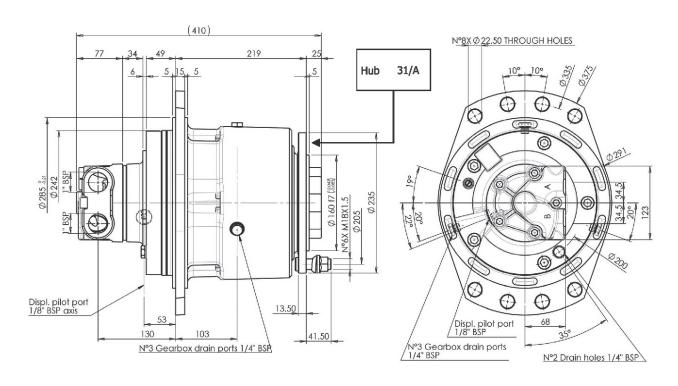
<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

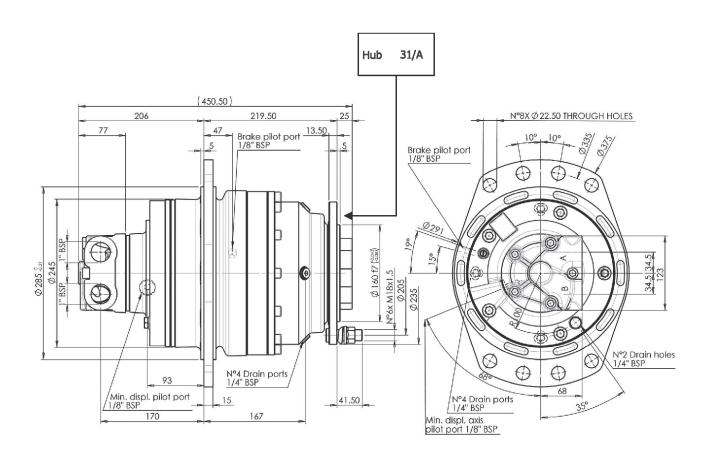
The brake requires to be periodically engaged and disengaged to mantain the desired performance.



### **BDK3 - INSTALLATION DRAWINGS**

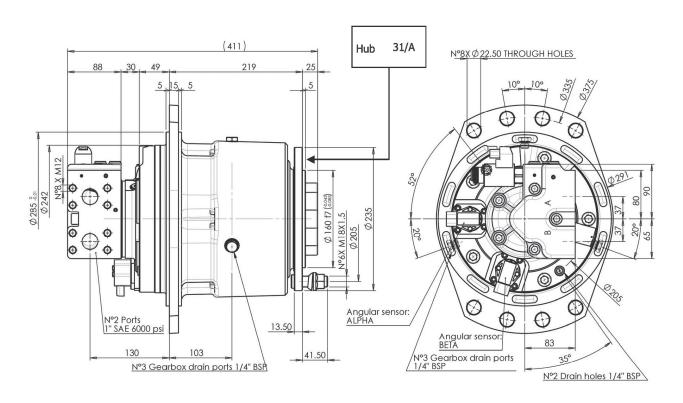


### **BDFK3R - INSTALLATION DRAWINGS**

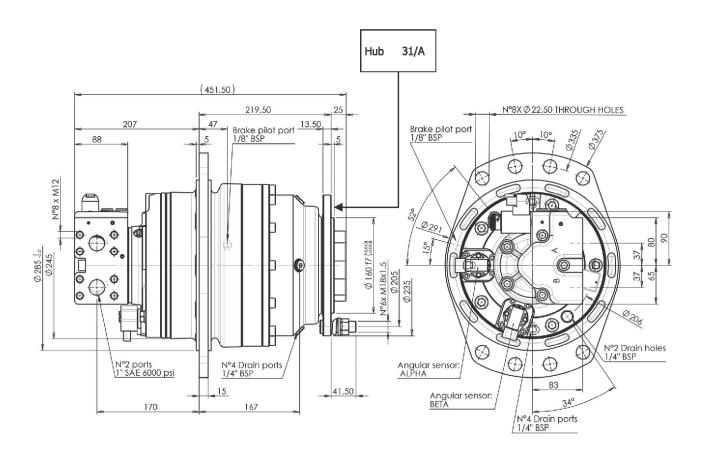




### **BVK3 - INSTALLATION DRAWINGS**



#### **BVFK3R - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX K Series

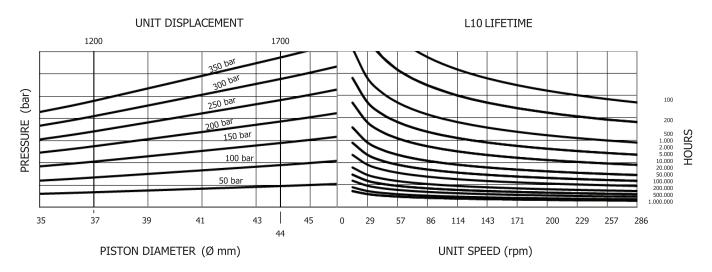
BDK3 - BDFK3R BVK3 - BVFK3R

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 32 mm.

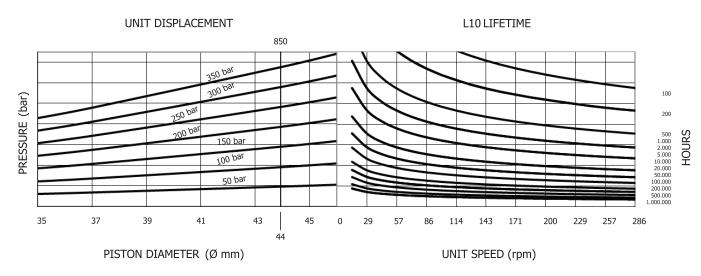
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 16 mm.

Please contact our Technical Department for other graphs relating to this product.





### WHEEL MOTORS WITH GEARBOX K Series

GK3A (fixed displacement without brake)
GFK3AR (fixed displacement with brake)



		500	650	750	850	1000	1150	1200	1450	1550
Equivalent displacement (1)	[cc/rev]	493	643	770	860	1005	1108	1216	1448	1571
Reduction ratio						5:1				
Bore	[mm]	28	32	35	37	40	42	44	48	50
Stroke	[mm]					32				
Specific torque	[Nm/bar]	7,84	10,24	12,25	13,69	16,00	17,64	19,36	23,04	25,00
Continuous pressure	[bar]	250	250	250	250	250	250	250	220	205
Peak pressure (2)	[bar]	425	400	400	375	350	350	350	300	280
Peak power (3)	[kW]					48				
Continuous speed (4)	[rpm]	110	110	110	110	110	110	90	70	70
Maximum speed (4)	[rpm]	200	200	200	180	160	140	140	130	130
Approximative weight	[kg]	75	unit		Type of bra	ke		Negative	disc brake	
Maximum casing pressure	[bar] -	1 5	continuous peak	=	Admissible -	temperatu	res	[°C]	-20 mini +80 max	mum imum
Motor oil capacity	[1]	1,5			Static braki	ng torque	5)	[Nm]	8200	
Gearbox oil capacity	[1]	1,7			Minimum bi	ake pilot p	ressure	[bar]	20	
Brake pilot volume	[cm³]	3,9			Maximum b	rake pilot	pressure	[bar]	50	
Bolt torque setting	[Nm]	767,0 958,0	coarse 799,0	HHE	Suggested	oolt type		M22	12.9	
			NOT	ΓES						
(1) Equivalent displacement = motor	displacement x	reduct	ion ratio of gearb	ox (5 :1)						
(2) For higher peak pressure please c	ontact our Tech.	Dept.								

<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

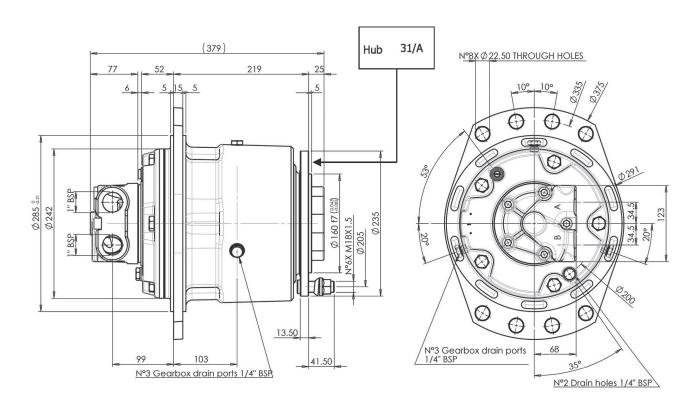
 $<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. \ Dept. \\$ 

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

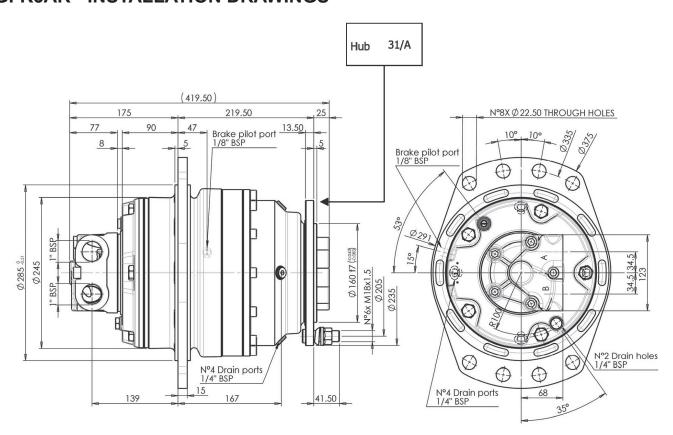
The brake requires to be periodically engaged and disengaged to mantain the desired performance.



### **GK3A - INSTALLATION DRAWINGS**



### **GFK3AR - INSTALLATION DRAWINGS**



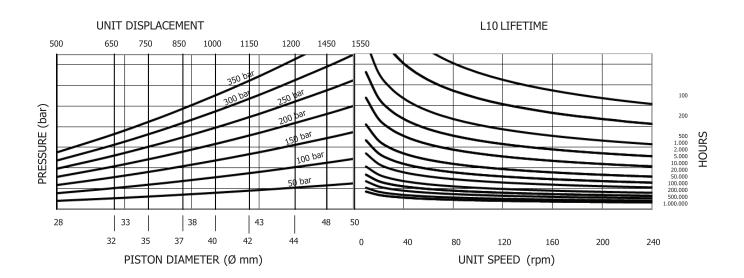


### WHEEL MOTORS WITH GEARBOX K Series

### GK3A GFK3AR

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank



### WHEEL MOTORS WITH GEARBOX K Series

BDK3A (dual displacement without brake) BDFK3AR (dual displacement with brake)

BVK3A (variable displacement without brake) BVFK3AR (variable displacement with brake)

				500	250	850	215	875	400	1250	300	1250	625
Equivalent displacement (1)	[cc/rev]			510	270	874	215	880	380	1216	304	1216	608
Reduction ratio								5:1					
Bore	[mm]			37	37	37	37	44	44	44	44	44	44
Stroke	[mm]			19	10	32	8	23	10	32	8	32	16
Specific torque	[Nm/bar]			8,12	4,28	13,50	3,42	13,90	6,04	19,36	4,84	19,36	9,68
Continuous pressure	[bar]			250	250	250	250	250	250	250	250	250	250
Peak pressure (2)	[bar]			425	425	400	400	400	400	350	350	350	350
Peak power (3)	[kW]			55	42	55	42	55	42	55	42	55	42
Continuous speed (4)	[rpm]			100	300	100	300	100	300	100	300	100	300
Maximum speed (4)	[rpm]			300	300	200	300	200	300	170	300	170	300
Approximative weight	[kg]	75	unit			Туре	of bral	ке			Negative	disc br	ake
Maximum casing pressure	[bar]	1 5	continue peak	ous		Admi	ssible t	empera	atures		[°C]		minimum maximum
Motor oil capacity	[1]	1,5				Statio	brakir	ng torqu	ле <sup>(5)</sup>		[Nm]	8200	
Gearbox oil capacity	[1]	1,7				Minim	num br	ake pilo	ot pres	sure	[bar]	20	
Brake pilot volume	[cm³]	3,9				Maxir	num bi	rake pil	ot pres	ssure	[bar]	60	
Volume pilot change displace <sup>ment</sup>	[cm³]	2,12					pressu	re chan nt	ge		[bar]	25 35	minimum maximum
Bolt torque setting	[Nm]	767,0 958,0	coarse	799,0 1008,0	fine	Sugg	ested b	oolt typ	е		M22	12.9	
				NOTE	S								

Equivalent displacement = motor displacement x reduction ratio of gearbox (5:1)

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

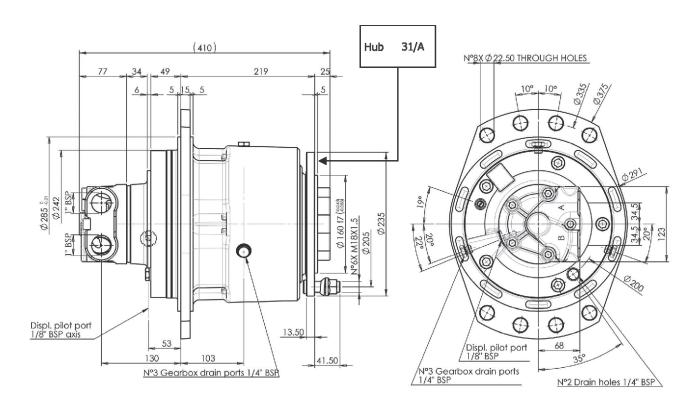
<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

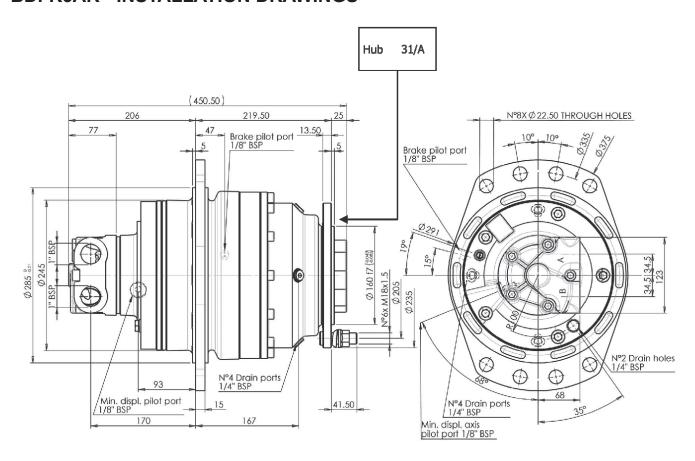
<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably. The brake requires to be periodically engaged and disengaged to mantain the desired performance.



### **BDK3A - INSTALLATION DRAWINGS**

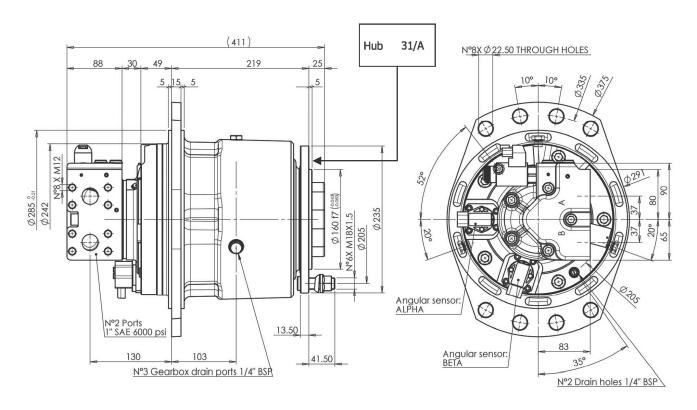


### **BDFK3AR - INSTALLATION DRAWINGS**

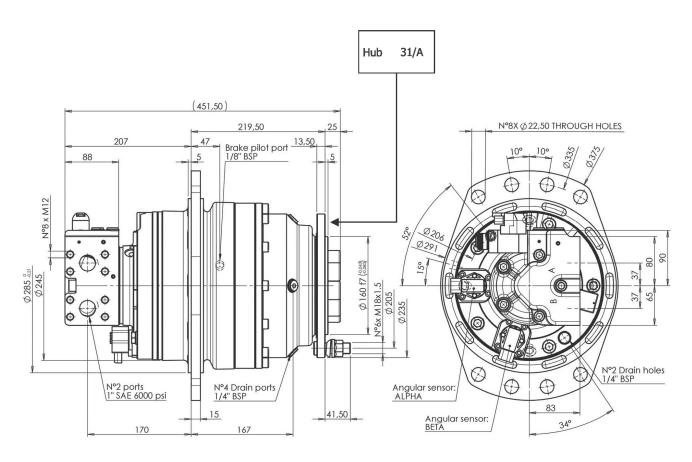




### **BVK3A - INSTALLATION DRAWINGS**



### **BVFK3AR - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX K Series

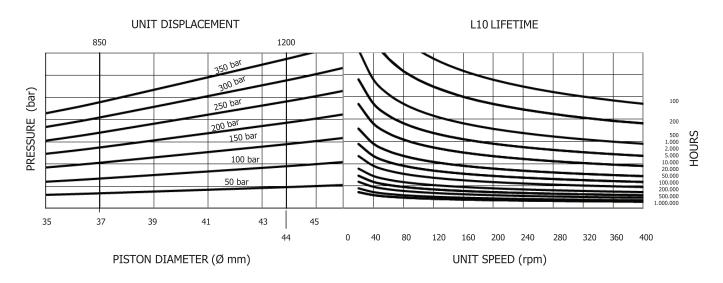
BDK3A - BDFK3AR BVKA3 - BVFK3AR

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 32 mm.

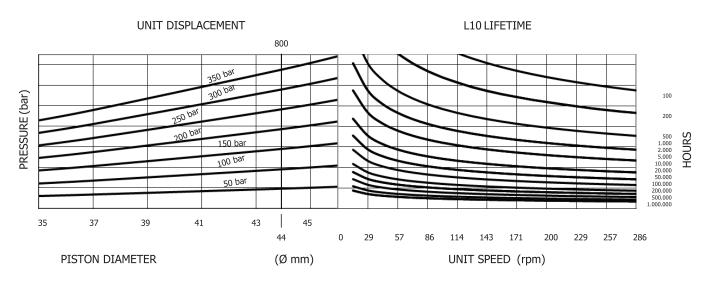
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 16 mm.

Please contact our Technical Department for other graphs relating to this product.





### WHEEL MOTORS WITH GEARBOX K Series

GK4 (fixed displacement without brake)
GFK4 (fixed displacement with brake)



		1120	1400	170	00 1950	2400	2800	3200	3500
Equivalent displacement (1)	[cc/rev]	1078	1407	170	3 1943	2379	2759	3167	3491
Reduction ratio					5,6	:1			
Bore	[mm]	35	40	44	47	52	56	60	63
Stroke	[mm]				40	)			
Specific torque	[Nm/bar]	17,15	22,40	27,1	10 30,93	37,86	43,90	50,40	55,57
Continuous pressure	[bar]	250	250	250	250	250	250	250	250
Peak pressure (5)	[bar]	425	425	400	375	350	350	300	280
Peak power (2)	[kW]				59	)			
Continuous speed (6)	[rpm]	125	125	89	89	80	80	80	71
Maximum speed (6)	[rpm]	185	175	135	5 135	134	125	125	115
Approximative weight	[kg]	166	unit		Gearbox oil capac	ity	[1]	3	,5
Maximum casing pressure	[bar]	<u>1</u> 5	continuous peak		Motor oil capacity	(3)	[1]		2
Admissible temperatures	[°C]	-20 +80	minimum maximum		Static braking torc	lue (4)	[Nm]	18000	
Type of brake		N	legative disc brak	е	Minimum brake pi	lot pressure	[bar]	20	
Brake pilot volume	[cm³]	37,5			Maximum brake p	ilot pressure	[bar]	50	
Bolt torque setting	[Nm]	767,0 958,0	coarse 799,0 1008,0	fine	Suggested bolt ty	ре	M22	12.9	
			NOT	ES					

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (5,6:1)

<sup>(2)</sup> For higher peak power please contact our Tech. Dept.

<sup>(3)</sup> The motor, the brake and the gearbox can either share the lubricating oil or be separated. The standard is with separated oil and has a 0,3 bar safety valve.

<sup>(4)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

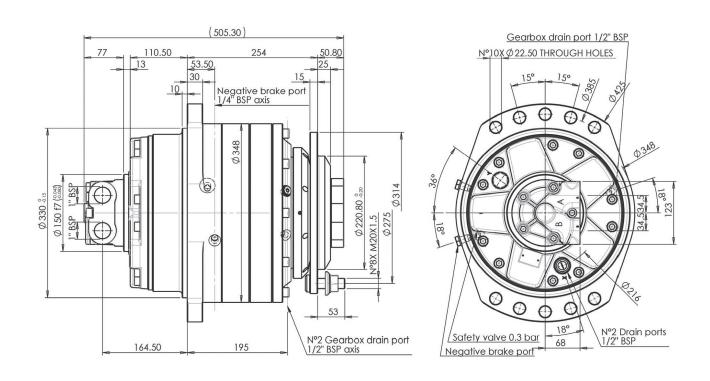
The brake requires to be periodically engaged and disengaged to mantain the desired performance.

 $<sup>\</sup>hbox{(5) For higher peak pressure please contact our Tech. Dept.}\\$ 

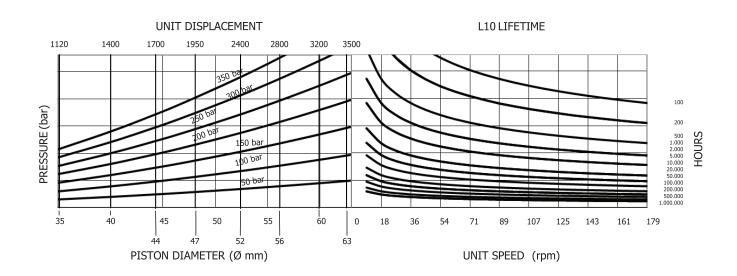
<sup>(6)</sup> For higher continuous and maximum speed please contact our Tech. Dept. Maximum speed can reach up to 250 rpm.



### **GK4 - GFK4 - INSTALLATION DRAWINGS**



### **GK4 - GFK4 - BEARING LIFETIME GRAPHS**





### WHEEL MOTORS WITH GEARBOX K Series

BDK4 (dual displacement without brake) BDFK4 (dual displacement with brake)

BVK4 (variable displacement without brake) BVFK4 (variable displacement with brake)

		1400	350	1400	700	1950	500	1950	1000	2800	700	2800	1400
Equivalent displacement (1)	[cc/rev]	1407	352	1407	705	1943	487	1943	972	2759	688	2759	1377
Reduction ratio							į	5,6:1					
Bore	[mm]	40	40	40	40	47	47	47	47	56	56	56	56
Stroke	[mm]	40	10	40	20	40	10	40	20	40	10	40	20
Specific torque	[Nm/bar]	22,40	5,60	22,40	11,20	30,93	7,73	30,80	15,40	43,90	10,98	43,90	21,95
Continuous pressure	[bar]						2	250					
Peak pressure (2)	[bar]	425	425	425	425	375	375	375	375	350	350	350	350
Peak power (3)	[kW]	75	65	75	65	75	65	75	65	75	65	75	65
Continuous speed (4)	[rpm]	125	260	125	260	125	260	125	260	70	260	70	140
Maximum speed (4)	[rpm]	175	300	175	300	175	300	175	300	140	300	140	285
Approximative weight	[kg] 16	6 unit		•	Gearl	box oil	capacit	у		[1]	3,5	•	
Maximum casing pressure	[bar] 1/5		ous		Moto	r oil cap	acity (	3)		[1]	2		
Admissible temperatures	[°C] $\frac{-20}{+8}$				Statio	brakin	g torqı	ле <sup>(4)</sup>		[Nm]	18000		
Type of brake	Ne	egative disc	brake		Minin	num bra	ake pilo	ot press	sure	[bar]	20		
Brake pilot volume	[cm³] 37	,5			Maxir	mum br	ake pil	ot pres	sure	[bar]	50		
Bolt torque setting	[Nm] 76 <sup>-</sup>	7,0 coarse 8,0	799,0 1008,0		Sugg	ested b	olt typ	e		M22	12.9		
			NOTE	S									
(1) Equivalent displacement = motor	displacement x redu	ction ratio of	gearbox	(5,6:1)									
(2) For higher peak pressure please co	ontact our Tech. Dept												
(3) For higher peak power please con	tact our Tech. Dept.												

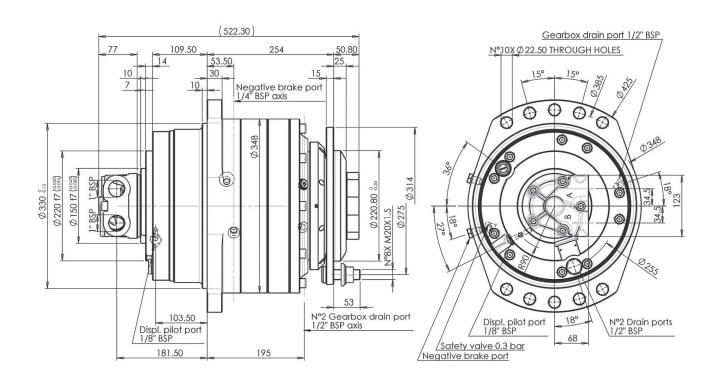
 <sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

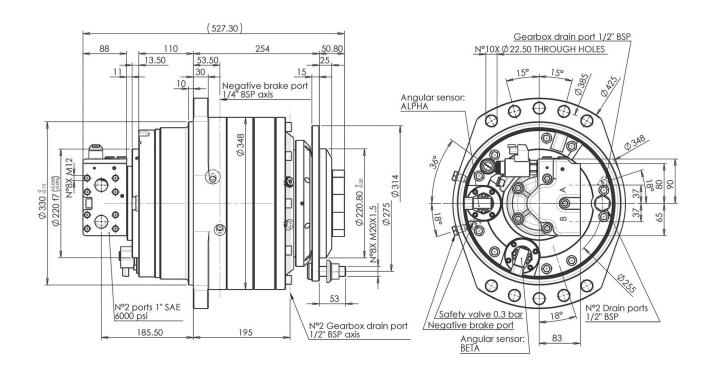
The brake requires to be periodically engaged and disengaged to mantain the desired performance.



#### **BDK4 - BDFK4 - INSTALLATION DRAWINGS**



#### **BVK4 - BVFK4 - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX K Series

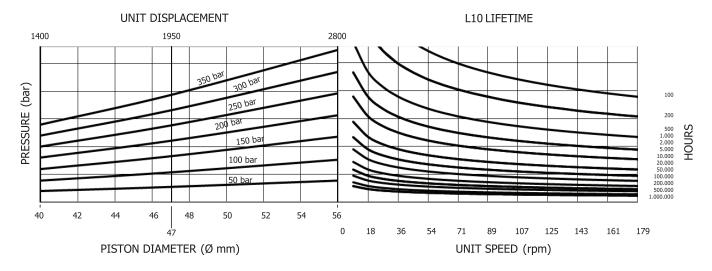
BDK4 - BDFK4 BVK4 - BVFK4

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 40 mm.

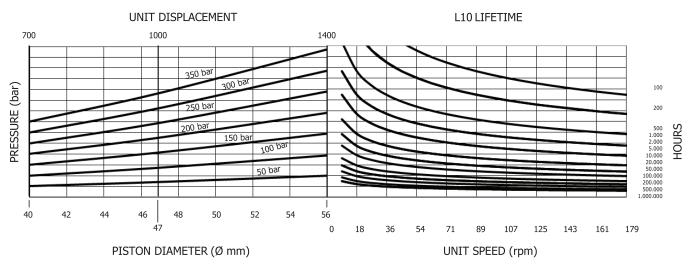
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 20 mm.

Please contact our Technical Department for other graphs relating to this product.





### WHEEL MOTORS WITH GEARBOX K Series

### **ORDER CODE**

1	2	3		4		5	5		6		7		8		9		10
G +		+ K3F	₹ +		+			+		+	D40	+		+		+	
					G		=	Fixed	displace	ment							
1 Motor	type				BD				displace:								
					BV				ole displa		nt						
					No co	nde	_	no br	ako								
2 Brake	option					Jue											
					F		=	brake									
					K3		=				rake optio Compac						
					КЗА		=				rake opti Compac						
3 <b>Gearb</b>	ox series				K3R		=		tion ration		eability to	MS11					
					K3AR	l.	=		tion ration ole inter		eability to	MS11					
					K4		=		angeabl ction rati								
4 Displa	cement				see ta	able											
5 <b>Hub o</b> j	otions				31A 31B 31D		=	hub 3 hub 3 hub 3		ssette"	,						
6 <b>Option</b>	ıs				V I			FKM s	seals h valve								
7 Lubric	ation opt	ions			O U		=	separ	ated lub d lubrica		n						
8 Distrib	utor						outo	rs sec		-							
	on of rot	<b>ation</b> output side	2)		No co	ode	=	clock	wise rota	ition							
		: A, out in po			L		=	anti-c rotati	lockwise on	!							
					No co	ode	=	positi	on 1								
10 <b>D</b> :		auit	Hom		DM2		=	positi	on 2								
10 DISTIB	utor cove	er orientat	LION		DM3		=	positi	on 3								
					DM4			positi									
					DM5		=	positi	on 5								

Example

GFK3 700 31AU D40

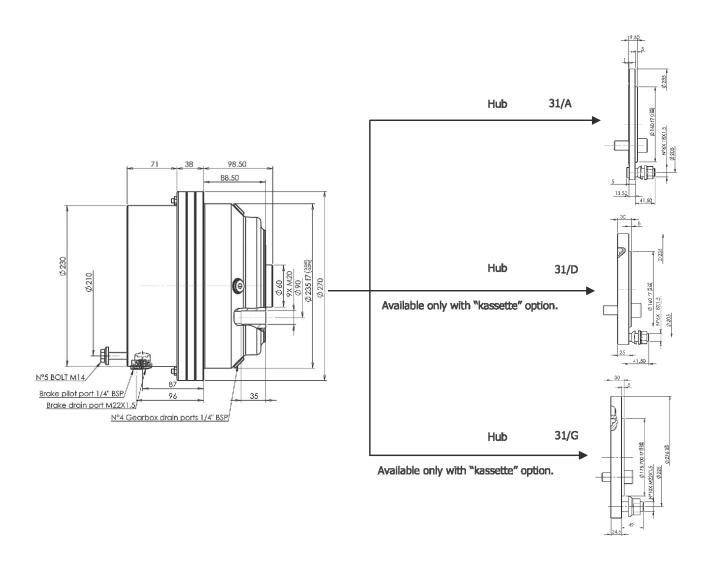
(standard)

GFK3 700 31AVU D40L DM5

(options: FKM seals and anti-clockwise sense of rotation)

# WHEEL MOTORS WITH GEARBOX G3 - G3A Series PRODUCT OVERVIEW

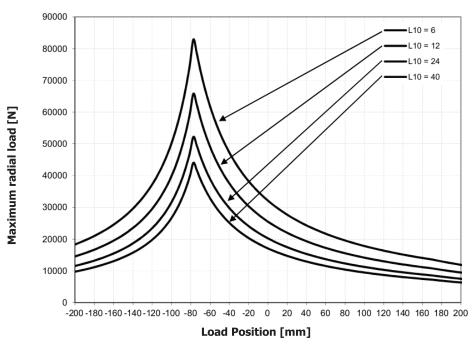
			G3	G3A
Maximum continuous torque	[Nm]		3500	5000
Peak torque	[Nm]		7000	10000
Reduction ratio			7:1	5:1
Maximum braking torque	[Nm]		6500	8750
Brake pilot pressure	[bar]	minimum	18	15
Brake pilot pressure	[Dai]	maximum	60	60
Gearbox weight	[kg]		47	75
			GM05	GM05
Applicable motors			GM1	GM1
r deligenia illacara			BD1	BD1
			BV1	BV1



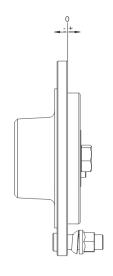


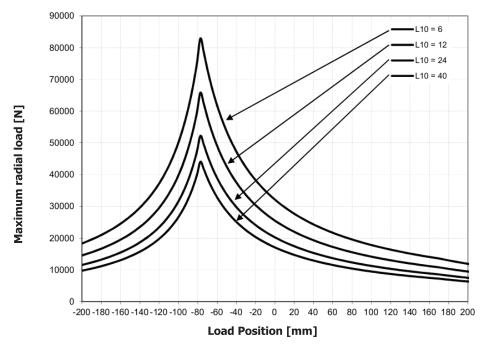
### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

### LOAD POSITION GRAPH

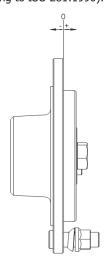


Bearing lifetime has been estimated according to  $L_{10}$  (according to ISO 281:1990).





Bearing lifetime has been estimated according to  $L_{10}$  (according to ISO 281:1990).



### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

GM05 + G3 (fixed displacement without brake)
GM05 + F10L + G3 (fixed displacement with brake)



		275	400	)	520	600	800	900	1050	1150	1350
Equivalent displacement (1)	[cc/rev]	275	412	!	517	602	808	903	1056	1164	1336
Reduction ratio							7:1				
Bore	[mm]	25	25		28	37	35	37	40	42	45
Stroke	[mm]	16	24		24	16	24	24	24	24	24
Specific torque	[Nm/bar]	4,38	6,56	5	8,24	9,58	12,86	14,37	16,82	18,49	21,26
Continuous pressure	[bar]	250	250	)	250	250	250	250	210	190	165
Peak pressure (2)	[bar]	450	450	)	425	375	400	375	325	325	280
Peak power (3)	[kW]	20	20		33	33	33	33	33	33	33
Continuous speed (4)	[rpm]	100	100		100	100	90	90	90	85	85
Maximum speed (4)	[rpm]	140	140	)	140	140	125	125	125	110	110
Approximative weight no brake	[kg]	42	unit			Approximat	ive weight	with brake	[kg]	56 unit	
Maximum casing pressure	[bar]	1 5	continuo peak	ous		Admissible	temperatu	res	[°C]		mum imum
Motor oil capacity	[1]	0,8				Type of bra	ike		Negat	ive disc brak	e
Gearbox oil capacity	[1]	1,7				Static braki	ng torque	(5)	[Nm]	6500	
Brake oil capacity	[1]	0,45				Minimum b	rake pilot p	oressure	[bar]	35	
Brake pilot volume	[cm³]	65,1				Maximum b	orake pilot	pressure	[bar]	60	
Bolt torque setting	[Nm]	68,0 84,0	coarse	71,0 89,0	fine	Suggested	bolt type		M10	12.9	
				NOTI	ES						
(1) Equivalent displacement = motor d	splacement x	reducti	ion ratio of	gearbo	x (7 :1)						
(2) For higher peak pressure please con	tact our Tech.	Dept.									
(3) For higher peak power please conta	ct our Tech. D	ept.									
(0.5.1:1				_							

 <sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

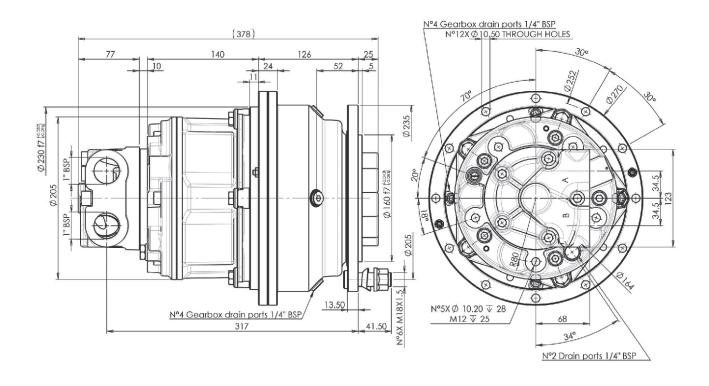
<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

The brake requires to be periodically engaged and disengaged to mantain the desired performance.

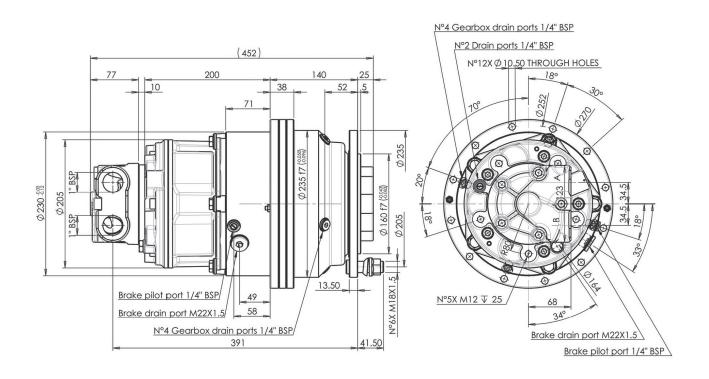


### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

### **GM05 + G3 - INSTALLATION DRAWINGS**



### **GM05 + F10L + G3 - INSTALLATION DRAWINGS**



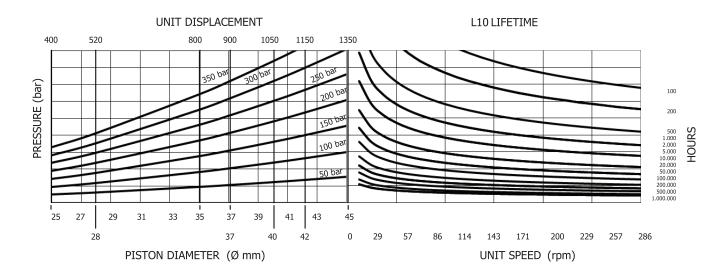


### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

GM05 + G3 GM05 + F10L + G3

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank

### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

GM1 + G3 (fixed displacement without brake)
GM1 + F10L + G3 (fixed displacement with brake)



		700	90	0	1000	1200	1400	1600	1700	200	0 2200
Equivalent displacement (1)	[cc/rev]	690	901	L	1078	1204	1407	1552	1703	202	7 2199
Reduction ratio							7:1				
Bore	[mm]	28	32		35	37	40	42	44	48	50
Stroke	[mm]						32				
Specific torque	[Nm/bar]	10,98	14,3	4	17,15	19,17	22,40	24,70	27,10	32,2	26 35,00
Continuous pressure	[bar]	250	245	5	200	180	155	140	130	10!	5 100
Peak pressure (2)	[bar]	425	400	)	400	365	310	280	255	21!	5 200
Peak power (3)	[kW]						48				
Continuous speed (4)	[rpm]	78	78		78	78	78	78	64	50	50
Maximum speed (4)	[rpm]	150	150	)	150	130	103	100	100	100	90
Approximative weight no brake	[kg]	70	unit			Approxima	tive weight	with brake	[kg]	95 ι	ınit
Maximum casing pressure	[bar]	1 5	continuo peak	ous		Admissible	temperatu	res	[°C]		minimum maximum
Motor oil capacity	[1]	1				Type of bra	ake		Negati	ve disc bra	ake
Gearbox oil capacity	[1]	1,7				Static brak	ing torque	(5)	[Nm]	6500	
Brake oil capacity	[1]	0,4	5			Minimum b	rake pilot <sub>l</sub>	oressure	[bar]	20	
Brake pilot volume	[cm³]	65,1	L			Maximum	orake pilot	pressure	[bar]	60	
Bolt torque setting	[Nm]	68,0 84,0	coarse	71,0 89,0	fine	Suggested	bolt type		M10	12.9	
				NOTE	ES						
(1) Equivalent displacement = motor d	isplacement x	reducti	on ratio of	gearbo	x (7 :1)						
(2) For higher peak pressure please con	tact our Tech.	Dept.									

<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

 <sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

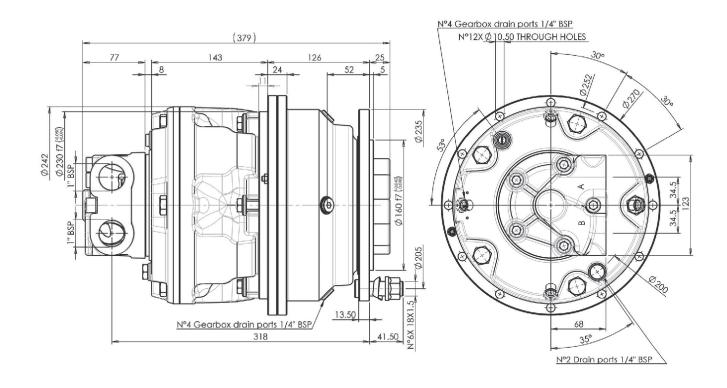
<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

The brake requires to be periodically engaged and disengaged to mantain the desired performance.

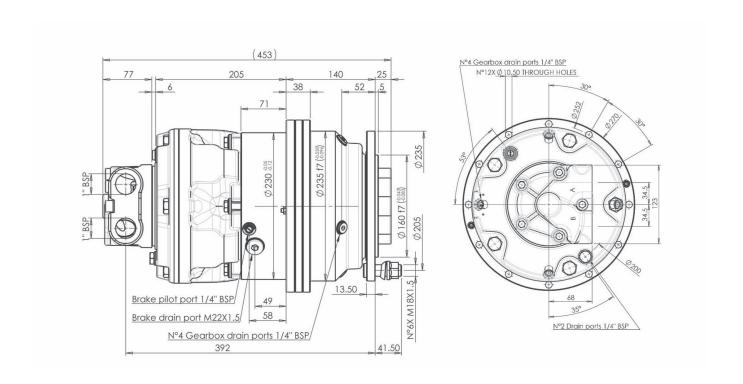


### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

### **GM1 + G3 - INSTALLATION DRAWINGS**



### **GM1 + F10L + G3 - INSTALLATION DRAWINGS**



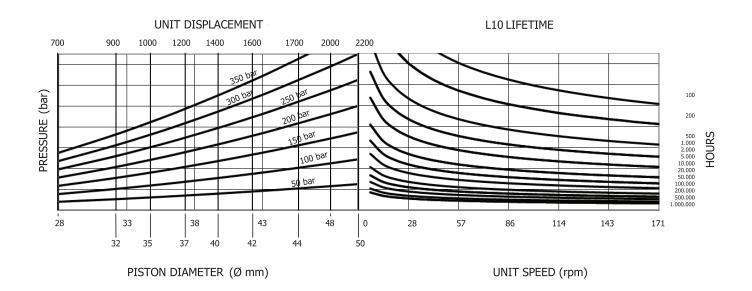


### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

GM1 + G3 GM1 + F10L + G3

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank

### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

BD1 + G3 (dual displacement without brake)

BD1 + F10L + G3 (dual displacement with brake)

**BV1 + G3** (variable displacement without brake)

BV1 + F10L + G3 (variable displacement with brake)



			700	375	1200	300	1200	550	1700	425	1700	850
Equivalent displacement (1)	[cc/rev]		714	378	1204	301	1232	532	1701	427	1701	851
Reduction ratio							7:1					
Bore	[mm]		37	37	37	37	44	44	44	44	44	44
Stroke	[mm]		19	10	32	8	23	10	32	8	32	16
Specific torque	[Nm/bar]		11,40	6,30	19,20	4,80	19,55	8,45	27,07	6,79	27,30	13,51
Continuous pressure	[bar]		300	300	185	300	180	300	125	300	125	250
Peak pressure (2)	[bar]		425	425	370	400	355	400	250	375	250	375
Peak power (3)	[kW]		50	42	50	42	50	42	50	42	50	42
Continuous speed (4)	[rpm]		70	200	70	200	70	200	70	200	70	200
Maximum speed (4)	[rpm]		200	200	140	200	140	200	120	200	120	200
Approximative weight no brake	[kg]	70 unit	•		Appro	ximati	ve weig	ht with	brake	[kg]	95	unit
Maximum casing pressure	[bar]	1 con	tinuous k	Admissible temperatures				[°C]	-20 +80	minimum maximum		
Motor oil capacity	[1]	1,5			Type of brake					Negative disc brake		
Gearbox oil capacity	[1]	1,7			Static	brakir	ıg torqu	ie (5)		[Nm]	6500	
Brake oil capacity	[1]	0,45			Minim	um br	ake pilo	t press	sure	[bar]	20	
Brake pilot volume	[cm³]	65,1			Maxin	num bi	ake pile	ot pres	sure	[bar]	60	
Bolt torque setting	[Nm]	<sup>68,0</sup> coa	rse 71,0 89,0	111111	Sugge	ested b	olt type	9		M10	12.9	
NOTES												

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (7:1)

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

<sup>(3)</sup> For higher peak power please contact our Tech. Dept.

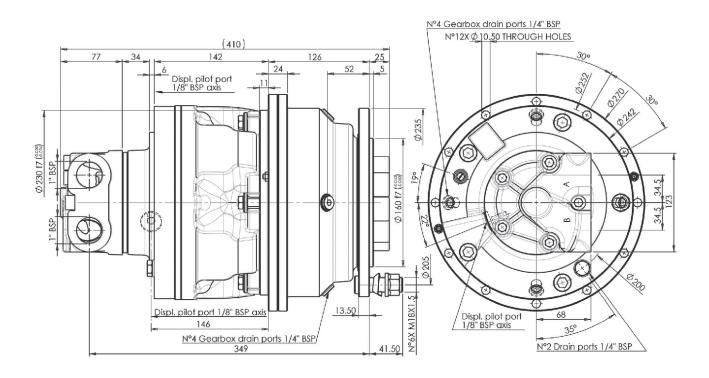
<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably. The brake requires to be periodically engaged and disengaged to mantain the desired performance.

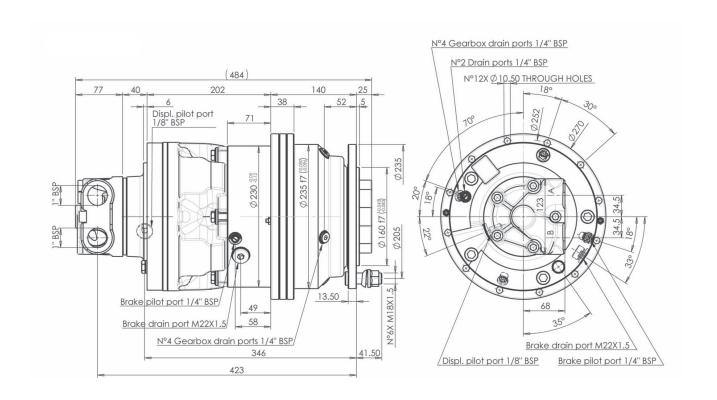


#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

#### **BD1 + G3 - INSTALLATION DRAWINGS**



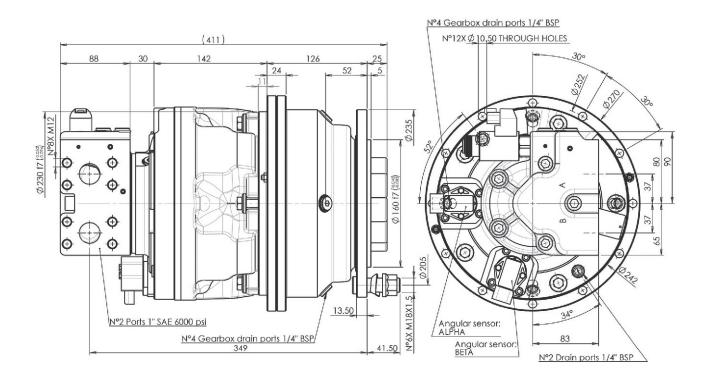
#### **BD1 + F10L + G3 - INSTALLATION DRAWINGS**



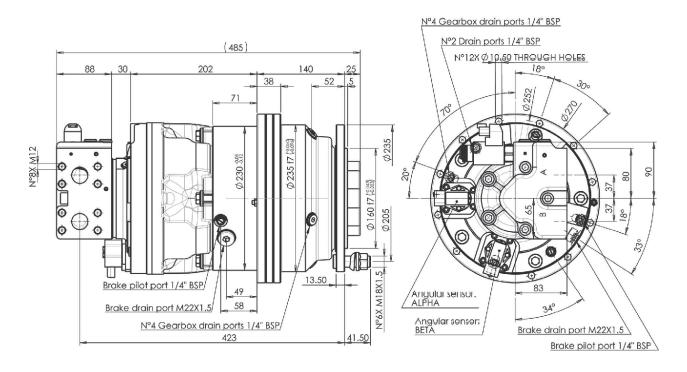


#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

#### **BV1 + G3 - INSTALLATION DRAWINGS**



#### **BV1 + F10L + G3 - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

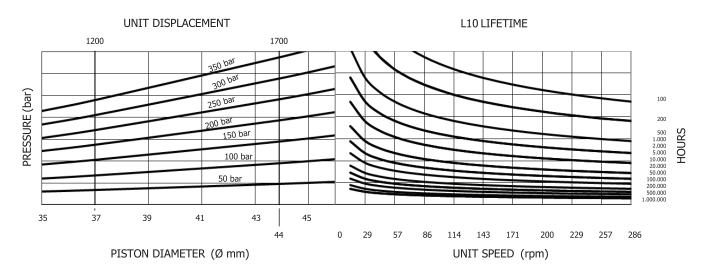
BD1 + G3 - BD1 + F10L + G3 BV1 + G3 - BV1 + F10L + G3

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 32 mm.

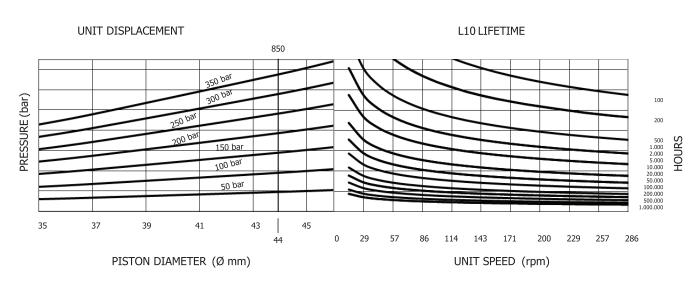
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 16 mm.

Please contact our Technical Department for other graphs relating to this product.





#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

**GM05 + G3A** (fixed displacement without brake) GM05 + F10L + G3A (fixed displacement with brake)

### **TECHNICAL SPECIFICATION**



		200	300	400	450	600	650	750	800	950
Equivalent displacement (1)	[cc/rev]	195	295	370	430	575	645	755	805	955
Reduction ratio						5:1				
Bore	[mm]	25	25	28	37	35	37	40	42	45
Stroke	[mm]	16	24	24	16	24	24	24	24	24
Specific torque	[Nm/bar]	3,10	4,70	5,90	6,85	9,19	10,27	12,00	13,2	3 15,20
Continuous pressure	[bar]	250	250	250	250	250	250	250	250	250
Peak pressure (2)	[bar]	450	450	425	400	375	375	325	325	280
Peak power (3)	[kW]	20	20	33	33	33	33 33		33	33
Continuous speed (4)	[rpm]	140	140	140	140	130	130	130	120	120
Maximum speed (4)	[rpm]	200	200	200	200	180	180	180	160	160
Approximative weight no brake	[kg]	44	unit		Approxima	itive weight	with brake	[kg]	55 u	nit
Maximum casing pressure	[bar] -	1 5	continuo peak	ous	Admissible	temperatu	res	[°C]		ninimum naximum
Motor oil capacity	[1]	0,8			Type of br	ake		Negative	disc brake	
Gearbox oil capacity	[1]	1,7			Static brak	ting torque	(5)	[Nm]	8750	
Brake oil capacity	[1]	0,45			Minimum I	orake pilot p	ressure	[bar]	20	
Brake pilot volume	[cm³]	65,1			Maximum	brake pilot	pressure	[bar]	60	
Bolt torque setting	[Nm]	68,0 84,0	coarse	71,0 89,0 fine	Suggested	bolt type		M10	12.9	
				NOTES						

(1) Equivalent displacement = motor displacement x reduction ratio of gearbox (5:1)

(2) For higher peak pressure please contact our Tech. Dept.

(3) For higher peak power please contact our Tech. Dept.

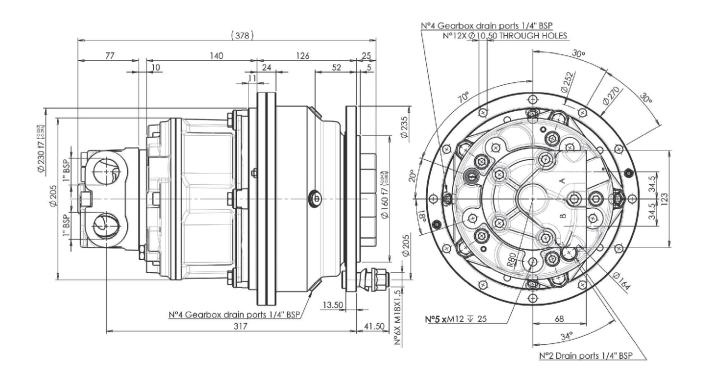
 $(4) For higher continuous and maximum speed please contact our Tech. \ Dept. \\$ 

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably. The brake requires to be periodically engaged and disengaged to mantain the desired performance.

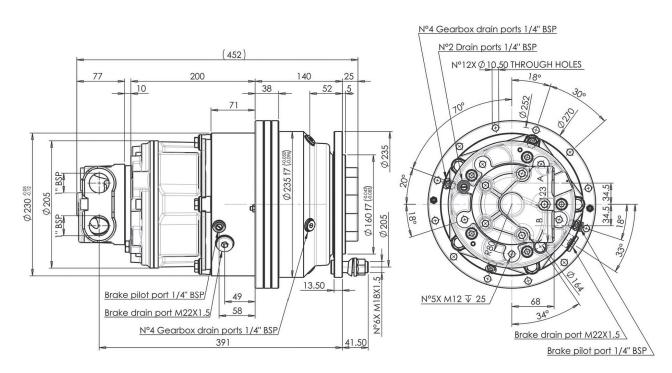


#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

#### **GM05 + G3A - INSTALLATION DRAWINGS**



#### **GM05 + F10L + G3A - INSTALLATION DRAWINGS**





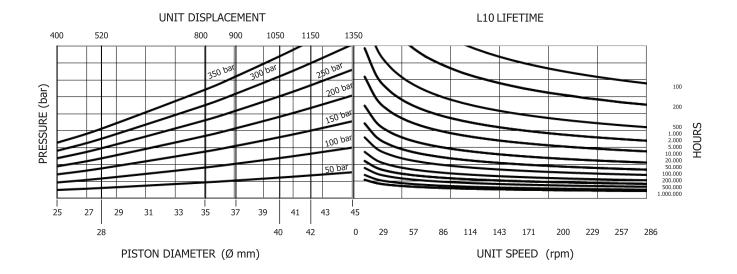
#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

GM05 + G3A GM05 + F10L + G3A

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank

#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

GM1 + G3A (fixed displacement without brake)
GM1 + F10L + G3A (fixed displacement with brake)

#### **TECHNICAL SPECIFICATION**



		500	650	750	850	1000	1150	1200	1450	1550
Equivalent displacement (1)	[cc/rev]	493	643	3 770	860	1005	1108	1216	1448	1571
Reduction ratio						5:1				
Bore	[mm]	28	32	35	37	40	42	44	48	50
Stroke	[mm]					32				
Specific torque	[Nm/bar]	7,84	10,2	6 12,25	13,69	16,00	17,64	19,36	23,04	25,00
Continuous pressure	[bar]	250	250	250	250	250	250	250	220	205
Peak pressure (2)	[bar]	425	400	400	375	350	350	350	300	280
Peak power (3)	[kW]					48				
Continuous speed (4)	[rpm]	110	110	110	110	110	110	90	70	70
Maximum speed (4)	[rpm]	200	200	200	180	160	140	140	130	120
Approximative weight no brake	[kg]	47	unit		Approximative weight with brake [kg] 59				59 unit	
Maximum casing pressure	[bar]	1 5	continuo peak	ous	Admissible	temperatu	res	[°C]		mum imum
Motor oil capacity	[1]	1			Type of br	ake		Negative	disc brake	
Gearbox oil capacity	[1]	1,7			Static brak	ing torque	(5)	[Nm]	8750	
Brake oil capacity	[۱]	0,45			Minimum b	orake pilot p	ressure	[bar]	35	
Brake pilot volume	[cm³]	65,1			Maximum	brake pilot	pressure	[bar]	60	
Bolt torque setting	[Nm]	68,0 84,0	coarse	71,0 89,0 fine	Suggested	bolt type		M10	12.9	
		· ·		NOTES						
(1) Equivalent displacement = motor di	splacement x	reducti	on ratio of	gearbox (5 :1)						
(2) For higher peak pressure please con-	tact our Tech.	Dept.								
(3) For higher peak power please containing	ct our Tech. De	ept.								
(4) For high or continuous and magainst the		4 .	-4 Tl-	Doub						

 $<sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. \ Dept. \\$ 

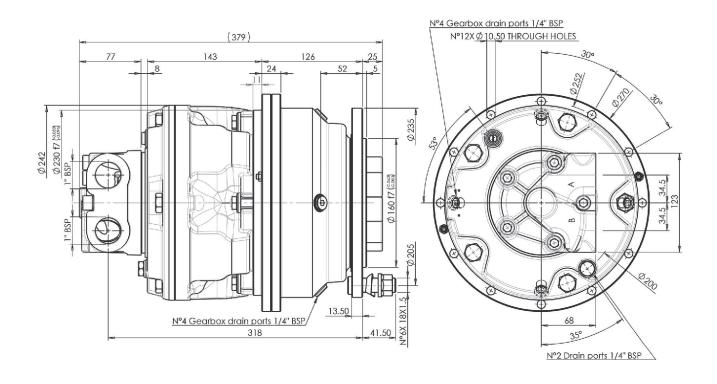
<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

The brake requires to be periodically engaged and disengaged to mantain the desired performance.

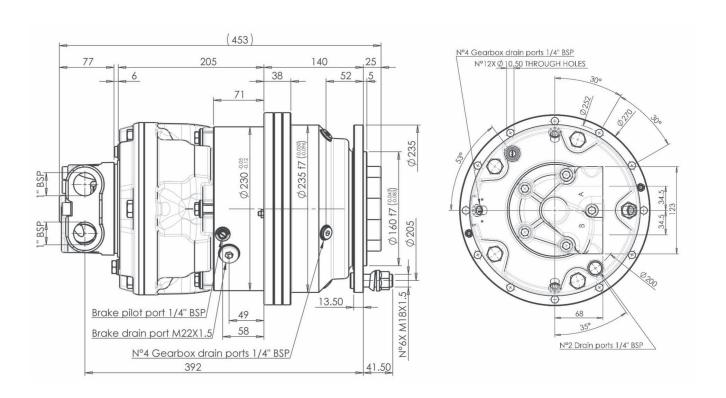


#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

#### **GM1 + G3A - INSTALLATION DRAWINGS**



#### **GM1 + F10L + G3A - INSTALLATION DRAWINGS**



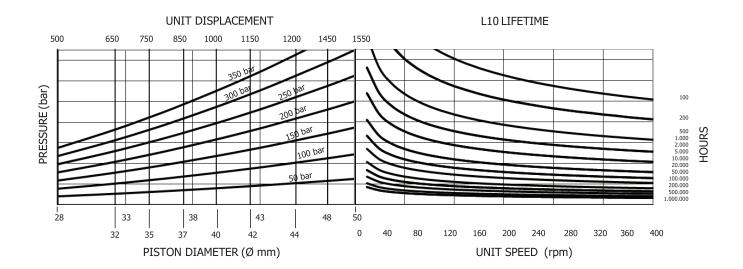


#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

GM1 + G3A GM1 + F10L + G3A

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank



#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

BD1 + G3A (dual displacement without brake)

BD1 + F10L + G3A (dual displacement with brake)

**BV1 + G3A** (variable displacement without brake)

BV1 + F10L + G3A (variable displacement with brake)



#### **TECHNICAL SPECIFICATION**

				500	250	850	215	875	400	1250	300	1250	625
Equivalent displacement (1)	[cc/rev]			510	270	860	215	880	380	1215	305	1215	608
Reduction ratio								5:1					
Bore	[mm]			37	37	37	37	44	44	44	44	44	44
Stroke	[mm]			19	10	32	8	23	10	32	8	32	16
Specific torque	[Nm/bar]			8,11	4,30	13,69	3,42	14,00	6,04	19,34	4,85	19,40	9,65
Continuous pressure	[bar]			250	250	250	250	250	250	250	250	250	250
Peak pressure (2)	[bar]			425	425	400	400	300	400	375	375	375	375
Peak power (3)	[kW]			55	42	55	42	55	42	55	42	55	42
Continuous speed (4)	[rpm]			100	300	100	300	100	300	100	300	100	300
Maximum speed (4)	[rpm]			300	300	200	300	200	300	170	300	170	300
Approximative weight no brake	[kg]	55	unit			Appro	oximati	ve weig	ght wit	h brake	[kg]	67	unit
Maximum casing pressure	[bar]	1 5	continu peak	ious		Admi	ssible t	empera	atures		[°C]		minimum maximum
Motor oil capacity	[1]	1,5				Туре	of bra	ke			Negative	e disc bra	ake
Gearbox oil capacity	[1]	1,7				Statio	brakir	ng torqu	ıe (⁵)		[Nm]	8750	
Brake oil capacity	[1]	0,45				Minin	num br	ake pilo	ot pres	sure	[bar]	20	
Brake pilot volume	[cm³]	65,1				Maxir	num b	rake pil	ot pres	ssure	[bar]	60	
Bolt torque setting	[Nm]	71,0 89,0 fine Suggested bolt type					M10	12.9					
				NOTE	S							·	

NOTES

 $<sup>(1) \</sup> Equivalent \ displacement = motor \ displacement \ x \ reduction \ ratio \ of \ gearbox \ (5:1)$ 

<sup>(2)</sup> For higher peak pressure please contact our Tech. Dept.

 $<sup>\</sup>hbox{(3) For higher peak power please contact our Tech. Dept.}\\$ 

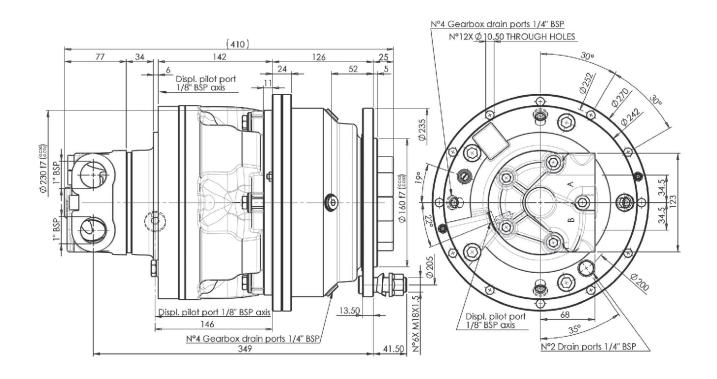
 <sup>(4)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(5)</sup> If the brake is engaged for a long time, the braking torque could increase considerably. The brake requires to be periodically engaged and disengaged to mantain the desired performance.

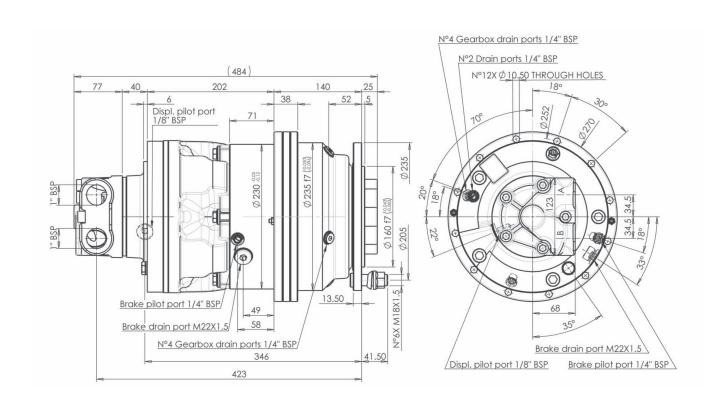


#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

#### **BD1 + G3A - INSTALLATION DRAWINGS**



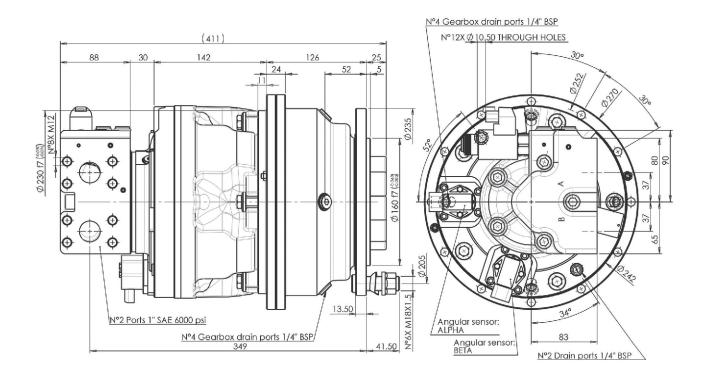
#### **BD1 + F10L + G3A - INSTALLATION DRAWINGS**



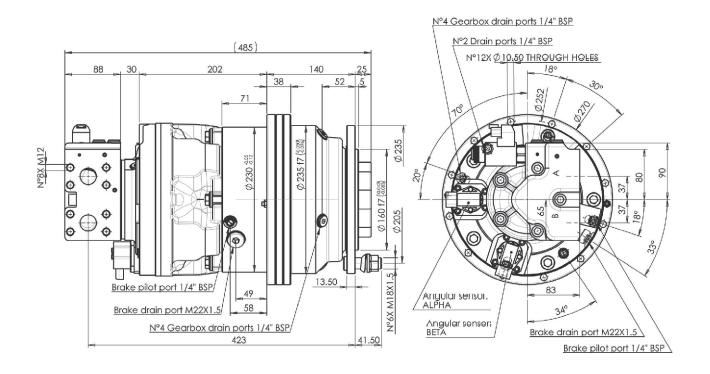


#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

#### **BV1 + G3A - INSTALLATION DRAWINGS**



#### **BV1 + F10L + G3A - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

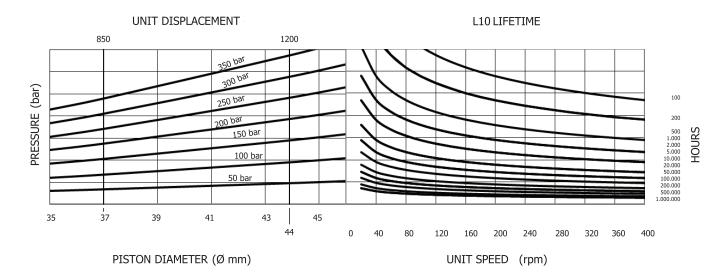
BD1 + G3A - BD1 + F10L + G3A BV1 + G3A - BV1 + F10L + G3A

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 32 mm.

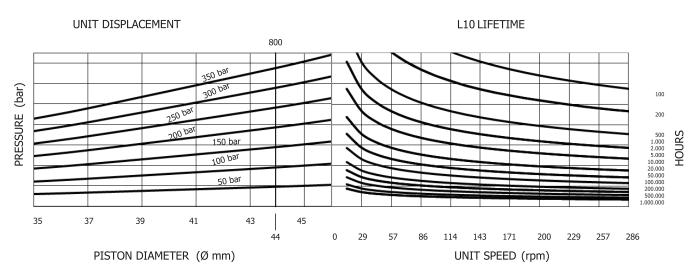
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 16 mm.

Please contact our Technical Department for other graphs relating to this product.



#### WHEEL MOTORS WITH GEARBOX G3 - G3A Series

#### **ORDER CODE**



1 Motor type	
2 Displacement	see table
<sub>3</sub> Additional	U = shared oil
options	O = separated oil
	see distributors section
4 Distributor	D40 standard
Direction of rotation	No code = clockwise rotation
5 (viewed from the output side) with flow in port A, out in port B.	L = anti-clockwise rotation
	No code = position 1
	DM2 = position 2
6 Distributor cover orientation	
	DM5 = position 5
7 <b>G</b> series	G3 = reduction ratio 7:1
7 <b>G</b> series	G3A = reduction ratio 5:1
	No code = no hub
8 Hub option	31/A = standard
o Hub option	31/D
	31/G

Example

GM05 600 U D40 G3

(standard)

GM05 600 U D40L G3A

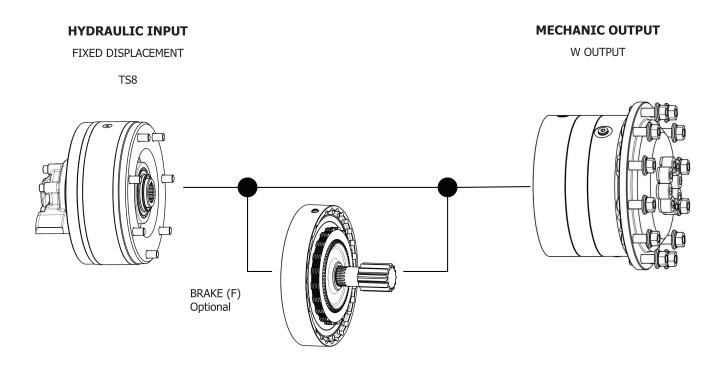
(options: anti-clockwise sense of rotation)



This page has been deliberately left blank

#### WHEEL MOTORS WITH GEARBOX TS Series





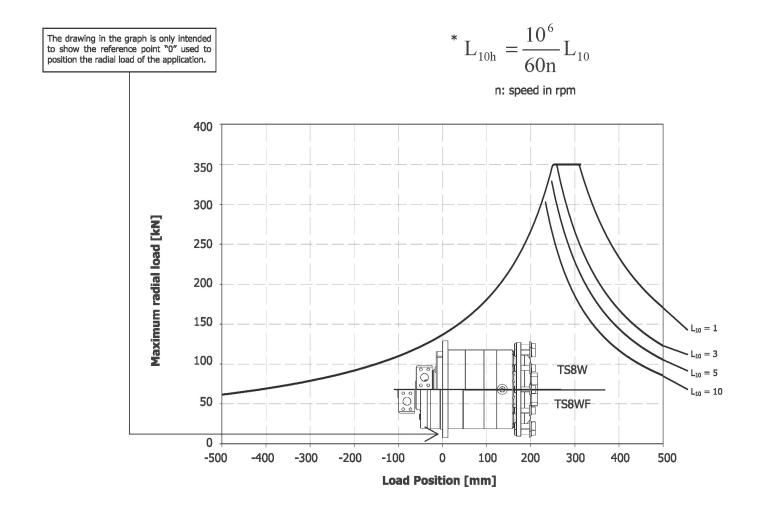
#### WHEEL MOTORS WITH GEARBOX TS Series

Bearings lifetime calculation:

Permissible loads are calculated for different steps of lifetime L<sub>10</sub> according to ISO 281:1990.

 $L_{10}$ : lifetime of the bearing system in millions of revolutions.  $L_{10}$  value can be converted in hours  $L_{10h}$  using the formula\*. Permissible radial load in dynamic conditions and at maximum torque of 43000 Nm.

Notes: Diagrams are influenced by the shaft permissible radial loads.





#### WHEEL MOTORS WITH GEARBOX TS Series

TS8W (fixed displacement without brake)
TS8WF (fixed displacement with brake)

#### **TECHNICAL SPECIFICATION**

		2700	3600	5000	6000	6700	7400
Equivalent displacement (1)	[cc/rev]	2667	3576	4995	5793	6650	7332
Reduction ratio				6:1			
Bore	[mm]	38	44	52	56	60	63
Stroke	[mm]	56	56	56	56	56	56
Specific torque	[Nm/bar]	42,45	56,92	79,50	92,20	105,84	116,69
Continuous pressure	[bar]	400	400	400	380	330	300
Peak pressure	[bar]	450	450	450	450	400	370
Peak power	[kW]	220	220	220	220	220	220
Minimum speed	[rpm]	1	1	1	1	1	1
Continuous speed	[rpm]	185	138	100	90	80	80
Maximum speed	[rpm]	200	200	150	115	105	105
Approximative weight	[kg]	380 unit		Approximative	weight with brake	[kg]	410 unit
Maximum brake pilot pressure	[bar]	50 50	0	Static braking t	orque (4)	[Nm]	40.000
Minimum brake pilot pressure	[bar]	25 2	5	Brake pilot vol	ume	[cm³]	60
Maximum casing pressure (hub version)	[bar]	1 continu	ious	Admissible tem	peratures	°C -	-20 minimum +80 maximum
Bolt torque setting	[Nm]	767,0 958,0 coarse	<sup>799,0</sup> fine	Suggested bolt	type	M22	12.9
Unit oil capacity (3)	[1]	5,5		Available distril	outors	D907	
Constant of lifetime (5)	nxh T[Nm]	10.000 35.000	25.000 30.000	50.000 27.000		00.000 21.500	
			NOTES				

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (6:1)

 $<sup>\</sup>ensuremath{\text{(2)}}\ For\ higher\ continuous\ and\ maximum\ speed\ please\ contact\ our\ Tech.\ Dept.$ 

<sup>(3)</sup> The motor, the brake and the gearbox share the lubricating oil.

<sup>(4)</sup> If the brake is engaged for a long time, the braking torque could increase considerably.

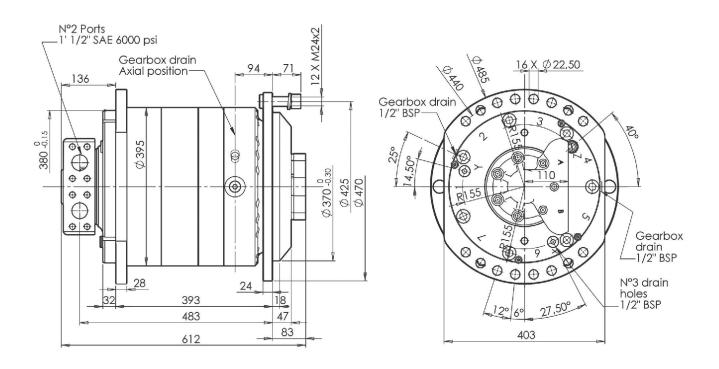
The brake requires to be periodically engaged and disengaged to mantain the desired performance.

<sup>(5)</sup> Where n = gearbox output speed (rpm) and h = working time (hours)

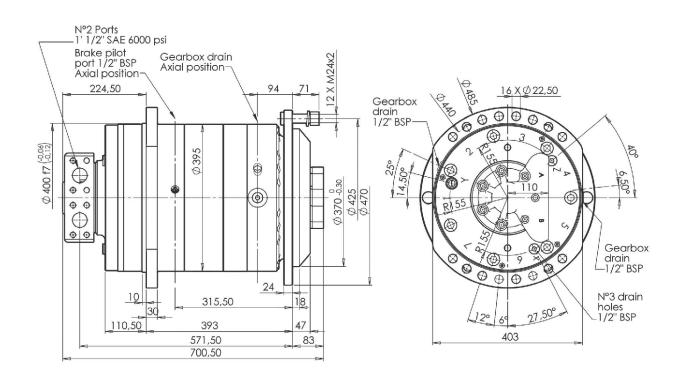


#### WHEEL MOTORS WITH GEARBOX TS Series

#### **TS8W - INSTALLATION DRAWINGS**



#### **TS8WF - INSTALLATION DRAWINGS**



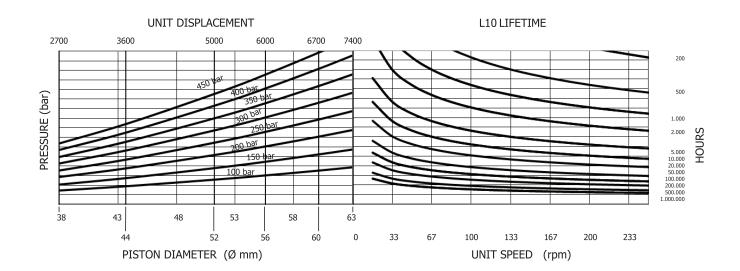


#### WHEEL MOTORS WITH GEARBOX TS Series

#### TS8W TS8WF

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990). Please contact our Technical Department for other graphs relating to this product.





This page has been deliberately left blank



#### WHEEL MOTORS WITH GEARBOX TS Series

TS8DW (dual displacement without brake)
TS8VW (variable displacement without brake)
TS8DWF (dual displacement with brake)
TS8VWF (variable displacement with brake)



#### **TECHNICAL SPECIFICATION**

			2700	700	3600	900	5000	1250	6000	1450	6700	1700	7400	1850
Equivalent displacement (1)	[cc/rev]		2667	666	3576	894	4995	1248	5793	1446	6650	1662	7332	1830
Reduction ratio					I		6	5:1						
Bore	[mm]		38	1	44		52		56		60		6	3
Stroke	[mm]		56	14	56	14	56	14	56	14	56	14	56	14
Specific torque	[Nm/bar]		42,45	10,57	56,92	14,19	79,50	19,81	92,20	22,95	105,84	26,38	116,69	29,05
Continuous pressure	[bar]		40	0	40	00	40	00	380	400	330	350	300	350
Peak pressure	[bar]		45	0	45	50	4:	50	4	50	40	00	370	400
Peak power	[kW]		220	200	220	200	220	200	220	200	220	200	220	200
Minimum speed (2)	[rpm]		1		1	l	:	1		1		1	:	1
Continuous speed (2)	[rpm]		185	200	138	200	100	200	90	200	80	200	80	200
Maximum speed (2)	[rpm]		200	250	200	250	150	250	115	250	105	250	105	250
Approximative weight	[kg]	380	) unit				Appro	ximativ	ve weigl	nt with I	brake	[kg]	410 ur	nit
Unit oil capacity (3)	[1]	5,5	j					num ca version	sing pre	essure	[	Dui	_	inuous eak
Static braking torque (4)	[Nm]	40	.000				Brake	pilot v	olume		[	[cm³]	60	
Maximum brake pilot pressure	[bar]	50					Minim	num bra	ıke pilot	pressui	re	[bar]	25	
Admissible temperatures	°C	-20 +80	minimu maximur				Availa	ıble dist	tributors	5		D9	07D D9	907V
Bolt torque setting	[Nm]	767,0 958,0	COARCA	799,0 1008,0			Sugge	ested bo	olt type		N	122 1	12.9	
Constant of lifetime (5)	nxh T[Nm]		0.000 5.000	25.0 30.0			.000		.000 000	500. 21.				
				NOT	FS									

NOTES

<sup>(1)</sup> Equivalent displacement = motor displacement x reduction ratio of gearbox (6:1)

<sup>(2)</sup> For higher continuous and maximum speed please contact our Tech. Dept.

<sup>(3)</sup> The motor, the brake and the gearbox share the lubricating oil.

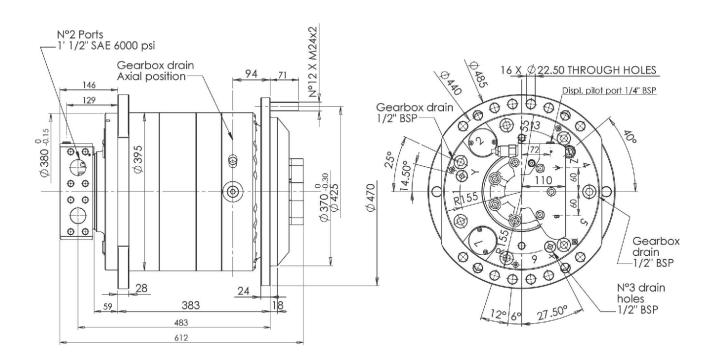
<sup>(4)</sup> If the brake is engaged for a long time, the braking torque could increase considerably. The brake requires to be periodically engaged and disengaged to mantain the desired performance.

<sup>(5)</sup> Where n= gearbox output speed (rpm) and h= working time (hours)

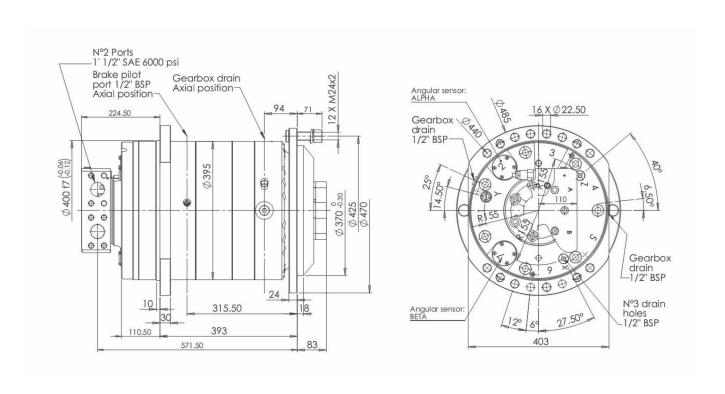


#### WHEEL MOTORS WITH GEARBOX TS Series

#### **TS8DW - INSTALLATION DRAWINGS**



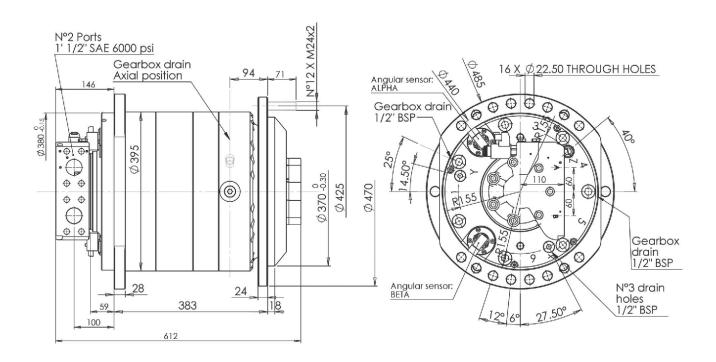
#### **TS8DWF - INSTALLATION DRAWINGS**



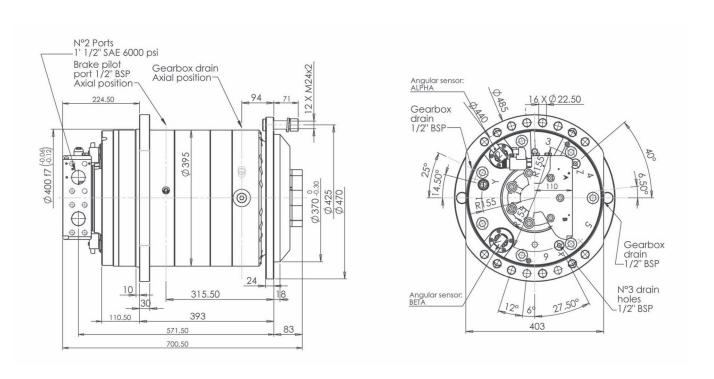


#### WHEEL MOTORS WITH GEARBOX TS Series

#### **TS8VW - INSTALLATION DRAWINGS**



#### **TS8VWF - INSTALLATION DRAWINGS**



#### WHEEL MOTORS WITH GEARBOX TS Series

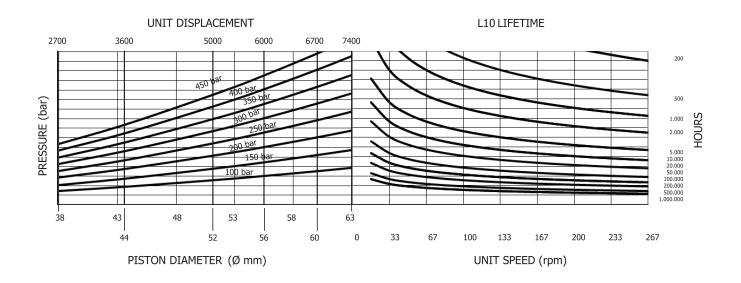
TS8DW - TS8DWF TS8VW - TS8VWF

#### **BEARING LIFETIME GRAPHS**

Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 56 mm.

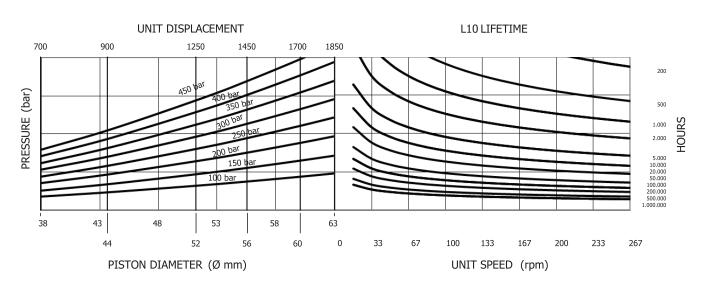
Please contact our Technical Department for other graphs relating to this product.



Bearing lifetime has been estimated according to L10 (according to ISO 281:1990).

The following graph has been plotted using the stroke of 14 mm.

Please contact our Technical Department for other graphs relating to this product.





#### WHEEL MOTORS WITH GEARBOX TS8 Series

#### **ORDER CODE**

Т	S8	+		+	W	+		+		-	+	D907	+		+		+	
								No	code	=	fixe	d displacem	ent					
1	Туре	of dis	placem	ent				D		=	dua	I displacem	ent					
								V		=	varia	able displac	ement					
2	Brake	e optio	on					F	= brake									
3	3 Displacement								table									
								D9(	07	=	For	TS8W and <sup>-</sup>	rs8WF					
4	Distributor							D9(	)7D	=	For	TS8DW and	TS8DW	/F				
								D9(	)7V	= For TS8VW and TS8VWF								
								V		=	FKM	1 seals						
5	Optio	ns						I		= breath valve								
								RS		=	rota	tive sensor						
6					rotatio	n		No	code	=	cloc	kwise rotati	on					
	(viewed from the output side) with flow in port A, out port B.							L		=	anti-	-clockwise r	otation					
								No	code	=	posi	ition 1						
7	Distributor cover orientation						DM	2	= position 2									
								DM	3	= position 3								

Example

TS8W 6000 D907

(standard)

TS8VWF 6000 D907V VL

(Options: FKM seals and direction anti-clockwise of the rotation)



This page has been deliberately left blank

# HANSA-TMP

### **Wheel Motors**

#### **DISTRIBUTORS**









Please note that this page is to be considered an introduction to the Distributors Catalogue. For further information please consult the mentioned catalogue.

Distributor series			D3	D4	D5	D9
Canad	[mmm]	continuous	300	1600	1600	700
Speed	[rpm]	maximum	500	2400	2400	1200
	[head]	continuous	250	250	250	250
Pressure	[bar]	maximum	500	500	500	500
Flow	[]/main]	continuous	200	200	200	500
	[l/min]	maximum	400	400	400	1000

Low speed distributors such as D31, D37 can be supplied mounted with a bronze disc. With this option (called DBM) the distributors reach the same maximum speed as the high speed distributors.

	D3	D4	D5	D9
P05R / P05R + F25	0	Х	0	-
P1G / P1G + F30D	0	X	0	-
P2G / P2G + F32	0	Х	0	-
BD2 / BD2 + F32	0	X	0	=
GM05 + WR6B / WR10	0	X	0	=
GM1 + WR6B / WR10 / WR20	0	X	0	-
BD1 + WR6B / WR10 / WR20	0	Х	0	-
BV1 + WR6B / WR10 / WR20	0	X	0	-
GM05 + G3 / F10L + G3 / G3A / F10L + G3A	0	Χ	0	-
GM1 + G3 / F10L + G3 / G3A / F10L + G3A	0	Х	0	-
BD1 + G3 / F10L + G3 / G3A / F10L + G3A	0	Х	0	-
BV1 + G3 / F10L + G3 / G3A / F10L + G3A	0	Χ	0	-
GK3 / GFK3R / GK3A / GFK3A	0	X	0	-
BDK3 / BDFK3R / BDK3A / BDFK3AR	0	Х	0	-
BVK3 / BVFK3R / BVK3A / BVFK3AR	0	X	0	=
GK4 / GFK4 / BDK4 / BDFK4 / BVK4 / BVFK4	0	X	0	=
TS8W	-	-	-	X
TS8DW	-	-	-	X
TS8VW	-	-	-	X

ALWAYS POSSIBLE	Х
POSSIBLE ON REQUEST	0
NOT POSSIBLE	-



#### **DISTRIBUTORS**

Distributor	Ports	Description
D31	3/4" BSP	
D310	1" BSP	
D311	1" BSP	
D312	3/4" BSP	
D313	1" BSP	
D314	1" BSP	
D322	3/4" BSP	Distributor with anti-cavitation valve
D37	1" SAE 3000psi	
D40	1" BSP	Standard for all motors unless otherwise described
D47	1" SAE 3000psi	
D47R	1" SAE 6000psi	
D47D	1"SAE 6000psi	
D47PV	1"SAE 6000psi	
D48	1" BSP	With double pressure relief valves, 240 bar, 150 l/min
D481	1" BSP	With double pressure relief valves, 240 bar, 150 l/min. With purge valve 20 l/min at 20 bar
D49	1" BSP	With double pressure relief valves, 210 bar, 80 l/min
D491	1" BSP	With double pressure relief valves, 210 bar, 80 l/min. With purge valve 20 l/min at 20 bar
D504	1" BSP	With double overcentre valve 10:1, 120 l/min, 270 bar and shuttle valve
D508	1" BSP	
D508/A	1" BSP	
D51	1" BSP	With double pressure relief valves, 240 bar, 150 l/min
D510	1" BSP	Short circuit freewheeling
D907	1 1/2" SAE 6000psi	
D907D	1 1/2" SAE 6000psi	
D907V	1 1/2" SAE 6000psi	



#### **APPLICATION DATA SHEET**

					Ge	eneral	informa	ation									
Vehicle model						Re	eference	name									
Vehicle type (mark with an	X)																
Agricultural vehicle	Fork	lift		□ D	umper			Mot	orized traile	er 🔲 (	Off-road	vehicle					
Road roller	Skid	steer loa	ader	П Н	arvestin	ng vehi	cle [	╗		Other. F	Please sp	ecify bel	ow				
	'						,										
					Vel	hicle s	pecifica	ations									
No. of wheels						No	o. of mot	tors									
External tyre diameter of d	riving wh	eels				Fr	ont whe	els (m)		Rear wheels (m)							
Vehicle weight	Unladen	(kg)				Fu	ılly lader	ı (kg)									
Weight distribution on vehicle axles (in kg)																	
Front axle				Mau elene	ha aaa	(i= 0()											
Unladen Rear axle			Rear a	xle				тмах ѕюре	to overcome	(In %)							
Max vehicle working speed	(km/h)					M	Max vehicle working speed (km/h)										
Steering system	Steering system									Primary engine							
1 wheel steering	2 wh	neel steer	ring	<u> </u>	wheel s	steerin	Maxim	num po	wer (kW)								
Skid steering	Trac	ks		ШМ	otorized	d traile	r Maxim	num sp	eed (rpm)								
Hydraulic pump																	
If a pump has already bee	n selected	d please s	specify														
Quantity		Туре					Displa	cemen	t	ı	Max pres	sure					
Vehicle operating condi	tions																
Please specify the type of	errain	Tarr	mac/Cond	rete		Dry of	-road		☐ Wet o	ff-road		Sand					
Rails		Sno	w			Other	(please s	specify)	)								
Max number of hours of w	ork	Per day			Per y	year											
Required options																	
Will the motor be operating	g in freew	heeling?		Yes		No											
If brakes are required plea	se specify	/	No	. of bra	kes per	vehicl	e		0	n which whe	els						
Brake actuation		Mechani	cal		Hydr	raulic n	egative	(for sta	itic brake)	Hydra	aulic pos	itive (for	dynami	c brake)			
					Cor	mpany	inform	ation									
Company name											Date	2			_		
Country of origin		□ I					ı I							$\perp \perp$			
Select type of company		∐  Dist	ributor					facture									
Contact name						-	ontact er										
Contact phone number						Ico	ontact fa	x numi	Jer								
						Si	gnature	& stam	р								



#### **APPLICATION DATA SHEET**

Company name  Country of origin  Select type of company Distributor Manual  Contact name Contact er  Contact phone number Contact fa		General i	nfor	mation	
Winch	Nar	ne or reference of the machine			
Winch					
Auger   Pinion drive   3   Conveyor   Mixer   4   Pilastic injection moulding machine   Other   Pilease specify below   Pilease specify below   Pilease specify below   Pilease specify below   Pilease specify motors used below   Pilease specify	ele	ect type of machine			
Conveyor		Winch		Concrete mixer	
Plastic injection moulding machine  Other Please specify below  Innual production   Qty If machine in production please specify motors used below  Idaximum number of hours of work  Idaximum number of hours  Idaximum numb		Auger		Pinion drive	
Other Please specify below  Annual production		Conveyor		Mixer	
Annual production  If machine in production please specify motors used below  Maximum number of hours of work  Der day		Plastic injection moulding macl	nine		
If machine in production please specify motors used below  Maximum number of hours of work per day		Other	Plea	ase specify below	
f machine in production please specify motors used below  Maximum number of hours of work  per day					
Maximum number of hours of work per day	Anr	nual production		(	Qty
Hydraulic technical specifications    Model name	If n	nachine in production please spe	ecify	motors used below	
Hydraulic technical specifications    Model name					
Hydraulic technical specifications    Model name	Max	kimum number of hours of work			
Model name Displacement Power rating Flow Maximum pressure Maximum speed System pressure setting Maximum power Inertia values (if known) If the motor has to work in freewheeling please specify Maximum speed If brakes are required please specify whether they have Mechanical actuation Hydraulic fluid used Mineral oil Mineral oil Mineral oil Mineral oil Mosphate-ester Water emulsion Biological oil Viscosity  Company name Country of origin Select type of company Contact name Contact phone number  Contact phone number  Contact fax number	per	day	per	year	
Displacement Power rating Flow Maximum pressure Maximum speed Maximum speed Maximum speed Power rating Maximum speed Maximum speed Maximum power Inertia values (if known) If the motor has to work in freewheeling please specify Maximum speed Mechanical actuation Hydraulic (negative) actuation Hydraulic fluid used Mineral oil Mineral oil Maximum speed Maximum speed Mechanical actuation More actu		Hydraulic techni	ical	specifications	
Power rating   kW   Flow   l/min   Maximum pressure   bar   Maximum speed   rpm   System pressure setting   bar   Maximum speed   System pressure setting   bar   Maximum power   Inertia values (if known)   If the motor has to work in freewheeling please specify   Maximum speed   rpm   If brakes are required please specify whether they have   Mechanical actuation   Hydraulic (negative) actuation   Hydraulic fluid used   Mineral oil   Water emulsion   Biological oil   Water emulsion   Biological oil   Company name   Company name   Company name   Contact email address   Contact phone number   Contact fax number		Model name	Π		
Power rating Flow   Flow	Р	Displacement		[1	сс
Flow   //min   bar   Maximum pressure   bar   Maximum speed   rpm   System pressure setting   bar   Maximum power   Inertia values (if known)   If the motor has to work in freewheeling please specify   Maximum speed   rpm   If brakes are required please specify whether they have   Mechanical actuation   Hydraulic (negative) actuation   Hydraulic fluid used   Mineral oil   Water glycol   Phosphate-ester   Water emulsion   Biological oil   Viscosity   cSt   Company information   Company name   Country of origin   Select type of company   Distributor   Manufacturer   Contact mame   Contact fax number   Contact fax		Power rating		ļ	kW
Maximum torque Maximum speed System pressure setting Maximum power Inertia values (if known)  If the motor has to work in freewheeling please specify Maximum speed If brakes are required please specify whether they have Mechanical actuation Hydraulic fluid used Mineral oil Water glycol Phosphate-ester Water emulsion Biological oil Viscosity  Company information  Company name  Country of origin Select type of company Contact name Contact phone number  Maximum speed Ir pm Inertia values (if known) Inertia val		Flow	Г	ļ	l/min
Maximum speed		Maximum pressure		ļ	bar
Maximum speed System pressure setting Maximum power Inertia values (if known)  If the motor has to work in freewheeling please specify  Maximum speed If brakes are required please specify whether they have Mechanical actuation Hydraulic (negative) actuation Hydraulic fluid used Mineral oil Water glycol Phosphate-ester Water emulsion Biological oil Viscosity  Company information  Company name  Country of origin Select type of company Contact name Contact name Contact phone number  Contact fax number		Maximum torque		ļ	Nm
System pressure setting bar Maximum power Inertia values (if known)  If the motor has to work in freewheeling please specify  Maximum speed rpm  If brakes are required please specify whether they have Mechanical actuation Hydraulic (negative) actuation  Hydraulic fluid used Water glycol Phosphate-ester Water emulsion  Biological oil  Viscosity Company information  Company name  Country of origin  Select type of company Distributor Manufacturer  Contact name Contact phone number  Contact fax number		Maximum speed		ı	rpm
Maximum power   KW     Inertia values (if known)     If the motor has to work in freewheeling please specify     Maximum speed   rpm     If brakes are required please specify whether they have       Mechanical actuation   Hydraulic (negative) actuation     Hydraulic fluid used       Mineral oil   Water glycol       Phosphate-ester   Water emulsion     Biological oil     Viscosity   cSt     Company information     Company name     Country of origin     Select type of company   Distributor   Manufacturer     Contact name   Contact email address     Contact fax number		System pressure setting		İ	bar
If the motor has to work in freewheeling please specify  Maximum speed	0	Maximum power		i i	kW
Maximum speed rpm  If brakes are required please specify whether they have  Mechanical actuation Hydraulic (negative) actuation  Hydraulic fluid used  Mineral oil Water glycol  Phosphate-ester Water emulsion  Biological oil  Viscosity cSt  Company information  Company name  Country of origin  Select type of company Distributor Manufacturer  Contact name Contact email address  Contact fax number		Inertia values (if known)		<u>'</u>	
If brakes are required please specify whether they have  Mechanical actuation   Hydraulic (negative) actuation  Hydraulic fluid used  Mineral oil   Water glycol  Phosphate-ester   Water emulsion  Biological oil  Viscosity   CSt  Company information  Company name  Country of origin  Select type of company   Distributor   Manufacturer  Contact name  Contact name  Contact phone number   Contact fax number	If t	he motor has to work in freewhe	elin	please specify	
Mechanical actuation	Max	kimum speed		Į.	rpm
Hydraulic fluid used  Mineral oil  Phosphate-ester  Biological oil  Viscosity  Company information  Company name  Country of origin  Select type of company  Contact name  Contact name  Contact phone number  Water emulsion  Cost  Manufacturer  Contact fax number	If b	rakes are required please specif	y wh	ether they have	
Mineral oil Phosphate-ester Water emulsion Biological oil Viscosity Company information  Company name Country of origin Select type of company Contact name Contact phone number  Water emulsion  Manufacturer Contact fax number  Contact fax number		Mechanical actuation		Hydraulic (negative) ac	tuation
□ Phosphate-ester □ Water emulsion □ Biological oil  Viscosity □ CSt  Company information  Company name  Country of origin  Select type of company □ Distributor □ Manufacturer  Contact name □ Contact email address  Contact phone number □ Contact fax number	Нус	Iraulic fluid used			
□ Phosphate-ester □ Water emulsion   □ Biological oil    Company information  Company name  Country of origin  Select type of company  Contact name  Contact name  Contact phone number  Water emulsion  CSt  Manufacturer  Contact email address  Contact fax number		Mineral oil		Water glycol	
Company information  Company name  Country of origin  Select type of company  Contact name  Contact name  Contact phone number  Contact fax number		Phosphate-ester			
Company information  Company name  Country of origin  Select type of company Distributor Manufacturer  Contact name Contact email address  Contact phone number Contact fax number		Biological oil	_		
Company name  Country of origin  Select type of company  Contact name  Contact email address  Contact phone number  Contact fax number	Viso			[6	cSt
Country of origin  Select type of company  Contact name  Contact phone number  Contact fax number  Contact fax number					Compa
Country of origin  Select type of company  Contact name  Contact phone number  Contact fax number  Contact fax number	Cor	npany name			
Contact name Contact email address Contact phone number Contact fax number	Country of origin				
Contact name Contact email address Contact phone number Contact fax number	⊢			Distributor	
	_		Г		
	Cor	ntact phone number	T		
Signature & stamp		-			

As HANSA-TMP has a very extensive range of products and some products have a variety of applications, the information supplied may often only apply to specific situations.

If the catalogue does not supply all the information required, please contact HANSA-TMP.

In order to provide a comprehensive reply to queries we may require specific data regarding the proposed application.

Whilst every reasonable endeavour has been made to ensure accuracy, this publication cannot be considered to represent part of any contract, whether expressed or implied.

HANSA-TMP reserves the right to amend specifications at their discretion.



Tel.: +39 059 415 711 Fax: +39 059 415 730

E-mail: hansatmp@hansatmp.it Website: www.hansatmp.it

Certified Company ISO 9001:2015 - ISO 14001:2015



Share Capital: € 300.000,00 VAT Number: IT01167360369 REA Number: MO-225785